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Search for new Phenomena in Dijet Angular Distributions at $\sqrt{s} = 8$ and 13 TeV

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SEARCH FOR NEW PHENOMENA IN DIJET ANGULAR
DISTRIBUTIONS AT $\sqrt{s} = 8$ AND 13 TEV

LENE BRYNGEMARK

Thesis submitted for the degree of
Doctor of Philosophy



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ABSTRACT

A new energy regime has recently become accessible in collisions at the Large Hadron Collider at CERN. Abundant in hadron collisions, the two-jet final state explores the structure of the constituents of matter and the possible emergence of new forces of nature, in the largest momentum transfer collisions produced. The results from searches for phenomena beyond the Standard Model in the dijet angular distributions are presented. The data were collected with the ATLAS detector in proton-proton collisions at centre-of-mass energies of 8 and 13 TeV, corresponding to integrated luminosities of 17.3 fb^{-1} and 3.6 fb^{-1} , respectively. No evidence for new phenomena was seen, and the strongest 95% confidence level lower limits to date were set on the scale of a range of suggested models. This work details the limits on the compositeness scale of quarks in a contact interaction scenario with two different modes of interference with Standard Model processes, as well as on the threshold mass of quantum black holes in a scenario with 6 extra spatial dimensions, and on the mass of excited quark states. It also includes new exclusion limits on the mass of a dark matter mediator and its coupling to fermions, as derived from the contact interaction limits using an effective field theory approach.

The performance in ATLAS of the jet-area based method to correct jet measurements for the overlaid energy of additional proton-proton collisions is also presented. It removes the dependence of the jet transverse momentum on overlaid collision energy from both simultaneous interactions and those in the neighbouring bunch crossings, and was adopted as part of the jet calibration chain in ATLAS.

Hur förklarar vi vad som hände efter Big Bang? Hur är det möjligt att titta 14 miljarder år tillbaka i tiden, isolera de första miljarddelarna av en sekund, och studera vad som pågår precis där och då? Svaret är såklart, att vi inte kan det. Det vi kan göra, är att om och om igen återskapa några viktiga aspekter av de förhållanden som rådde då, och studera vad som händer. Metoden vi använder är att omvandla energi till partiklar med massa — precis som vi föreställer oss hände i universums begynnelse. Det gör vi genom att accelererera upp stora mängder av protoner — atomkärnor av universums lättaste och vanligaste grundämne, väte — till höga energier i en partikelaccelerator, och sedan låta dem kollidera. Runt kollisionspunkten placeras en detektor. I kollisionerna kan tunga partiklar bildas eftersom det finns så mycket energi tillgänglig. De tunga partiklarna sönderfaller sedan till lättare partiklar, ibland i långa sönderfallskedjor fram till de lätta partiklar som är det som universum består av idag. De växelverkar med materialet i detektorn och ger upphov till elektriska signaler som läses ut och används till att rekonstruera vad som bildades i kollisionen. På så sätt kan vi få en glimt av vad som kunde hända med den stora tillgängliga energi som fanns koncentrerad i en mycket liten volym i universums begynnelse.

Den vanligaste typen av växelverkan mellan protonernas beståndsdelar — kvarkar och gluoner, eller med ett gemensamt namn: partoner — är den så kallade starka kraften. I protonkollisionerna växelverkar två partoner, och ett möjligt utfall är att nya partoner bildas med hög energi, och slungas ut från kollisionspunkten. Men en egenskap hos den starka kraften är att en parton aldrig kan isoleras! Istället bildas kontinuerligt nya kvark/antikvark-par i dess kölvatten, av rörelseenergin hos partonen, som successivt bromsas in av energiförlusten. Resultatet blir en riktad skur av partiklar — en *jet* — som tillsammans har den energi och de andra kvantmekaniska egenskaper som parto-

nen fick i kollisionen. Genom att mäta jetens egenskaper kan vi säga något om egenskaperna hos partonen som bildades.

Den här avhandlingen beskriver dels en metod för att noggrant kunna mäta jetenergier även när mätningen påverkas av energi från andra kollisioner, och dels hur vinklarna mellan jetpar kan användas för att leta efter fenomen som inte beskrivs av den rådande teori som beskriver vilka naturlagar (krafter och fundamentala partiklar) som finns. Vi vet att det behövs en mer fundamental teori än den nuvarande, eftersom det finns observationer som den inte förklarar, t ex den stora skillnaden mellan massorna av olika typer av kvarkar. En av den experimentella partikelfysikens viktigaste uppgifter just nu är därmed att finna tecken på avvikelser från den rådande teorin, så att vi kan börja ana på vilket sätt vi bättre kan beskriva universums beståndsdelar och krafter. Avhandlingen visar att vid de mest högenergetiska kollisioner vi hittills kunnat åstadkomma i en accelerator, har vi ännu inte observerat några avvikelser från den rådande teorin.

LIST OF PUBLICATIONS

Some of the original work described in this thesis has appeared previously in the following publications:

- [1] ATLAS Collaboration. Search for New Phenomena in Dijet Mass and Angular Distributions from pp Collisions at $\sqrt{s} = 13$ TeV with the ATLAS Detector. *Physics Letters B*, 754:302 – 322, 2016.
- [2] ATLAS Collaboration. Search for New Phenomena in the Dijet Angular Distributions in Proton-Proton Collisions at $\sqrt{s} = 8$ TeV with the ATLAS Detector. *Phys. Rev. Lett.*, 114:221802, 2015.
- [3] ATLAS Collaboration. Performance of pile-up mitigation techniques for jets in pp collisions at $\sqrt{s} = 8$ TeV using the ATLAS detector. *To be published in EPJC*, 2015. arXiv:1510.03823.
- [4] ATLAS Collaboration. Search for new phenomena in the dijet mass distribution using p - p collision data at $\sqrt{s} = 8$ TeV with the ATLAS detector. *Phys. Rev. D*, 91:052007, 2015.
- [5] ATLAS Collaboration. Search for New Phenomena in Dijet Mass and Angular Distributions with the ATLAS Detector at $\sqrt{s} = 13$ TeV. Technical Report ATLAS-CONF-2015-042, CERN, Geneva, Aug 2015.
- [6] ATLAS Collaboration. Pile-up subtraction and suppression for jets in ATLAS. Technical Report ATLAS-CONF-2013-083, CERN, Geneva, Aug 2013.
- [7] ATLAS Collaboration. Search for New Phenomena in the Dijet Mass Distribution updated using 13.0 fb^{-1} of pp Collisions at $\sqrt{s} = 8$ TeV collected by the ATLAS Detector. Technical Report ATLAS-CONF-2012-148, CERN, Geneva, Nov 2012.

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Torsten, who suggested the research topic of dijet distributions and became my main supervisor. Always online, always there for physics or coffee or both, just waiting to make a discovery (I'm sorry we didn't yet). It's safe to say that without you, this thesis would not have been.

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The pursuit of a PhD is the hardest on, and least gratifying for, the persons closest to you. Elina, words will never be enough. Thank you for letting me get absorbed, and waiting for me to come out again. This one is for you.

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Part I

INTRODUCTION: THE THESIS, THE
STANDARD MODEL, AND THE
EXPERIMENT

THESIS INTRODUCTION

– What is the smallest thing you know?

When asked what my research is about, I often find asking this question to be the most fruitful way to start. The answer varies, of course. Molecules, atoms, quarks? The smallest thing *I* know, is a mathematical point. This is a theoretical concept: just a point, a place-holder in some coordinate system, which is infinitesimally small — regardless of how much you zoom in, you will never see it; it has no extension in space. Mind-bogglingly, the particles I try to envision when doing my particle physics research are exactly this: point-like. They have mass, various charges, and they interact with each other, but they have no size. That is, to our current knowledge they don't. They are fundamental. And when you think about it, this is probably how it has to be: an entity with extension in space but still un-splittable, without constituents, is very difficult for the human mind to imagine. Conversely, a fundamental particle has no constituents, and thus no extension.

1.1 A WORD ON PARTICLE PHYSICS


Particle physics is the human endeavour to understand what the fundamental constituents of matter are, and how they interact. The

programme is as simple as that. *Following* this programme is far from trivial: it takes building the largest instruments, fastest electronics, among the largest scientific collaborations and the coldest places in the Universe.¹

At this point, all our knowledge and predictions about matter constituents and their interactions are neatly connected in the Standard Model of particle physics. Well, with one exception: this theory of the laws of nature does not include gravity. But it does include the three other interactions we have observed, and moreover, it does a splendid job describing them. The Standard Model will be described in greater detail shortly — suffice it to say here, that we know that it can still not be the final answer. This knowledge we base, quite simply, on the fact that we have more questions than it can answer. Some of the properties of the particles we observe — for instance, their masses — are not described in the Standard Model, but are free parameters that need to be experimentally established. Furthermore, there are several classes of observations indicating that there is a type of matter in the Universe which is not present in the Standard Model. Interestingly, this matter interacts with gravity, which is the only force of nature interacting with “normal” matter that is not included in the Standard Model.

1.1.1 *Some mention of the scales*

The matter around us is made up of atoms, which in turn consist of one or several electrons orbiting a nucleus made of one or several nucleons. If we were to draw a simple picture of this system, what would be the relative scale of its pieces? If we draw the nuclear radius as 1 cm, then we would have to draw the electrons as infinitesimally small dots, about one kilometre away. The quarks making up the proton don't seem to have a size yet either, but we know it's less than one thousandth of the proton's size — so on this sketch, it would be

 *nucleon*: nucleus constituent, that is, proton or neutron

¹ Disclaimer: as far as we know — there could of course be some other civilisation somewhere achieving temperatures even closer to the absolute zero. But to be clear, we do know the temperature of outer space, and it is higher than what we use in some of our accelerators and experiments.

10 μm . Oh, and how large is the human scale on this drawing? 10 billion times larger than an atom — you would only need to draw a stack of 10 average European adults to cover the whole distance from the Earth to the Sun.

1.2 THE ENERGY FRONTIER

With the start-up of CERN's new accelerator, the Large Hadron Collider (see Chapter 3), in 2009, a decade-long wait for the next energy leap was over. In the history of accelerators — which is the history of particle physics, since at least the 50's [1] — roughly speaking, when a new fancy accelerator was built, a new particle was found. This was true for instance for the Tevatron (the top quark) at almost 2 TeV and the SPS (the W and Z bosons) at 540 GeV. With the LHC, it took us three years to harvest the first crop after decades of planning: the H boson. But we still hope for more.

At the basis of this relation (new accelerator = new particle), the most famous formula of physics — the Einsteins' $E = mc^2$ — lies. In fact, it's not the new accelerator that is key. It's the new energy regime.

This formula is actually at the heart of our science. It states, that if we can produce enough energy, we can produce massive particles, since mass is a form of energy. In this game, mass is potential energy. Think of a rock held in your hand. Its potential energy with respect to gravity is released once you let go of it, and it falls to the ground, gaining kinetic energy as it falls. Similarly, a very massive particle often has potential energy with respect to another force field (recall the four fundamental forces of nature in our current description of nature) which is released as the particle transforms into lighter particles, generally with some kinetic energy — a decay.

Stop and think about it. We say that as we reach higher energies, we can produce heavier particles than ever before. This means, that the chance of finding something new, that was out of reach before, and which doesn't fit into our general picture (because our general picture worked fine as long as we didn't have to worry about this new

☛ We assume a field, where information is carried by some mediator. If the mediator is recognisable by both sides, the transformation from kinetic energy to massive particle — and back to kinetic energy and lighter particles! — can happen.

thing) increases dramatically when we take a new energy leap. In one sense, we don't need to assume much: only that mass is a form of energy. But on the other hand, this new heavy particle must be able to communicate with the incoming particles carrying this high energy. So in another sense, it's not a small requirement. Luckily, in quantum mechanics, generally all the things that are at all possible will happen eventually — it's just a matter of probabilities. And waiting.

Another aspect of being at the energy frontier is that higher energies correspond to resolving smaller details. This is another quantum mechanical feature: particles behave like waves, and waves like particles — it's a matter of at which energy scale you're looking. So, when we collide particles, the energy they have correspond to some wavelength. The higher the energy, the shorter the wavelength. And with a shorter wavelength, you can resolve smaller distances. Think of a boat lying in the sea: it will affect the pattern of the waves, which means that even if we wouldn't see the boat, we would be able to deduce that there was something in the water, some structure, from looking at the wave patterns. Now imagine a football floating next to the boat. This object is much smaller than the typical wavelength of the waves, and the wave pattern will not be distorted by its presence — we won't notice the ball. The same way, we can only resolve small details in the structure of matter if we have small enough waves, meaning, high enough energy. This means that for every leap in energy, we have a new possibility to resolve smaller structures in matter — effectively, to see if the particles we considered fundamental actually consist of something!

So what would you do with this knowledge? You know that the most probable things are already observed. You know that we have a new energy regime at our hands. You know that we can resolve smaller structures than ever before. And you know that in every collision, there is this, possibly small, quantum mechanical probability of any type of outcome allowed in nature. Well. I chose to study an enormous sample of the most energetically far-reaching type of outcomes: dijet events.

Here our journey begins. I set out to teach you all I know. I'm proud to say, it will take a little while.

1.3 THIS THESIS: OUTLINE

The work presented here, aims at using the collision final state of two *jets* (see Part ii) as a probe of phenomena beyond the Standard Model. The observable used is the angular correlations of these two jets, an observable theoretically predictable almost from first principles, and thoroughly studied at lower energies, including at the LHC [2–7]. The road to such a measurement is however somewhat winding. Here, with the privilege of retrospect, I will rearrange the dots so as to be able to connect them with the shortest possible, continuous path, with the pattern finally (and hopefully!) emerging clearly when I’m done.

In Chapter 2, the current best knowledge of particle physics, as described by the Standard Model, is briefly outlined. Here the theoretical foundations needed for the interpretation of the experimental results are laid. Then two chapters on the experimental equipment: the accelerator (Chapter 3) and the detector (Chapter 4), follow. We then switch gears and delve into the subject of measuring jets in Chapters 5–7. The last part of the thesis, Chapters 8–11, comprises of the description of the analysis method details and the results from the dijet measurements made. Finally, the conclusions follow in Chapter 12.

1.4 THE AUTHOR’S CONTRIBUTIONS

The ATLAS experiment, which will be described later, is a large collaboration of currently approximately 3000 physicists, and has been designed and constructed for roughly two decades before it started producing papers about particle physics measurements. All publications are made in the name of the collaboration. Hence, only after a thorough internal review, the entire collaboration signs off on each article, note, presentation and even poster made public. The author list, when shown, is extensive, and follows strict alphabetical order.

Having a publication in your name is thus a slightly different game in this context than in many other scientific communities. Firstly, one needs to qualify to become a member of the author list. My

☛
Qualification task:
 work done for the
 greater good of the
 collaboration,
 spanning at least 50%
 of full working time
 over a year.

qualification task was to evaluate and, if useful, introduce a new method to correct jet measurements for the impact of energy from additional proton collisions (pile-up). This work will be detailed in Chapter 7, and resulted in first a conference note [8], documenting the work in preparation for presenting the results at a conference , and later in a paper [9]. I was one of two main editors of the conference note, taking the initiative to start writing, and I wrote the text describing the general concepts and ingredients of the method and the proof-of-principle studies I made in simulation. Much of this text was later re-used for the paper, which also describes other aspects of improving jet measurements in the presence of pile-up. For all the assessment of the method in real data, I worked closely with the other authors. This method is now standardly used as part of the jet calibration chain in ATLAS, and thus underlies all ATLAS measurements involving (or vetoing on) jets using the 2012 data set or later. This illustrates the second aspect of the author list convention: every publication stands on the shoulders of countless hours of work by the (past and present) fellow members of the collaboration. Hence choosing a main author would be not only very difficult, but also very rude.

During 2012, I was part of the day-to-day detector operation, as *hardware on-call* for the Liquid Argon calorimeter (for more details on the calorimeters, see Chapter 5). I was on-call for approximately one quarter of the data taking over the year.

☛
 In ATLAS
 nomenclature, a *search*
 is a measurement on
 data with the aim of
 discovering physics
 beyond the Standard
 Model.

The next publication where I contributed directly to the measurement at hand was a conference note on the dijet mass resonance search using part of the 2012 data set [10]. There I contributed the expertise I gained from the qualification task, in an investigation of the impact of pile-up on the measurement. I also contributed this knowledge to the full 2012 data set publication of the same search [11]. This measurement is closely connected to the dijet angular distribution search, where I was the main responsible for the search using 2012 data [12], and wrote the lion's share of the internal documentation used to assess the maturity of the analysis, and forming the basis for writing the paper.

1.4 THE AUTHOR'S CONTRIBUTIONS

The work done on the 2012 data set was a fantastic head start for doing two well prepared and very fast analyses [13, 14] of the first data coming out of the LHC in 2015, after its upgrade to higher energy. With my previous experience, I continued leading the analysis of the angular distributions, and took over most of the work preparing the theoretical predictions of the distributions (including the assessment of systematic uncertainties). I again wrote most of the internal documentation of these studies. This time the search was made in tandem with the mass distribution analysis, with joint leadership, strategy and documentation. I edited all parts of it, as well as the final paper.

2

THE STANDARD MODEL AND BEYOND

It is often said that the Standard Model (SM) is a theory of interactions. That means, that it describes the laws of nature by assigning its pieces a susceptibility to certain forces. This is modelled as a charge with respect to a field, which in this respect is nothing more than a quantum of how strongly it couples to the force carriers of that field.

The most familiar of charges is probably electric charge. Consider how static electricity separates the straws of your hair — this happens when there are a lot of same-sign charges repelling each other, a large total charge. It does not happen when there are only local fluctuations up and down in charge, as there normally is (they largely cancel). The same way, the magnitude of the charge on a fundamental particle determines how strongly it is coupled to the corresponding field.

But how do the straws of your hair know about the electric charge of their neighbours? Well, the charge is communicated by the exchange of a messenger: a field quantum. The field quantum of electromagnetism is the photon — a particle of light. In every interaction in the SM, a field quantum is exchanged. These are commonly called gauge bosons. The different forces of nature in the SM all correspond to their own field, and are communicated with each their own set of gauge bosons. For gravity to fit into this picture, it too should probably be mediated by a particle: the stipulated *graviton*, which remains to be observed.

➤ A net charge arises as the hair is stripped of or receives *electrons* — fundamental particles with electric charge $-1e$. Unlike a compound object, a fundamental particle has an intrinsic, fixed charge.

In fact, that it is not observed, and that mass (the coupling to gravity) is not quantised, indicates that gravity cannot yet be described as a *quantum field theory* like the other forces of nature. From now on, we will not consider gravity further, and as a matter of fact, we can safely neglect it, as it is many orders of magnitude weaker than the other three known forces of nature, which completely dominate particle interactions.

☛ This could be an indication of a more fundamental theory than the SM.

Moving from macroscopic compound objects like a straw of hair, the fundamental particles the SM deals with are *fermions* and *bosons*, with half-integer and integer (including zero) spin, respectively. Like charge, *spin* is an intrinsic quantum number to the particle, and it has a sign (is a directional quantity). In addition, a particle may carry charge under several fields, and thus interact with several forces. The combination of quantum numbers (spin type and charges) and mass uniquely defines a fundamental particle. In total, the SM describes the interactions of 17 fundamental particles. The interactions and their range and relative strengths are listed in Table 1.

☛ Here it is again, the elusive, seemingly fundamental, concept of mass...

Force	relative strength	range (m)
Strong	1	10^{-15}
Electromagnetic	$\frac{1}{137}$	∞
Weak	10^{-6}	10^{-18}
Gravity	10^{-39}	∞

Table 1: The four fundamental interactions currently known, their strength relative to the strong interaction at their respective appropriate scale, and range in metres [15].

Although the table lists the properties of the fundamental interactions, let me immediately introduce a caveat. It so happens, that the strength of the interactions depend on the energy scale at which the interactions are probed. This is called “running of the coupling constants” and actually implies that at certain energies, forces can unite (unless they evolve exactly the same way). For instance at energy

2.1 ELECTROMAGNETISM: QED

scales accessible to today's particle physics experiments, we often refer to electroweak (EW) interactions.

As mentioned, the SM is a theory of interactions, and it is through the laws of interaction we can distinguish the particles. I will thus introduce the fundamental particles in the SM in terms of the interactions. It will become evident that some interactions and prediction techniques are more relevant to my work, as they will be described in greater detail, and will serve as a use-case for some of the general features of the SM formalism. Mathematically, the SM is also a theory of symmetries; from symmetries, interactions and conservation laws arise. These conservation laws have profound implications on the interpretation of the theory, but are also part of our experimental toolbox, as they allow us to deduce certain quantities that aren't directly observed.



Electroweak as in the unification of electromagnetic and weak interactions

2.1 ELECTROMAGNETISM: QED

Magnetism has been known by humanity for thousands of years, and even used (e.g. for navigation). Electricity was understood as a force much later, in the 19th century. The electron would be the first particle discovered which is still considered fundamental.



Electron: from the Greek word for amber

In the quantum world, electromagnetism is described by Quantum ElectroDynamics (QED). Its mediating gauge boson is the photon (often represented by a γ). It is an infinite-range force, since the mediator is mass- and chargeless. This is the force which keeps atoms together, from the opposite electric charge sign of electrons and atomic nuclei. It also governs the electromagnetic waves we encounter in our everyday lives in form of radio (cell phone) signals, visible light or X-rays.

QED is one of the most tested theories we have — that is, we can both predict and measure quantities very precisely. The energy in an atomic energy level transition in hydrogen is often quoted as an example, as it is measured to 14 digits [16]! Yet, as we shall see, it is not a complete theory to all scales.

2.1.1 *The charged leptons*

Here we encounter our first particle type: the electrically charged leptons. One of these, the lightest, is the aforementioned electron (e). It partly makes up matter as we know it in our everyday life. However, it has heavier siblings: the muon, μ , and the tau lepton, τ . These siblings have different *flavour*, and different mass, but apart from that they are very similar. Flavour is a quantum number that is conserved under the electromagnetic interaction. The charged leptons have unit electric charge.

☛ The electron being the first fundamental particle discovered, it set the standard for electric charge — as the name suggests.

2.2 THE WEAK (NUCLEAR) INTERACTION

The weak interaction is suitably named, as it is substantially weaker than both the strong and electromagnetic interaction. It is mediated via massive vector bosons, the electrically charged W and the neutral Z boson, and unlike electromagnetism, it can transform particles into a sibling of different flavour. The masses of the gauge bosons make it a short range force. The weak interaction charge is called *weak isospin*, and it is only carried by particles of *left-handed chirality*.

☛ In the unified electroweak force, the charge is instead *weak hypercharge*, which takes both weak isospin and electric charge into account.

A particle of right-handed helicity is one where spin orientation and direction of motion coincides, while a left-handed has these two in opposite directions. This means that handedness depends on the reference frame of the observer. For massless particles, there is no choice of two frames with respect to which the massless particle can appear to move in opposite directions, since no observer can travel faster than the particle. Thus they are always of definite helicity, which coincides with its chirality. For massive particles, only chirality is invariant of choice of reference frame. This “handedness” or chirality is necessary to explain certain experimental observations, such as parity violation.

2.3 THE STRONG (NUCLEAR) INTERACTION: QCD

2.2.1 The neutral leptons

Along with the weak interaction, the need for neutral leptons — *neutrinos* — arises. They are ordered in flavour doublets with the charged leptons as illustrated below, in order of increasing mass:

$$\begin{pmatrix} e \\ \nu_e \end{pmatrix}_L \quad \begin{pmatrix} \mu \\ \nu_\mu \end{pmatrix}_L \quad \begin{pmatrix} \tau \\ \nu_\tau \end{pmatrix}_L$$

As for the neutrino masses themselves, they are too small to have been measured yet. That neutrinos do have mass is however established through the phenomenon of neutrino oscillations: neutrinos produced in one flavour state can oscillate into another flavour state as they travel. And travel they do! Since they only carry charge under the weak interaction, they rarely interact, and they are very likely to travel straight through even large macroscopic objects like planets.

The weak interaction can convert an upper particle in a doublet to its lower counterpart. This is possible since there are charged weak bosons, W^\pm , which can carry the incoming charge such that it is overall conserved. For instance, in radioactive β decay, it is the weak interaction which is at play: $n \rightarrow p + e^- + \bar{\nu}_e$ involves the exchange of a W boson. But to understand that process, we first need to introduce a set of particles commonly associated with the last known fundamental force of nature.

2.3 THE STRONG (NUCLEAR) INTERACTION: QCD

In our everyday lives, the main effect of the strong interaction is to keep the atomic nuclei together. This is not a small impact! The strong interaction is however a short-range force, limited to within the size of a nucleon, and only a smaller residual force is actually felt between the nucleons.

Colour charge is the quantum number making particles susceptible to the strong interaction or colour force, described by Quantum Chromodynamics (QCD). The colour charges are, in an analogy to the



The right-handed counterparts are flavour singlets, and thus stand alone: e_R, μ_R, \dots



Flavour oscillations are a quantum mechanical subtlety, relating to the flavour *eigenstate* not being the same as the mass *eigenstate*. Oh, yes, there it is again...

components of white light, *red*, *green* and *blue*, expressed below in a colour triplet:

$$\psi_a = \begin{pmatrix} \psi_1 \\ \psi_2 \\ \psi_3 \end{pmatrix} \quad (1)$$

The gauge boson of the strong interaction is the *gluon*. Gluons carry colour charge themselves. In contrast to QED, where the photon does not carry electric charge, this makes the range of strong interaction finite even though gluons are massless.

The QCD Lagrangian, the equation of motion describing all of the workings of the theory, is formulated in a gauge invariant way as

$$\mathcal{L} = \mathcal{L}_q + \mathcal{L}_g = \bar{\psi}_a (i\gamma^\mu \partial_\mu \delta_{ab} - g_s \gamma^\mu t_{ab}^C \mathcal{A}_\mu^C - m\delta_{ab}) \psi_b - \frac{1}{4} F_A^{\mu\nu} F_{\mu\nu}^A, \quad (2)$$

where Eqn. 1 enters, and the field tensor

$$F_{\mu\nu}^A = \partial_\mu \mathcal{A}_\nu^A - \partial_\nu \mathcal{A}_\mu^A + g_s f^{ABC} \mathcal{A}_\mu^B \mathcal{A}_\nu^C \quad (3)$$

makes up the kinetic term in the gauge field. The third term of Eqn. 2 makes $\bar{\psi}i\not{\partial}\psi$ gauge invariant. Gauge invariance is a means for making local symmetries in a theory evident, and in practice it means that a given new choice of coordinate system must be accompanied by a choice of *covariant* derivatives (the ∂_μ for instance), such that there is no net change on the predictions of the theory. The physics doesn't change! But the choice of formalism can make it more or less obscure. Since local symmetries give rise to forces, this is a central point in the Lagrangian formulation. On a similar note, global symmetries correspond to conserved currents, or put more simply, conservation laws.

8 = 3² - 1, QCD being an SU(3) symmetry group

In Eqs. 2-3, the eight gluons enter in the $\mathcal{A}_\mu^1, \dots, \mathcal{A}_\mu^8$, accompanied by the eight generators t_{ab} and the structure constants f^{ABC} . The superscripts here are colour indices implicitly summed over. From the strong coupling strength, g_s , we define the strong coupling constant $\alpha_s = g_s^2 / (4\pi)$. The last term in Eqn. 3 is the self-interaction term due to the colour charge of the gluons.

2.4 THE BROUT-ENGLERT-HIGGS MECHANISM AND THE PARTICLE MASSES

2.3.1 The quarks

The six quarks are fermions — building blocks of larger compounds of particles. They carry colour charge, meaning they belong in colour triplets, and non-integer electric charge: *up* (u), *charm* (c), *top* (t) have $+\frac{2}{3}e$, while *down* (d), *strange* (s) and *bottom* (b) carry $-\frac{1}{3}e$. Note that gluons carry one colour and one anti-colour, giving them the possibility to change the colour state of for instance a quark in an interaction. None of the other fermions in the SM interact via the strong interaction — they are colourless, or colour singlets. Like the leptons, the quarks also come in three generations, ordered in flavour doublets as represented below, again ordering the doublets in increasing mass:

$$\begin{pmatrix} u \\ d \end{pmatrix}_L \quad \begin{pmatrix} c \\ s \end{pmatrix}_L \quad \begin{pmatrix} t \\ b \end{pmatrix}_L$$

From this structure, it should be clear that the quarks also carry weak isospin and take part in weak interactions. However, due to the much smaller weak interaction coupling strength, QCD processes are much more probable and thus happen more often.

Had the history of discovery been different, the electric charge of the electron had likely been defined as $-3e$ instead.

2.4 THE BROUT-ENGLERT-HIGGS MECHANISM AND THE PARTICLE MASSES

No thesis covering work done in ATLAS in recent years would be complete without mentioning the Brout-Englert-Higgs (BEH) mechanism, and the related H boson discovered in 2012. This mechanism gives masses to the fermions and weak gauge bosons via the mechanism of electroweak symmetry breaking, splitting the massless gauge bosons of the underlying symmetry into the massless photon and the massive W and Z bosons, thus splitting the electroweak theory into electromagnetic and weak interaction. Knowing at which energy we have unification, we could predict approximately what the mass of the H boson should be, even though mass is always a free parameter in the SM.

The relation between energy and velocity is given by $E^2 = m^2 + \vec{p}^2$



In the general picture of quantised coupling strengths, the H boson is a little special since the coupling to different particles is related to their mass. Or, conversely, the mass of a particle is a measure of — given by! — how strongly it couples to the BEH field. In relativity, mass governs how fast something can travel at a given energy. Nothing travels faster than light in vacuum, precisely because photons are massless. And even though the BEH field permeates even the vacuum, photons don't interact with it and remain massless. Other particles can't travel as fast, as they are interrupted by having to interact with the medium. It is actually very similar to light in an atomic medium, such as glass. Here light travels more slowly than in vacuum, which gives glass its refractive index. At an atomic level, what happens is that the photon is constantly absorbed and re-emitted, slowing it down. On top of that, it is emitted in any random direction. From quantum mechanical effects, however, the sum of all possible paths introduces a lot of cancellations, and one direction of a light ray will be the final one. The final effect is that the light ray has refracted. In the process, the photons were moving more slowly, which can be thought of as acquiring an effective mass. Analogously, particles interacting with the BEH field acquire their masses too — the only difference being, that this medium exists **everywhere**. The masses of the fundamental particles as currently known are listed in Table 2.

For comparison, the proton and neutron weigh in at about 1 GeV. It is obvious that there are many fundamental particles which are heavier than these composite ones! Why the masses differ by up to five orders of magnitude between the three families is indeed a mystery in the present theoretical system.

2.5 ANTIPARTICLES AND FEYNMAN DIAGRAMS

For all of the fermions, there are also antiparticles, with the opposite sign on charges (charge conjugation). These are, for the electrically charged leptons, simply denoted with a $+$ instead of a $-$: the electron e^- has an anti-particle e^+ . For neutrinos and quarks, antiparticles are denoted with a bar: u and \bar{u} .

2.5 ANTIPARTICLES AND FEYNMAN DIAGRAMS

	particle	symbol	mass
leptons	neutrinos	ν_e, ν_μ, ν_τ	<25 eV
	electron	e	511 keV
	muon	μ	105.6 MeV
	tau lepton	τ	1776.2 ± 0.1 MeV
quarks	up	u	$2.3^{+0.7}_{-0.5}$ MeV
	down	d	$4.8^{+0.5}_{-0.3}$ MeV
	strange	s	95 ± 5 MeV
	charm	c	1.275 ± 0.025 GeV
	bottom	b	4.18 ± 0.03 GeV
	top	t	$173.21 \pm 0.51 \pm 0.71$ GeV
bosons	photon	γ	0
	gluon	g	0
	charged weak	W	80.4 GeV
	neutral weak	Z	91.2 GeV
	Higgs boson	H	125.7 ± 0.4 GeV

Table 2: The masses of fundamental particles as experimentally measured, or in most quark cases, calculated [15]. Note that the light quark masses are current quark masses, as calculated in the $\overline{\text{MS}}$ scheme at a scale of 2 GeV.

The seemingly simple concept of antiparticles is still a crucial ingredient in charge conservation: only if the net charge is equal before and after the interaction, a transformation from energy in the form of one set of particles to another can occur. This is achieved in the annihilation or creation of particle-antiparticle pairs, where the net charge is 0 both before and after the interaction.

To guide intuition, there is the useful construct of a Feynman diagram. It has a profound interpretation in terms of probabilities of different processes, but let's focus on its illustrative strengths for now. In these diagrams, time flows from left to right, lines represent

This convention goes back to considering antiparticles as particles moving backwards in time, as introduced in [17].

particles, and each vertex represents an interaction. Fermions are represented with solid straight lines, with arrows pointing right for particles and left for antiparticles. Gauge bosons are represented with wavy or curly lines for electroweak bosons and gluons, respectively. Figure 1 is our first encounter: it illustrates how two electrons interact with (repel) each other under the exchange of a photon, the gauge boson of QED. As mentioned before, this gauge boson exchange is the model for how particles are affected by each other’s presence.

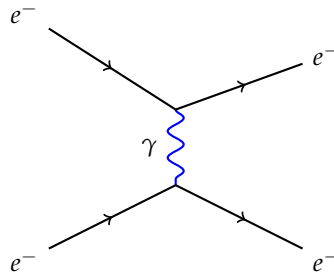


Figure 1: Feynman diagram illustrating $e^-e^- \rightarrow e^-e^-$ scattering, under the exchange of a photon (γ).

Figure 1 shows a “space like” process. If we rotate the diagram by 90° , we get a “time like” process, as shown in Figure 2.

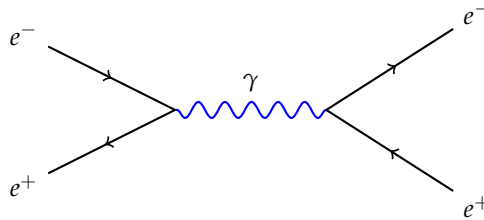


Figure 2: Feynman diagram illustrating $e^+ - e^-$ annihilation into a photon (γ), and pair production back into an $e^+ - e^-$ pair.

Guided by the direction of the arrows, we realise that what is depicted in Fig. 2 is particle-antiparticle annihilation and pair production.

The mass energy of the particles is converted into photon energy. This is in turn converted back into a particle-antiparticle pair. As long as the available energy is large enough, a vertex like this can go in any direction (creation as well as annihilation). There is no requirement that the photon conserves flavour; it has no memory thereof as its flavour quantum number is zero (as is the combined positive and negative flavour quantum numbers of the electron and anti-electron). As long as the other vertex conserves the flavour content, by for instance creating a muon-antimuon pair which taken together has zero flavour, all is well, and if the energy of the photon is large enough to create the mass of two muons, this can happen.

☛ anti-electron: also known as positron

2.6 HADRON CASE STUDY: THE PROTON

At this point, we have covered all the fundamental particles. But there is yet another important particle: the proton, which we use for particle collisions. The proton is one example of a hadron – a particle composed of quarks. Being composite, it is a suitable strong interaction case study, and we will use it to introduce some additional concepts. This is however a fairly complex topic, and we need to split it into pieces.

☛ The concept of hadrons is older than the quark model, so, they must have certain unique characteristics, evident already before.

While quarks carry colour, hadrons as a whole are colourless. This can be accomplished in two ways: by a combination of colour-anticolour (e.g. a red-antired) as in *mesons*, or in a combination of all three (anti)colours red–green–blue, as in *baryons*. Hadrons thus consist of two or three (anti)quarks. These are called valence quarks, since there always occurs quantum fluctuations where a gluon splits into a quark-antiquark pair which then annihilate back into a gluon. These fluctuation quarks are virtual, or *sea*, quarks.

☛ Virtual particles can “borrow” additional energy from the vacuum, but only for a short time.

Firstly, we establish that the proton is a baryon: it consists of three valence quarks, *uud*. This gives the proton a net electrical charge of $+1e$, and as mentioned before, no net colour charge. The other baryon making up ordinary matter, the neutron, has valence quarks *udd*, making it electrically neutral. The neutron is heavier than the proton, and an isolated neutron thus decays to a proton. At quark level, the

☛ More strictly speaking: $m_n > m_p + m_e + m_{\bar{\nu}_e}$

transformation from d to u would imply weak decay involving a W boson, as illustrated in Figure 3. There is in general not enough energy to create real W bosons when this happens, only virtual or *off-shell* W bosons that immediately produce a real lepton and neutrino. The comparatively long life-time of the isolated neutron, ~ 13 minutes, reflects all of this.

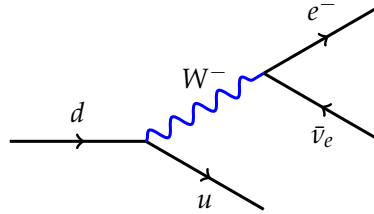


Figure 3: Feynman diagram illustrating what nuclear β decay looks like at quark level, if one could resolve the W boson.

2.6.1 Parton Distribution Functions

Since the proton is a composite particle, if we accelerate the proton to carry a certain momentum, it is its constituents that carry this net momentum. The motion of constituents inside the proton is not restricted and can be both lateral and longitudinal, but the net effect has to be the overall proton momentum. We can thus stipulate

$$\sum_i \int x q_i(x) dx = 1, \quad (4)$$

where the x is the Bjorken x [18], which is the longitudinal momentum fraction carried by a parton, and the sum is over the quark indices i . We have already touched upon the concept of sea quarks, originating from quantum fluctuations inside the protons. By denoting proton as uud , we mean that we get a non-vanishing result

$$\int (u(x) - \bar{u}(x)) dx = 2 \quad (5)$$

and

$$\int (d(x) - \bar{d}(x)) dx = 1 \quad (6)$$

when we integrate over all the q and \bar{q} content of the proton. The number of sea quark flavours accessible depends on the energy scale at which the proton is probed. This immediately means that the fraction of the proton momentum carried by gluons and sea quarks, respectively, depends on the energy transfer Q in the collision probing the proton structure. In fact the fractions vary also for the valence quarks. Overall, the quarks and the gluons carry about half the momentum each. The fractions are given in the Parton Distribution Function (PDF). Two examples at different Q^2 are shown in Fig. 4, which shows that the valence quarks become increasingly less dominant at higher x when the proton is probed at larger momentum transfer. Although it is not theoretically known per se, the PDF evolution with Q^2 can be calculated from a given starting point using the Dokshitzer-Gribov-Lipatov-Altarelli-Parisi (DGLAP) equations. The starting point has to be an experimental measurement of the PDF at some Q^2 . This can be data from for instance electron-proton or proton-proton collisions since the proton structure itself is universal and not dependent on the type of experiment. However, in the former case only one proton PDF is probed, making the extraction of information a little less involved.

2.6.2 Perturbative QCD calculations

The logic of the Feynman diagrams, with a vertex for each interaction and mediating particles, easily lends itself to *perturbation theory*. Perturbative calculations are a methodology to split complicated calculations in pieces of increasing fine tuning, and start with the coarsest approximation. The approach is to make an expansion in increasing orders of your variable in a region where it is small, so higher order contributions rapidly get smaller. In practice, a suitably truncated expansion is often good enough — luckily, since higher-order corrections are often not known! It also saves a lot of computing time for a complicated expression.



The idea is similar to the method of Taylor expansion.

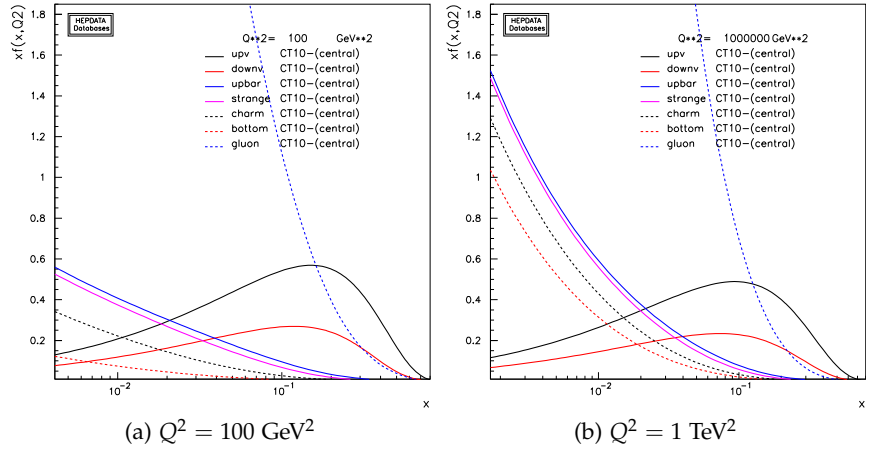


Figure 4: PDFs using NLO predictions including LHC data, for two values of Q^2 : (a) 100 GeV^2 and (b) 1 TeV^2 [19, 20].

Considering a process illustrated by a Feynman diagram, there is generally more than one way to draw it; there is more than one imaginable way to go from a given initial to final state, with more or less complicated steps in between. In quantum mechanics, we can't distinguish different possible histories — the intermediate steps in a process — leading up to a measured final state. But they all happen, with some probability! In a full calculation of the probability of an outcome, all of these possible paths need to be calculated, and summed correctly taking quantum mechanical interference into account. But in a Feynman diagram every vertex represents an interaction with a coupling strength, and all the vertices are multiplied to give the total probability, or *cross section*. This means that two different paths, with a different total number of vertices, are at different orders in coupling strength. If the coupling strength is small enough — as for the small-distance, high energy transfer collisions explored in this thesis — we can calculate the cross section of the process using a perturbative approach! In practice, perturbation theory holds already for $Q > 1 \text{ GeV}$, which is the proton mass and approximate confinement

scale in QCD. We also see that, since they are of high order in α_s , the more complicated paths contribute increasingly little to the final result. Often the leading, or lowest, order (LO) result is a good approximation, but the next-to-leading order (NLO) corrections can be substantial.

Factorisation theorem

We concluded that we can use perturbative calculations for the high-energy processes that we are generally interested in. We have also seen, that the effective energy at which we are probing the proton, and as a result the rate of the process, depends on the PDFs. These are however not possible to calculate perturbatively, which mathematically manifests itself as divergent integrals (infinite). But luckily, the two regimes are independent — they are *factorisable*. This means that we can rely on the calculation of the DGLAP evolution for the non-perturbative PDF part, and do perturbative calculations of the hard scatter part, without loss of generality. Technically this introduces a *factorisation scale* μ_F , with $1 \text{ GeV}^2 \leq \mu_F^2 < Q^2$. For the regime below the factorisation scale, we use the non-perturbative proton quark distribution. The hard-scatter cross section $\hat{\sigma}_{i,j}$ is governed by short-distance processes and perturbatively calculable. We can then express the cross section for a hard scatter in a hadronic collision factorised as

$$\sigma(P_1, P_2) = \sum_{i,j} \int dx_1 dx_2 f_i(x_1, \mu_F^2) f_j(x_2, \mu_F^2) \hat{\sigma}_{i,j}(\mu_R^2, \mu_F^2), \quad (7)$$

where the $P_{1,2}$ denote the incoming hadron momenta and the participating partons carry $p_1 = x_1 P_1, p_2 = x_2 P_2$. μ_R will be defined shortly. The $f_{i,j}(x, \mu_F^2)$ are the PDFs at some given Bjorken x , as given at the factorisation scale. This factorisation is schematically illustrated in Fig. 5.

2.6.3 Renormalisation

As mentioned, when applying the Feynman rules, all possibilities have to be integrated over, and they often come with momenta in

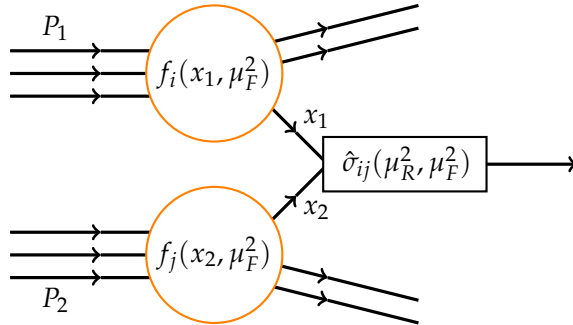


Figure 5: Schematic illustration of the factorisable processes in a pp collision, where one parton from each proton undergo a hard scattering.

the denominator. This again gives rise to divergent integrals, which would have to be cut off at some finite scale Λ to give finite results. Mathematically, this is not isolated to quantum field theories, even if it is a common feature of them.¹ Rather, it arises when one makes an expansion of a dimensionless quantity (e.g., a probability) around a small dimensionless parameter (say, coupling strength) of a function that depends on a dimensional parameter (for instance momenta). To remain dimensionless, the calculated quantity has to depend on the dimensional parameter through the ratio with another parameter of the same dimension — a *regulator*, say, Λ . After choosing a regularisation scheme, one can redefine couplings, masses and other parameters to absorb the divergences. Typically the redefinition corresponds to a physically measured quantity (such as a coupling constant) at a given scale, which we call the renormalisation scale μ_R , with the dimensions of mass. In practice what happens is that the implicit dependence on Λ in the original expansion was removed. Only after this, we let $\Lambda \rightarrow \infty$ and get finite results. The price paid in this procedure is that the coefficients in the perturbative expansion only make sense in a given context of scale and corresponding coupling. In addition, we must abandon thinking of parameters as constant: when a quantity

¹ This discussion loosely follows Ref. [21], which gives an overview of the renormalisation idea that is worth a read!

normalised at one scale is measured at a very different scale, the couplings and masses adjust. Also, the Λ introduced as an upper cut-off of the integrals to remove the divergence, can be thought of as the scale at which the physical theory no longer holds — a scale at which *new physics* enters.

The running of α_s

This immediately brings us to the question of the strong coupling constant. As indicated above, its value will depend on the scale at which we measure it. Experimentally, the value of α_s is given at the Z mass, and the world average is $\alpha_s(M_Z) = 0.1185(6)$ [15]. The scale dependence of α_s is controlled by the β function, which is precisely one of those parameters which do not depend on Λ :

$$\mu_R^2 \frac{d\alpha_s}{d\mu_R^2} = \beta(\alpha_s) = -(b_0\alpha_s^2 + b_1\alpha_s^3 + \mathcal{O}(\alpha_s^4)), \quad (8)$$

where $b_0 = (33 - 2n_f)/(12\pi)$, $b_1 = (153 - 19n_f)/(24\pi^2)$, and n_f is the number of accessible quark flavours. If we let $\mu_R^2 = Q^2$, where Q is the scale of the momentum transfer in the process at hand, the $\alpha_s(Q^2)$ will indicate the effective coupling strength in the process. Equation 8 shows a negative evolution of the coupling constant with the scale μ_R . The implications are even more evident in the expression for α_s itself: from the β function, we obtain

$$\alpha_s(Q^2) = \frac{4\pi}{b_0 \ln(Q^2/\Lambda_{QCD}^2)} \cdot \left[1 - \frac{2b_1}{b_0^2} \frac{\ln[\ln(Q^2/\Lambda_{QCD}^2)]}{\ln(Q^2/\Lambda_{QCD}^2)} + \mathcal{O}\left(\frac{1}{\ln^2(Q^2/\Lambda_{QCD}^2)}\right) \right] \quad (9)$$

Here the reference scale $\Lambda_{QCD} \sim 200$ MeV is the confinement scale of QCD: this is the limit where α_s diverges and becomes strong. In this regime, the perturbative approach is no longer valid. In the limit $Q \rightarrow \infty$, $\alpha_s \rightarrow 0$. In between these regimes, α_s depends only logarithmically on Q . Furthermore, it is immediately clear that also the α_s value will depend on the order to which the perturbative expansion is carried out.

☛ For QED the physically meaningful upper cut-off is the scale of unification with the weak interaction.

Confinement and asymptotic freedom

A possible way to think of a physical cause of the running coupling constant is in terms of (anti-)screening. Consider an electron. Just like a gluon fluctuates in and out of sea quark pairs, and electron constantly emits and reabsorbs field quanta, most likely photons. This can in turn create virtual loops of electron/positron pairs, which can screen the charge seen farther from the electron. The net effect is a smaller effective charge of the electron, making the field around it weaker. Similarly, gluons are constantly emitted from and reabsorbed by the quark. These can in turn create virtual gluon loops, which enhance the field strength at a distance, but smear the quark colour charge as we look closely. So, the strong interaction coupling “constant” depends on the distance, or equivalently energy, at which it is probed. At smaller distances (higher energies) α_s is smaller. In fact, at higher energies, more pair production becomes possible — this is one way of seeing why the classical (or leading order) approach breaks down: as we need to consider more possible paths, we need to introduce renormalisation.

☛ In the *natural units* commonly used in particle physics, where the speed of light in vacuum $c = 1$, distance has dimensions of $1/(\text{energy})$.

The small coupling constant at high energies is called asymptotic freedom: at small distances, well inside the hadron, partons barely interact and are very loosely bound. As two quarks are increasingly separated, the potential binding energy increases. In fact the potential between them increases linearly — much like in a classical spring or rubber band, a picture exploited in the Lund string model [22], which we will summarise shortly. This theoretically requires a non-Abelian term, causing self-interactions. Confinement means, that one can never observe a free quark.

☛ The electroweak theory is also non-Abelian, and W and Z bosons are self-interacting. Photons are not.

2.6.4 *Hadronisation*

Since only colourless particles can travel any macroscopic distances, an outgoing parton from a hard scatter has to *hadronise*. This is a non-perturbative process, occurring at lower energy and correspondingly larger distances than the hard scatter, where α_s is large.

☛ Macroscopic — or even outside the proton radius...

In the Lund string model, the force between two partons is pictured as a string. It has the properties of a classical string in the sense that the field contains a constant amount of field energy per unit length, meaning that the potential increases linearly when the string is stretched [22]. If two quarks are pulled apart, in for instance a high energy collision, the binding energy becomes so large that it is energetically “cheaper” to create a real quark-antiquark pair between them, which breaks the string without resulting in free quarks (but in new strings between quarks and anti-quarks). This process is repeated as long as there is sufficient energy. The end result is a collimated hadron shower, called a *jet*, in the direction of the original quark. This jet essentially carries the energy, momentum and other properties of the original quark. Note that since hadronisation happens at longer time scales than the hard scatter process, it can’t affect the partonic cross section of a process, or violate conservation laws. Measuring the jet properties is thus the way to measure the properties of the original quark, even if it can’t be isolated and measured itself. It is also a good way to measure their interactions.



The colour field lines are not radial (as in electromagnetism) but compressed in a flux tube between the partons

2.6.5 Underlying event

The remaining piece of our proton case study, is the remnants of the proton itself after a hard scatter involving one of its partons. In a violent high-energy collision, an outgoing parton produces jets due to confinement, as we have seen. Similarly, the proton remnants (illustrated in Fig. 5) acquire colour in the collision, and will undergo similar hadronisation. The remnants, however, often travel along the direction of the incident proton, and predominantly produce soft and diffuse radiation as measured in the transverse direction to the beam.

2.7 MONTE CARLO GENERATORS

In order to discern deviations from the expected SM behaviour in the processes studied, we need to make predictions of the SM. Our theoretical framework allows for perturbative calculations to finite

orders, and non-perturbative processes such as hadronisation will remain. Using a Monte Carlo (MC) event generator, we can obtain a (pseudo-)random representation of the possible outcomes in for instance a proton collision, mimicking the stochastic processes by sampling a probability distribution. Complete generators will model both the hard-scatter process and parton showers (initial and final state radiation), hadronisation, multiple interactions and underlying event, providing a list of produced particles and their four-vectors at a given stage of the process. There are also incomplete generators calculating the hard-scatter cross sections only, but in return they may provide these calculations to higher orders.

The underlying hypotheses for the non-perturbative processes giving these distributions can vary: the widely used complete MC generator PYTHIA [23] uses the Lund string model. This is the main generator used for the work described in this thesis.

2.8 THEORIES BEYOND THE STANDARD MODEL

There are numerous proposed extensions of the SM, intended to answer one or more of the outstanding questions posed by observations that seemingly have no fundamental explanation in the existing theoretical framework. Particle masses are, as I may have hinted before, a free parameter in the SM which still seems to be of some profound importance, especially if we want to unify all the known forces of nature. There are also numerous independent observations of phenomena that tell us that only about 5% of the total energy content in the universe is matter as we know it, and as all theories used in any field of science describe it. There is evidence that there is about five times as much *Dark Matter* as normal matter; the rest of the energy content in the universe is considered to be *Dark Energy* [24], the general properties of which are completely unknown. Finally, there is no *a priori* knowledge that the particles considered fundamental right now would not in fact have constituents — the history of particle physics actually points in the other direction. One could also argue that the mass hierarchy and generational structure points to fermion compositeness. All in all, the

SM seems to be an effective theory holding up very well at the scales and the precision at which we have been probing it so far, but it may eventually have to yield to a more complete description of nature.

The measurements described in this thesis would be sensitive to many of the new phenomena predicted by such proposed extended theories. The strategy relies on simple yet powerful assumptions on what we can expect from SM processes, and the primary goal is to quantify the deviations in data from the SM prediction, rather than discover a specific hypothesised new phenomenon. Here I will focus on describing the so-called *benchmark models* used in the analysis: models making distinct predictions of observable distributions compared to the SM. When comparing these predictions to data, we can often make statements about the degree of compatibility with data we obtain with certain parameter values in the model. Thus we can rule out certain parameter scenarios based on what we measure in data.



With a benchmark model, we learn something even from not discovering anything new: we learn how we *can't* describe nature.

2.8.1 Contact Interactions

One way to model fermion compositeness is to consider that at some energy scale, a new force of nature becomes manifest, as we resolve what is keeping the composite particles together. Well before that energy, however, there may be an effect on the probability and kinematic characteristics of a process, such as jet production. We can thus discern that there is something new before resolving the details of the process. This situation can be satisfactorily modelled with an *Effective Field Theory* (EFT), as depicted in Fig. 6. Actually, this approach is

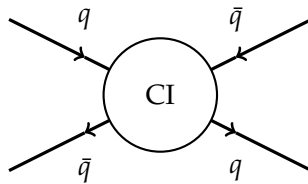


Figure 6: Feynman diagram illustrating the unresolved interaction leading to $q\bar{q}$ production in a Contact Interaction (CI) approach.

the same as in the four-point interaction of Fermi, describing nuclear β decay when there is not enough energy to resolve the W boson exchange. This is drawn in Fig. 7. In such a description, a scale Λ

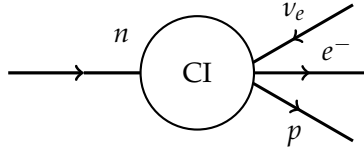


Figure 7: Feynman diagram illustrating the effective field theory approach to β decay.

is introduced, dictating at which point we can resolve the processes hidden in the circle — the Contact Interaction (CI) [25–27]. It follows that as Λ grows, the signal strength gets weaker, if we keep the probe energy constant. The description chosen in this work is an additional effective Lagrangian:

$$\begin{aligned} \mathcal{L}_{CI}(\Lambda) = & \frac{g^2}{2\Lambda^2} [\eta_{LL} (\bar{q}_{iL} \gamma^\mu q_{iL}) (\bar{q}_{jL} \gamma_\mu q_{jL}) \\ & + \eta_{RL} (\bar{q}_{iR} \gamma^\mu q_{iR}) (\bar{q}_{jL} \gamma_\mu q_{jL}) \\ & + \eta_{RR} (\bar{q}_{iR} \gamma^\mu q_{iR}) (\bar{q}_{jR} \gamma_\mu q_{jR})], \end{aligned} \quad (10)$$

where $i(j)$ is a flavour index, g denotes the strong coupling constant, and $\eta = 0, \pm 1$ represents the sign of the interference between CI and two-quark initial and final states of QCD: + for destructive and – for constructive interference. The CI is characterised by the compositeness scale Λ and its mode of interference with the QCD $q\bar{q} \rightarrow q\bar{q}$ process, where constructive interference is overall expected to lead to an enhanced signal, while for destructive interference, the effects of signal and interference compete. The CI modelling leads to non-resonant enhancement (or suppression) of jet production.

☞
Sign convention;
confusing but true

2.8.2 *Quantum Black Holes*

In a scenario where gravity propagates in more dimensions than the other fundamental forces, it would be diluted, causing it to appear much weaker than the others [28, 29]. This mechanism thus provides an explanation to the experimental observation that gravity is weaker than the other forces. The full set of space-time dimensions is commonly referred to as the *bulk*, while particles interacting under the SM live on the *brane*, a 4D hypersurface in the $4 + n$ dimensional scenario. The number n of extra dimensions vary between realisations; typically $n = 1$ in a Randall–Sundrum (RS) scenario [28] and $n = 6$ in an Arkani-Hamed–Dimopoulos–Dvali (ADD) scenario [29]. This would in both cases lower the fundamental scale of gravity, M_D ,² from the *Planck scale* $M_{Pl} \sim 10^{18}$ GeV to the vicinity of the electroweak scale $m_{EW} \sim 100$ GeV, which is clearly accessible at the LHC (see Chapter 3). This idea elegantly solves the so-called *hierarchy problem* in the SM, which is the question why these two seemingly fundamental scales are so widely separated, and it does so without introducing any new symmetries or interactions but by instead changing the space–time metric.

It does however introduce the possibility that microscopic or Quantum Black Holes (QBHs) are produced at the LHC. A TeV scale black hole created in a collision would decay to bulk and brane particles, giving an experimental possibility to detect it. If the black hole mass is larger than M_D , the black hole will thermalise and decay to high-multiplicity final states; however, there are many reasons to suspect that this is not the first mode of discovery, but rather 2-body final states are, as suggested in Ref. [30] and briefly summarised here.

Firstly, since they have not been discovered yet, it is unlikely that the energy threshold needed has been surpassed in previous experiments. Secondly, there is large suppression of Bjorken x through the PDFs, and energy loss from the initial parton-parton system, pushing the available black hole masses down for a given available centre-of-mass energy. In a regime below the production threshold energy,



Note that since they don't interact in the SM, right-handed neutrinos are here not constrained to stay on the brane!

² The naming conventions and parameter choices vary between models. Here we choose the ADD representation.

strong gravitational effects enhance the 2-body final state cross section through exchange of a mediating particle produced in strong gravity, even if the final state is not a black hole. Finally, even for cases with larger multiplicities, it may be seen as contrived to assume a complexity in which not also 2-body final states would be enhanced. Even so, a multi-body final state would still contribute to an analysis of 2-body final states which doesn't impose an upper limit on the number of final state objects.

2.8.3 *Dark Matter*

There is very little known about the properties of Dark Matter (DM). It interacts gravitationally, and makes up about $1/4$ of the energy content in the universe — a factor 5 more than the normal matter (at least partly) described by the SM. DM particles remain to be detected.

A common approach in collider searches for DM is to assume that the DM particles produced in a collision escape detection. However, for them to be produced in the first place, there has to be a production mechanism involving coupling to partons, leaving a non-zero probability also of jet production. The production mechanism is often modelled in an EFT approach, where the scale of the phenomena is too high to be resolved using the available collision energy. This resembles the treatment of CI outlined above. Care must however be taken to avoid using an EFT approach in the regime where the available energy is larger than the scale of the new phenomenon. Here a simplified theory, assuming a mediator with some mass and a set of coupling strengths to fermions and dark matter, is a more suitable approach.

2.8.4 *Excited quarks*

One consequence of quark compositeness would be the possibility of excited quark (q^*) states. Deexcitation proceeds through the emission of a gluon, making a resonant qg final state, since excitation energies would be discrete. Excited quark production and subsequent decay to

quarks and gluons via gauge interactions has been used as a common benchmark for the dijet mass resonance search [11, 31–34], and it is described in detail in Refs. [35, 36]. It is used in this thesis as a representative model for resonant dijet production.

THE LARGE HADRON COLLIDER

The Large Hadron Collider (LHC) [37] is a 27 km circumference storage ring with counter-rotating bunched proton or lead ion beams¹. It is located 100 m below ground at CERN outside Geneva, Switzerland. Some of the design specifications are given in Table 3.

The proton acceleration is staged in several steps, starting from the hydrogen source and over pre-acceleration using previous generations of CERN accelerators. The LHC is thus the last collider in a larger accelerator complex. When the protons are injected in the LHC the beam energy is already 450 GeV. From there the protons are further accelerated and the accelerator optics focus and defocus the bunches to optimise for efficient collisions and long beam lifetime. Once stable beams are declared, the lateral beam spot width in the ATLAS experiment, introduced below, is of $\mathcal{O}(10) \mu\text{m}$.

Similarly, reaching the design goals mentioned in Table 3 is done in incremental steps. During 2012, the beam energy was 4 TeV, with a bunch spacing of 50 ns. After Run1 a two-year upgrade shutdown followed, and Run2 began when the LHC started delivering beam at 6.5 TeV each, with a bunch spacing of 25 ns, in May 2015. As seen in the table, there are many empty proton bunch spaces — or *Bunch*

¹ As this work focuses on the proton collision data, the lead ion beams will not be discussed further.

THE LARGE HADRON COLLIDER

	Design	2012	2015
Beam energy (TeV)	7	4	6.5
Dipole magnetic field (Tesla)	8.33	~6.3	~8.0
Dipole cooling medium	liquid He		
Dipole temperature	1.9 K		
Peak luminosity in ATLAS (cm ² /s)	10 ³⁴	7.3·10 ³³	5.0·10 ³³
Number of protons per bunch	1.15·10 ¹¹	1.7·10 ¹¹	1.2·10 ¹¹
Number of proton bunches	2808	1374	2244
Number of bunch places	3564		
Bunch spacing (ns)	25	50	25 ²
Stored beam energy (MJ)	362	150	280
Expected luminosity lifetime	14.9 h	-	-
Minimum turnaround time	70 min		
Expected average turnaround time	7 h	-	-
Integrated luminosity/year (fb ⁻¹)	80 - 120	20.3	3.6

Table 3: Some design goal specifications for the LHC [37], along with actual performance by the end of 2012 and 2015.

Crossing Indices, BCIDs — foreseen. The 25 ns bunch spacing refers to the time spacing between BCIDs. Filled BCIDs are collected in the same *bunch train*, with many empty bunch spaces between trains, but none within them.

The beams only collide in dedicated collision points, where the beam paths intersect and around which detectors are built. The LHC has 8 such possible points, out of which 4 host large³ experiments: ATLAS [38], ALICE [39], CMS [40] and LHCb [41]. While ALICE and LHCb specialise in heavy ion- and *b*-physics respectively, ATLAS and CMS were both built to be general multi-purpose experiments, designed to both discover the *H* boson and, if possible, BSM phenomena.

³ In addition there are smaller experiments, which will not be detailed here.

3.0.5 Collider kinematics

The protons in the beam each carry the beam energy, presently 6.5 TeV. As two protons collide, the energy in the centre-of-mass frame, the centre-of-mass energy, is $\sqrt{s} = 2 \cdot 6.5 = 13$ TeV. Since the two protons have the same mass and same kinetic energy, they have opposite but equal magnitude momenta $|\vec{p}|$, and the proton-proton (pp) centre-of-mass frame and the detector or laboratory frame coincide. But, as we have learned, protons are composite particles, and in an LHC collision the energy is high enough to resolve the quark and gluon constituents. These constituents each carry a fraction of the proton momentum, which we denoted with (Bjorken) x . Thus, colliding partons may not have equal and opposite momenta, which means that the colliding centre-of-mass frame may differ from the detector frame. Here the concept of rapidity y comes in handy:

$$y = \frac{1}{2} \ln \left(\frac{E + p_z}{E - p_z} \right) \quad (11)$$

using the energy E and longitudinal momentum p_z of a particle. “Longitudinal” and “transverse” directions are taken with respect to the beam axis at the collision point. A collision system with unbalanced incoming longitudinal momenta in the lab frame will acquire a rapidity *boost* and as a whole move longitudinally along the beam direction. One can show that rapidity is additive, implying that the rapidity y as measured in the detector frame is related to that of the collision centre-of-mass frame y_{CM} through the simple transformation

$$y = y_{CM} + y_B \quad (12)$$

where we have introduced the boosted system rapidity with respect to the detector frame, y_B .

Given that the initial state momentum is not clearly known, the quantity of interest at a hadron collider tends to be the transverse momentum, p_T . Since the protons move along the beam axis and the partons inside have relatively small intrinsic transverse motion, the initial state p_T is considered to be 0. Being a vectorial quantity, linear



The proton mass energy is negligible: ~ 1 GeV, 10000 times smaller than the kinetic energy.



“Coincide” is a simplification: in reality a small crossing angle gives the pp frame a non-zero transverse component in the lab frame.

momentum is conserved also component wise, so we immediately know two things: that all transverse momentum must have been transferred in the collision, and that the total transverse momentum of all outgoing particles should sum up to 0. This makes p_T extremely useful for the hadron collider physicist.

We can now express the four-momentum of a massless particle as

$$\begin{aligned} p^\mu &= (E, p_x, p_y, p_z) \\ &= (p_T \cosh(y), p_T \sin(\varphi), p_T \cos(\varphi), p_T \sinh(y)), \end{aligned} \tag{13}$$

where all quantities are experimentally observable.

3.0.6 Luminosity and probability

In nuclear and particle physics, probability is often referred to in terms of cross section (σ). To discover the rare processes we haven't seen yet but we do hope are technically possible, we need a large number of collisions. The key concept here is instantaneous luminosity, L , defined through the rate R of events of some type and the cross section for them to happen:

$$R = L \cdot \sigma \tag{14}$$

which in a time interval Δt gives a number of events

$$N = \sigma \int_t^{t+\Delta t} L dt \tag{15}$$

which introduces the concept of integrated luminosity.

For a given cross section for a new phenomenon, a higher integrated luminosity will thus increase the chances for discovery. Conversely, if the integrated luminosity is known, information on the cross section can be deduced from the number of events observed. N and L are experimental quantities, while σ is a theory parameter, containing the information about the modelling of the physics process — the information we are really interested in. Knowing the integrated luminosity is thus the key to make theory interpretations of an experimental event count, and it is given in units of fb^{-1} or pb^{-1} on almost every data figure made public by a collider experiment.

☛
cross section, in units of barns, b, or cm^{-2} : in some sense an area, a geometrical image of how likely it is to hit something.
 $1\text{b} = 10^{-28}\text{m}^2$

3.1 COLLIDER DATA TAKING

This section introduces some data taking nomenclature, along with the specifics of selection of data to record.

In order to understand the data taking at a collider, it is useful to keep a couple of quantum mechanical facts in mind:

1. anything that can technically happen, will happen eventually (it's a matter of probability)
2. we already know about the things that happen quite often (it's a matter of probability)

As we shall see, these principles govern the design of accelerators as well as the data acquisition strategy of the experiments.


3.1.1 *The LHC/beam conditions*

Apart from an extended accelerator shutdown period in the winter, the experiments are continuously taking data. In practice this means that proton bunches are injected into the LHC (a “fill” starts), accelerated up to collision energy, and then the beams are focused in the accelerator optics to optimise the bunch geometries with respect to beam losses and collisions in the collision points. Once the beam properties are optimised, “stable beams” are declared, and collision data taking can begin. Data are collected over a period of time where beam and detector conditions are stable. This is called a run, and maximally lasts for the duration of a fill (but often shorter). As seen in Table 3, one fill can often last more than 15 hours.

Triggering

In the LHC beam conditions as of 2015, approximately every 25 ns there is a bunch crossing, and in each bunch crossing, there are multiple proton collisions⁴. If the signals from every collision were to be read out, that corresponds to a rate of 40 MHz. In reality, ATLAS

⁴ on average 20.7 in 2012 (50 ns bunch spacing), and 13.5 in 2015


 Going from 40 MHz to
 1 kHz means
 dismissing 99.9975%
 of the data

only writes collision data to tape at a rate of 1 kHz. This reduction by a factor 10^5 is not random, but based on selecting collisions according to certain criteria, viz. a signal from a certain amount of energy deposited in a certain sub-detector, and combinations thereof. This is called a *trigger*. At every bunch crossing, the detector signals are written to a buffer, and read out only if a trigger has “fired”. A trigger is based on signatures such as two energy depositions compatible with electrons passing through the detector, above a certain energy threshold, or, an energy deposition compatible with a highly energetic hadronic jet. In principle, the outcome of one given collision can fire multiple triggers. The triggered and recorded signal from a bunch crossing is called an *event*. In the subsequent data analysis, the trigger decision is used to select the events that are interesting with respect to the phenomenon one is interested in.

As mentioned previously, the already known phenomena are the ones occurring more frequently. For instance, the energy distribution of jets is steeply falling, meaning, that high-energy jet events are very rare compared to low-energy ones. This implies that in a range of single jet triggers at different energy thresholds, the low-threshold ones fire much more often than the ones at higher threshold. But, the high energy events are often of much higher interest. In order to reduce the relative triggering rate of less interesting events, allowing more bandwidth for the more ones considered more interesting, it is very common to apply a *prescale factor*. A prescale factor N_p means that only one in every N_p triggered events is actually recorded. A trigger with prescale factor $N_p = 1$ is called un-prescaled. The real rate of the triggering process is recovered by multiplying with the prescale factor, which in effect is a weight. The statistical precision is however smaller than that achieved by recording the full set of events. This means a loss of sensitivity to new phenomena at lower p_T , implying that it will take more data (longer time) to discover them. Using un-prescaled triggers only gives full sensitivity, but limited to the higher p_T regime.⁵

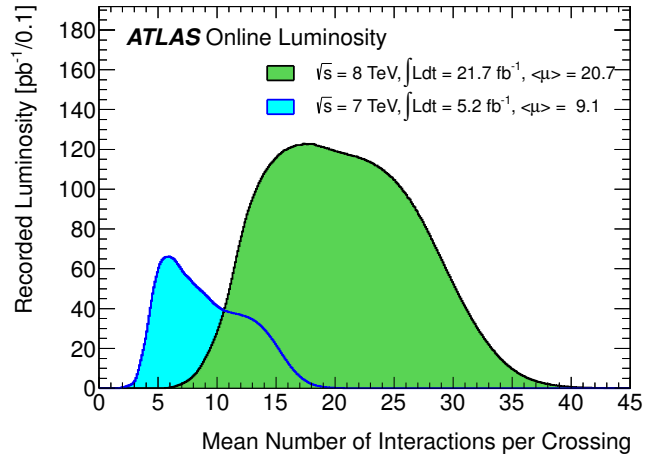
⁵ An elegant solution to this experimental trade-off is to read out a minimal amount of information from each event, which allows storing these at a higher rate. The challenge is ensuring that the reconstruction of these jets does not suffer from

3.2 PILE-UP

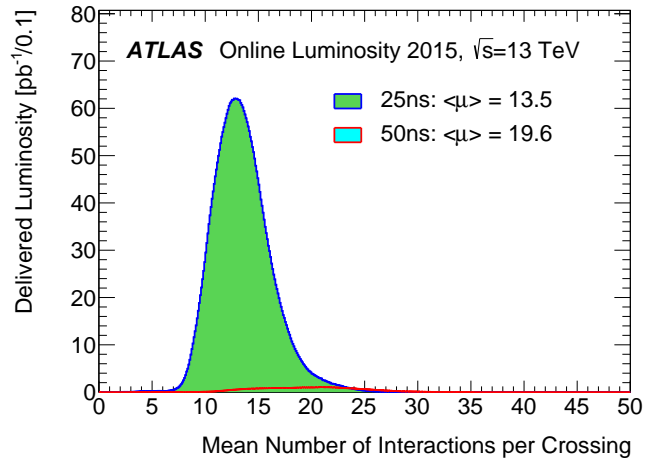
In Sec. 3.0.6 we introduced the concept of luminosity and linked that to the probability to observe a new, probably rare, phenomenon. In order to maximise the instantaneous luminosity, and thus quick discovery potential, the LHC operates in a mode of several simultaneous proton-proton interactions in a given bunch crossing. Most of these are processes that are already well known, but occasionally, a process that triggers the readout happens. The full event is then recorded, along with the overlaid activity from the simultaneous interactions. This is referred to as pile-up, which is a common term for when multiple signals get overlaid in detector readout, and generally this relates to the relationship between the rate of interactions and the signal collection and readout time. I stress that at the current typical LHC conditions, the overlaid events are *simultaneous* with the triggering collision within a time interval very much smaller than the bunch spacing, and events without pile-up are extremely rare, as is seen in Fig. 8. Since there is no way of avoiding collecting all this overlaid signal at once, techniques to recognise the triggering collision and correct for the signal from the rest have to be devised.

Figure 8b also shows the difference in the average number of simultaneous interactions per bunch crossing, denoted by $\langle \mu \rangle$, achieved with 25 and 50 ns bunch spacing, respectively. With fewer bunches, a larger number of pp collisions have to occur in the same bunch crossing to achieve the same instantaneous luminosity.

the loss of information from for instance the tracker. Far from my idea, I still venture to say that with higher luminosities ahead of us, this type of “trigger-level” analysis and fast reconstruction of objects at trigger level is the way forward to retain sensitivity to phenomena in the sub-TeV scale, without requiring associated production of objects whose dedicated triggers have a lower prescale.



(a) 2010–2011 (7 TeV) and 2012 (8 TeV)



(b) 2015 (13 TeV)

Figure 8: The distribution of the average number of simultaneous interactions per bunch crossing for data taking in (a) 2010–2012 and (b) 2015.

THE ATLAS EXPERIMENT

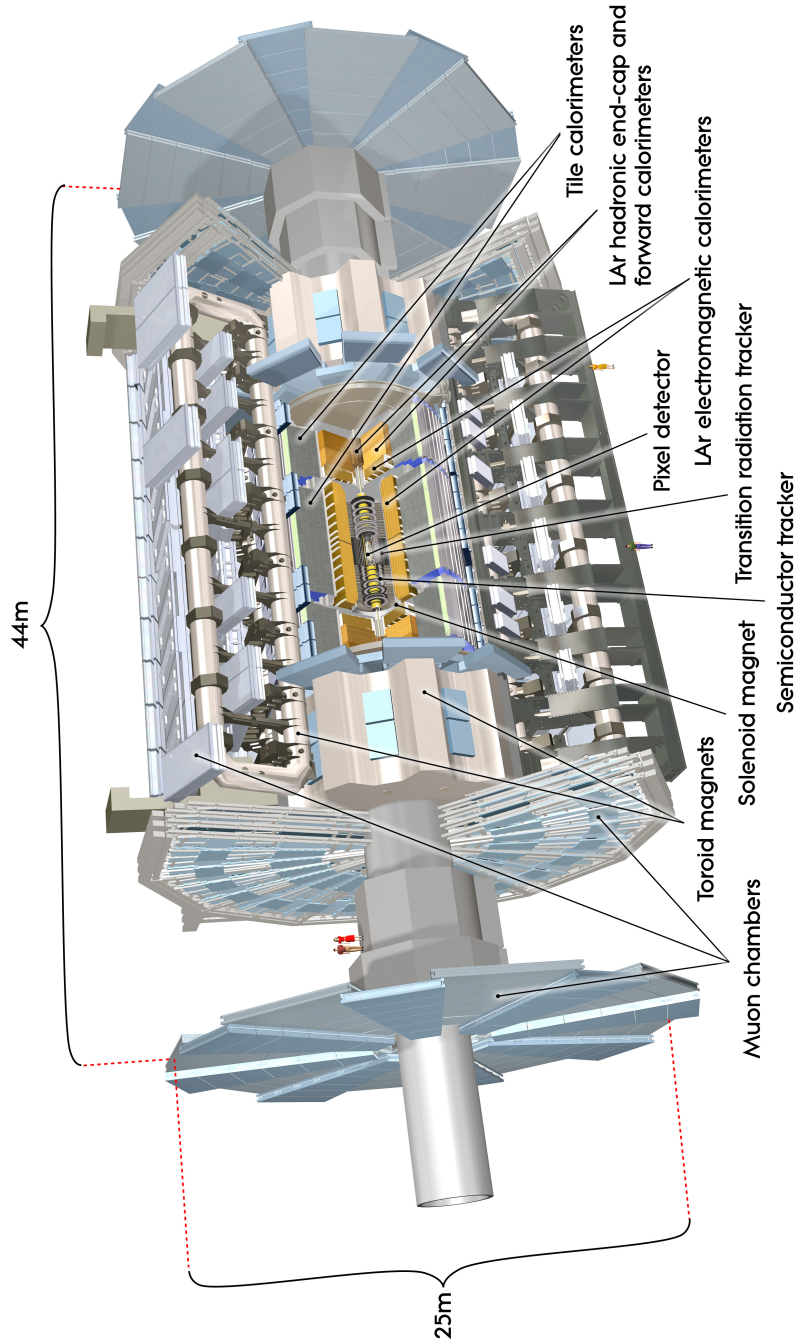
The ATLAS detector, drawn to scale in Fig. 9, is an impressive beast in many ways. To the visitor approaching in the pit 100 m below ground, already the size of this gradually emerging lying cylinder, 25 m high and 45 m long, inspires awe. It comprises several sub-detectors, each employing their own technique to contribute their piece to the puzzle of particle identification, and trajectory and energy measurement. These have been designed and built over decades, in collaboration between different institutes across different continents, and are operated day and night in the same spirit. Reading out, storing, and analysing the large amount of data it produces requires an equally large effort in design and collaborative operations. In this chapter, I will summarise the steps needed from proton collision to the data analysis that the rest of this book is devoted to. It has to be a selective description, and for more complete descriptions of ATLAS, the reader is referred to Ref. [38].



For coming upgrades
see for instance
Refs. [42, 43]

4.1 COORDINATE SYSTEM

ATLAS uses a right-handed coordinate system with its origin in the centre of the detector at the nominal interaction point (IP) and the



48 Figure 9: The ATLAS detector, with subdetectors indicated [44].

z -axis directed along the beam pipe.¹ The positive x -axis points from the IP to the centre of the LHC ring, and the y -axis points upward. Cylindrical coordinates (r, φ) are used in the transverse plane, φ being the azimuthal angle around the z -axis. The pseudorapidity is defined in terms of the polar angle ϑ as $\eta = -\ln \tan(\vartheta/2)$ with ϑ measured with respect to the z -axis. Pseudorapidity is a convenient concept when discussing coverage with respect to the beam axis.

4.2 COLLIDER PARTICLE DETECTORS: THE ONION DESIGN

The philosophy of an experiment designed for the discovery of something generally new and unknown is to measure everything — to not let anything escape. Now this is of course not physically possible with the knowledge we have — for instance, as mentioned in Sec. 2.2.1, neutrinos easily traverse entire planets without interacting at all. The next best thing, is then to make sure that the rest of the known particles will interact in the detector, such that upon creation, their properties can be carefully measured, and the remaining details deduced. To achieve this, the subdetectors are ordered radially from the interaction point — where particles are created and travel outwards — in such a way that finer details can be resolved in the beginning, and in the outer layers, the particle energies are measured by complete absorption — in effect, destruction of all remaining information!

The basic principles are illustrated in Fig. 10. Charged particles, like electrons and protons, interact with the tracker material, while neutral particles like photons and neutrons don't. Photons do shower in the electromagnetic calorimeter, while neutrons only interact hadronically. Combining the signal from the different subdetectors, one can thus distinguish these particle types. Muons barely interact with any of the material, and are thus the only particle to make it all the way out to the muon spectrometer. Neutrinos escape undetected as they don't interact with the material at all. Their presence can be deduced

¹ This differs from the beam axis: the beams collide at a slight angle to avoid interactions upstream.

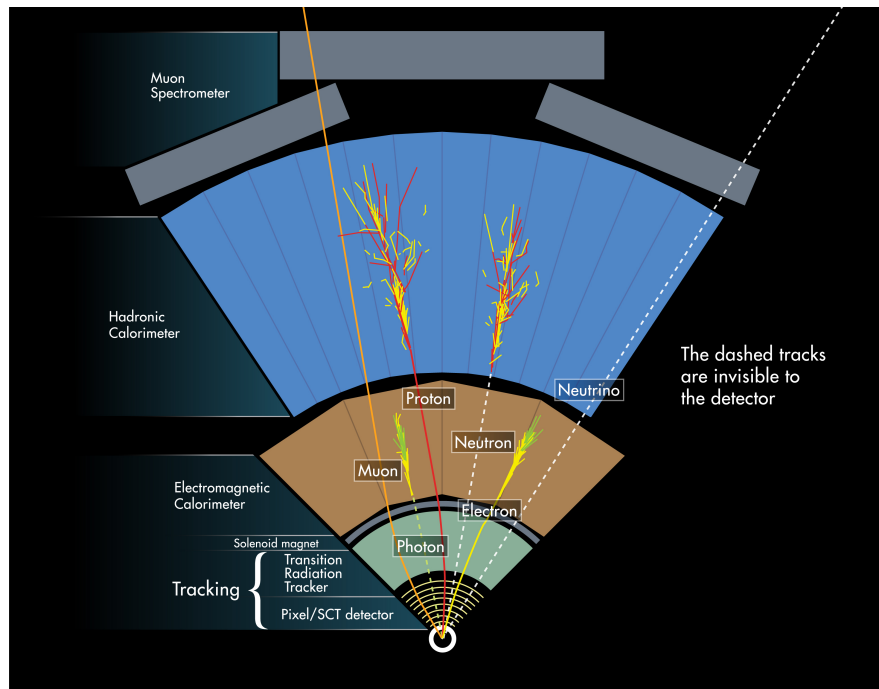


Figure 10: The principle of particle identification through interactions with a cross-sectional wedge view of the ATLAS detector [44].

from non-conservation of total transverse momentum in a collision (so-called missing transverse energy, E_T^{miss}).

It is an overall feature that there is finer segmentation of the detector closer to the centre. Apart from the pure geometrical fact that the density of produced particles will decrease radially as $1/R^2$, this is the result of a trade-off between precision measurement and the cost of finely segmented read-out. Electronics require room, feed-throughs, cracks in the detector coverage. They introduce material and heat load. Cooling introduces further material and cracks. Un-instrumented (“dead”) material in the detector reduces the resolution in the energy measurement. Cracks introduce regions where particles are poorly

measured or even escape the detector. Fine segmentation is thus only used where it is most needed.

The rest of this chapter will describe ATLAS's take on this design philosophy. It will be a maze of acronyms, but be patient; hopefully it's useful for later reference. Throughout this section, keep in mind that even when only one detector is mentioned, the symmetry in η entails that there is one of each detector type in the *end-caps* located on each side of the central *barrel* region.

4.3 THE ATLAS DETECTOR SUBSYSTEMS

While most of the information in this chapter is available in Ref. [38], ATLAS continuously evolves, with many of its institutes involved in detector research and development in parallel to data taking. During the long shutdown between Run1 and 2, a new vertexing detector, the Insertable B-Layer (IBL) [45, 46] was installed closest to the beam pipe.

4.3.1 Magnets

ATLAS uses two magnet systems: an outer air-core toroid system, and a thin 2 Tesla superconducting solenoid surrounding the inner detector containing tracking detectors. Figure 11 shows a sketch of the magnet geometry.

A magnetic field is crucial for momentum determination of charged particles, as the bending radius of a charged particle trajectory is proportional to the momentum perpendicular to the magnetic field direction. Since the solenoid and beam axes are aligned, this corresponds to determining the p_T of the particle. However, at high $|\eta|$, only a fraction of a particle's momentum is perpendicular to the field from the solenoid. The toroid system is intended for determining muon momentum with high precision and is arranged such that the field is mostly perpendicular to the muon trajectories even at large $|\eta|$, thus compensating the limitation of the solenoid. The open structure reduces the material in front of the muon spectrometers to a minimum,

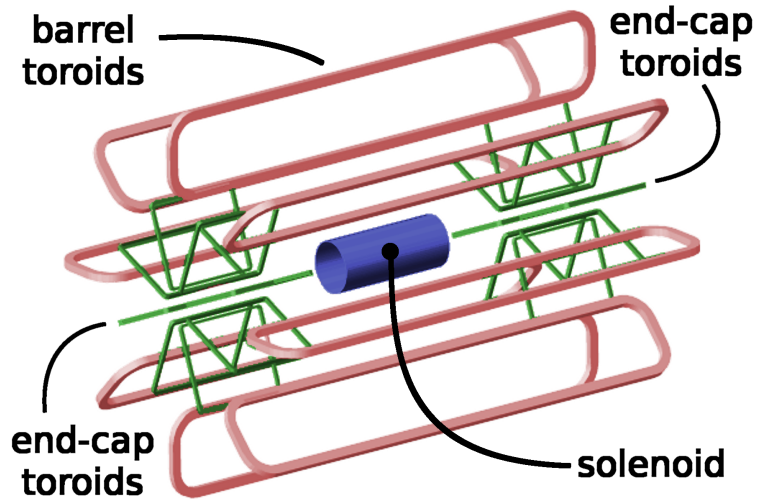


Figure 11: The ATLAS magnet system [47].

minimising the effect of multiple scattering that would deteriorate the resolution.

4.3.2 *The inner tracker: silicon strips and pixel detector*

Given that particles are produced in the interaction point, the track density is very high in the innermost detectors, requiring excellent spatial resolution of signal for momentum and vertex reconstruction. This is achieved with highly granular silicon tracking detectors, with concentric cylindrical geometry in the barrel region and perpendicular disks in the end-cap. The overall layout is seen in Fig. 12. Tracking extends to $|\eta| = 2.5$ in total, with the highest granularity detectors, the pixel and IBL detectors, located around the vertex region close to the IP. A typical track crosses eight strip layers (making four space points) and three pixel layers, giving position coordinates in 3D: the radius R , φ and z . The intrinsic accuracy in $R - \varphi$ is $10 \mu\text{m}$ in pixel, and $17 \mu\text{m}$ in the strips.

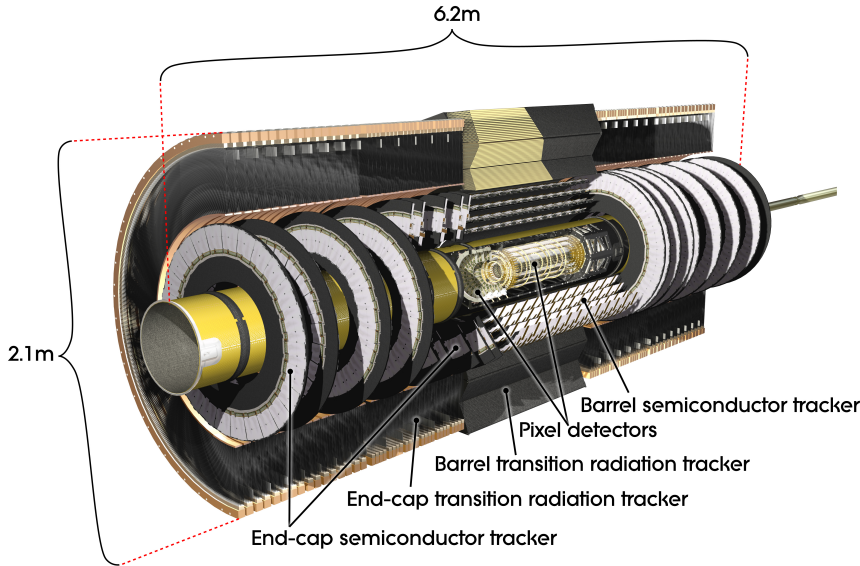


Figure 12: A zoomed-in cut-away view of the inner detector [44].

The most important job for the innermost detectors is vertex reconstruction. In an environment with high particle multiplicity and several proton collisions in the same bunch crossing, high precision reconstruction of the primary vertex, indicating the primary interaction point, is absolutely mandatory. Furthermore, for the identification of heavy quarks such as b or c -quarks, whose relatively long lifetime allows travelling a detectable distance before decaying, reconstruction of displaced secondary vertices, and determining their degree of pointing back to the primary vertex, is equally necessary.

As mentioned, the inner detector has recently been complemented with an additional pixel layer, the IBL. It improves the vertexing capabilities of ATLAS and supplements the previously innermost layer which has been, and will increasingly be, exposed to much radiation. Loss of coverage in these detectors would dramatically deteriorate vertex reconstruction as well as b -tagging.

4.3.3 The Transition Radiation Tracker

The TRT is a gaseous ionisation detector, with drift chambers made from thin cathode tubes (or *straws*) containing mostly Xe or Ar, and CO₂ for avalanche quenching. It surrounds the inner silicon tracker detectors and has a similar structure, as can be seen in Fig. 12: the straws are parallel to the z -axis in the barrel and radial to it in the end-cap. Signal is read out from thin anode wires in the straw centre. It is specialised in distinguishing electrons from other particles, using the *transition radiation* emitted when they cross a boundary between two media of different refractive indices. All charged particles emit such radiation, but the energy radiated is proportional to the Lorentz factor γ which for a given energy² is higher for lighter particles. Since electrons are much lighter than all other charged particles, this radiation turns out to be a good discriminant — especially against charged pions which could otherwise introduce ambiguities in case of insufficient information from other subdetectors. The transition radiation is provoked by radiators placed between the straws, and the X-rays thus produced are absorbed in the Xe, making a large ionisation signal.

Apart from its electron identification capacity, the TRT provides a large number of 2D points in $R - \varphi$ along a track, with an intrinsic accuracy of $130\mu\text{m}$ per straw. When combined with the 3D information from the inner tracker, they extend the track lever arm, enhancing the spatial as well as momentum resolution.

² With $\beta = v/c$, the particle's velocity v expressed as a fraction of the speed of light c , we define γ as

$$\gamma = \frac{1}{\sqrt{1 - \beta^2}} \quad (16)$$

and note that at fixed energy, lighter particles travel faster. It is clear that γ increases very steeply at high β , making the impact of even small changes in mass quite visible.

4.3.4 *Calorimetry*

The topic of calorimetry is of particular importance to much of the work described in this thesis. There will be a complete chapter dedicated to the calorimeters (Chapter 5) in the next part of the thesis. Here only the main features of the ATLAS calorimeters are mentioned.

The task of a calorimeter is to fully contain and measure the energy of an incident particle. Thus, it also absorbs the particle and no further measurement on it is possible. Good absorption prevents leakage out into the muon detectors.

An overview of the ATLAS calorimeter system is shown in Fig. 13. The combined ATLAS calorimeter systems provide near-hermetic

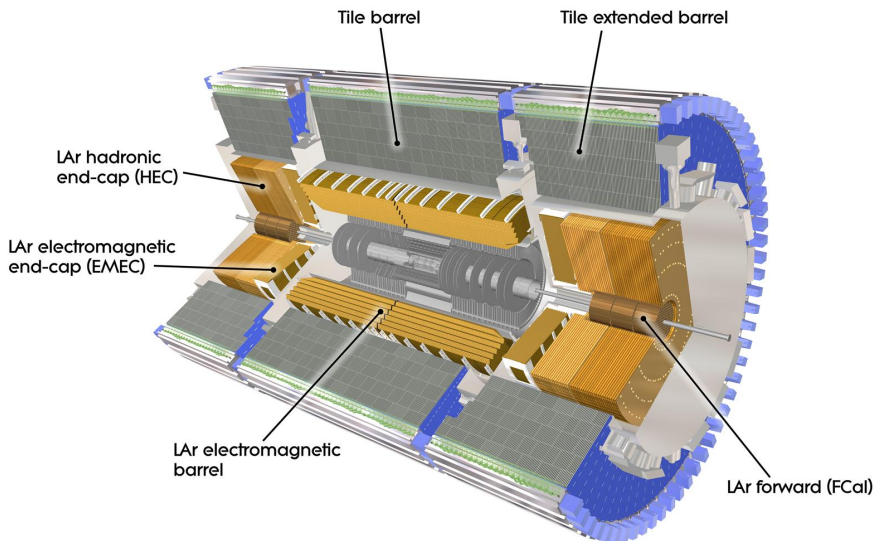


Figure 13: A cut-away view of the calorimeters [44].

electromagnetic and hadronic coverage out to $|\eta| = 4.9$. All ATLAS calorimeters have longitudinal and lateral segmentation to provide directional information. The central parts of the ATLAS calorimeters

have high granularity to enable pointing back to the primary vertex. The calorimeter is also extensively used for triggering.

4.3.5 *Muon spectrometers*

The outermost detector system of the big ATLAS cylinder is the muon system. It consists of chambers placed in three layers, cylindrical in the barrel region and in perpendicular planes in the end-cap region. They employ a range of charged particle detection techniques in subdetectors: drift tubes and cathode strip chambers for precision tracking, and fast resistive plate and thin gap chambers for triggering and second trajectory coordinate. The only hint that signal in these chambers comes from a muon is the simple fact that other charged particles are rarely expected to make it as far out in the ATLAS detector system.

Given the large scale of these detectors, relative alignment becomes crucial for an accurate momentum reconstruction. For instance, the drift tube alignment is continuously monitored using about 12000 precision-mounted alignment sensors, which optically detect deviations from straight lines. As for all tracking detectors, the final alignment is done from the reconstruction of tracks measured in the detectors themselves.

4.3.6 *LUCID*

Closest to the beam pipe, 17 m from the interaction point, the luminosity measurement detector LUCID (LUminosity measurement using Cerenkov Integrating Detector) sits. It detects the Cerenkov radiation produced in quartz windows as charged particles from the collision debris pass through it. It is in principle a particle counting device, using the approximate proportionality between particle multiplicity and the number of interactions to measure the instantaneous luminosity of the proton beam collisions. For an excellent account of the methods to do this, see Ref. [48]. Here, all we need to know is that the luminosity is deduced from the number of particles measured and

the cross section for inelastic proton collisions. It is averaged over a *lumiblock* — some period of time extending across several bunch crossings, typically of order one minute.

4.3.7 More forward: ALFA and ZDC

ALFA (Absolute Luminosity for ATLAS) and the ZDC (Zero-Degree Calorimeter) are located at 240 and 140 m from the interaction point, respectively. ALFA uses Roman pots to measure the proton-proton cross section, by counting forward protons as close to 1 mm from the beam. The ZDC measures the neutral component of beam remnants (spectators), which travel in a straight line while the beam bends, to measure centrality in lead ion collisions. It is also used for detection of diffractive processes and minimum-bias triggering.



The optical theorem relates the forward scattering amplitude of a process to its total cross section.

4.4 DETECTOR SIMULATION

Apart from collision data, ATLAS relies heavily on simulated collisions to make predictions based on the SM. The MC generators described in Sec. 2.7 can create detailed *MC truth* or *particle level* records of the particles produced in a simulated collision, but they don't take any detector effects into account. These effects can be everything from pure acceptance (or coverage) effects to energy loss in detector material or stochastic effects affecting the position resolution, and they are present all the time in the real data. To correct for this, simulated particles are “propagated” through a GEANT4 [49] detector simulation, where the passage of particles through matter is simulated in detail, based on the ATLAS geometry and material. This results in *reconstructed* or *detector level* distributions.



The concept of “truth” is often used when assessing the impact from experimental conditions on an observable.

4.5 ATLAS CONDITIONS

From collision to recording and analysis of data, there are still a few steps. Those common to all ATLAS data taking will be outlined here.

4.5.1 *Trigger system*

ATLAS uses trigger system split into a fast trigger system, Level-1 (L1), implemented in hardware and making the initial selection of events, and a slower system using the L1 decisions as input. In Run1 these were passed to the software triggers at Level-2 and the Event Filter (EF) level, which used Regions Of Interest to identify for instance localised high-energy deposits in the calorimeter, using a jet finding algorithm. In Run2 the software level was reduced to one High-Level Trigger (HLT). In Run1 the EF maximum accept rate was 400 Hz while in Run2 the HLT is capable of a rate of 1 kHz.

4.5.2 *Data quality*

As mentioned in Sec. 4.3.6, the average luminosity is measured in lumiblocks of 1-2 minutes. Generally, data quality stamps are also assigned on a lumiblock basis (for instance, high-voltage stability in the LAr calorimeters). The data taking lumiblocks where all detector conditions are understood and smooth are listed in a *Good Runs List* (GRL) applied as part of the event selection in every data analysis.

• The requirements on the detector differ between analyses; so do the GRLs.

4.5.3 *Data processing*

The outcome of both collision data taking and simulation of physics processes propagated through a detector simulation, is signals in the channels of the detector. The detector signals from a triggered event are digitised *online* (in real time) and through existing mapping from readout channel to geometry, reconstruction of for instance tracks and calorimeter energies can begin. The RAW detector data are here transformed to event level data, which amounts to a large reduction in size. In particular, storing a handful of track parameters requires much less space than storing ionisation information and coordinates in 3D for each hit. This size reduction continues as energy deposits in calorimeter cells are combined to form physics objects such as jet or electron candidates. The final data format used for analysis, presently

in the form of a *DAOD* (for Derived Analysis Object Data) often only includes the physics object candidates of interest to the analysis, along with trigger decision information and event-level information used for calibration and matching to the GRL, for instance. This amounts to both a reduction in size and a loss of detail available to the user, highlighting the need for several types of DAODs. Although substantially reduced in size, the final data set can still amount to several TB of data, which is too large for the individual user to store. Much of the analysis and the previous steps are thus done on common infrastructure and with distributed computing — simply put, the much more lightweight analysis code is sent to where the data are stored instead of the other way around. The event selection applied in the user code often reduces the data set size drastically, giving final files which are easily manipulated and stored on a regular laptop.

Part II

JETS

Having settled that partonic interactions, and notably hadronic final states, can be observed through the emergence of jets, we must now proceed to establishing a procedure for identifying a jet from our collision. This is a rich topic, as it encompasses the full range from our theoretical understanding of the mechanisms producing a jet, over the measurement of energy in our detectors and the difficulties associated with identifying the origin of that energy, to some clever assignment mapping some of it to our theoretical concept of a hadronic shower originating from an energetic parton. Luckily, it is also a crucial concept for the understanding of my research, and I will have the pleasure of expanding on it at length!

CALORIMETRY

This section will briefly describe the principles of energy measurement in calorimeters, as well as the algorithms used for identifying signal corresponding to energy depositions from interacting particles.

5.1 ELECTROMAGNETIC CALORIMETRY

The electromagnetic (EM) calorimeter detects photons and any charged particle through the energy depositions from the EM showers resulting when these particles traverse a dense medium. The thickness of a calorimeter is often expressed in *radiation lengths* X_0 . It is the mean distance travelled before an electron loses $1/e$ of its energy through emitting *bremsstrahlung*. Conversely, it is $7/9$ of the mean free path before a photon above threshold undergoes pair production. These two processes lead to an EM cascade or *shower* of electrons and photons. The radiation length is a characteristic scale of the EM shower evolution, but corresponds to a material specific actual length. Similarly, the transverse dimension of the shower is given by the Molière radius R_M , which relates to the radiation length approximately as $R_M = \frac{21\text{MeV}}{E_c}$, where the critical energy $E_c = \frac{500\text{MeV}}{Z}$, depends on the atomic number Z of the material. This radius gives the material specific shower position resolution: on average, 90% of the shower



e here is the base for the natural logarithm:
 $e \approx 2.71828$

energy is contained within a cylinder with this radius centred on the shower.

The cross section for EM processes is proportional to Z^2 . The material choice tends to reflect this, as a higher cross section will reduce the actual length corresponding to $1X_0$ as well as R_M . Another consideration is material transparency to or readout of the energy depositions. This leads to two main technologies:

- homogeneous scintillating crystals, with at least one high-Z element, which can be read out using photomultipliers, or
- sampling calorimeters where a high-Z absorber provokes energy loss, while an interleaved active medium is responsible for its detection via ionisation or scintillation.

The choice of homogeneous/sampling calorimeter applies also to hadronic calorimetry, albeit with different optimal material choices; ATLAS uses only sampling calorimeters.

5.1.1 *Liquid-Argon electromagnetic calorimeter*

The Liquid-Argon (LAr) EM calorimeter is a layered detector, using lead absorber plates and liquid argon as active medium producing ionisation. It is divided in Electromagnetic Barrel (EMB) and End-Cap (EMEC) parts, positioned outside the solenoid and housed in their own cryostats. The absorber plates and electrodes are arranged in an accordion shape as illustrated in Fig. 14. The accordion shape provides full φ coverage and comparatively fast readout. To compensate for energy absorption in the solenoid, a thin pre-sampler layer of instrumented argon is located between the solenoid and the central parts of the EM calorimeter. The EM calorimeter is more than $22X_0$ thick, to ensure minimal leakage of electromagnetic energy.

In $|\eta| < 2.5$, the region corresponding to the inner detector, the innermost layer has very fine granularity. Apart from allowing for precise measurement of photons and electrons, it enables distinction between neutral mesons (typically π^0) and photons. The latter is in fact a matter of separating showers from single photons, from those

Pb: $Z = 82$

Argon boils at 87 K.

Electromagnetic energy here refers to energy that could have been transferred in EM interactions.

5.1 ELECTROMAGNETIC CALORIMETRY

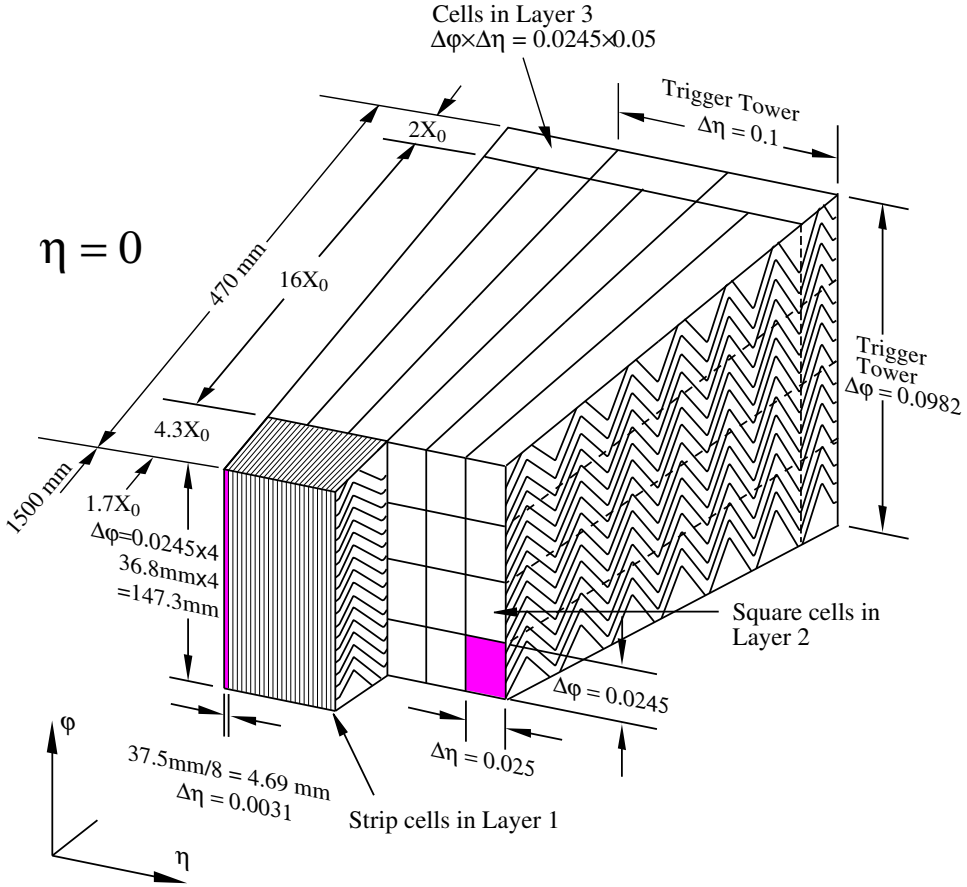


Figure 14: A sketch of the LAr geometry in an EMB module, showing the lateral and longitudinal segmentation in layers of radially coarser granularity [38].

stemming from two collinear photons from neutral meson decay. The small shower separation requires high granularity. Above all, from the first and second layers, this region has pointing capabilities to identify the vertex associated with photons, which don't produce tracks in the inner detector.

The opening angle is p_T dependent. At $p_T \sim 80 \text{ GeV}$ the π^0 rejection still benefits from segmentation.

5.2 HADRONIC CALORIMETRY

Hadronic energy loss is based on nuclear rather than atomic interactions. These include e.g. spallation, neutron capture and nuclear recoil. The secondary hadrons produced give rise to hadronic cascades as long as they carry enough energy. Hadronic cascades generally have relatively few high-energy particles compared to EM showers, and thus have large fluctuations. Eventually the low energy transfer reactions will remain undetected. For an electrically neutral hadron like a neutron, hadronic interactions is the only way to detect it. While the charged hadrons interact electromagnetically, they too may well produce neutral particles through nuclear interactions upstream. While most low-energy nuclear interactions such as recoils are lost, a fair fraction of the high-energy interactions lead to π^0 production which subsequently leads to EM showers in the hadronic calorimeter as the π^0 decays to a photon pair. Similarly, nuclear de-excitation γ rays lead to EM interactions.

The characteristic hadronic energy loss length is the *absorption length* λ_{int} , defined as the mean distance required to reduce by a factor $1/e$ the number of relativistic hadrons travelling through a medium. This is typically $\mathcal{O}(10)$ times longer than the radiation length in a medium, making hadronic calorimeters very thick. Thus, hadronic calorimeters form the outermost layer. The optimal choice of material is not necessarily the high Z materials of EM calorimeters. For instance, very light atoms such as hydrogen are often advantageous for neutron detection.

The relative detection efficiency of hadronic and electromagnetic energy depositions in a hadronic calorimeter is denoted by h/e . From the discussion above, it is clear that the detection efficiency of hadronic interactions is often comparatively small. If $h/e = 1$, the detector is said to be compensating. This can be achieved by reducing the EM efficiency, increasing the hadronic efficiency (through the use of materials containing hydrogen) or by introducing a fissile material producing additional radiation after fast neutron capture.

The ATLAS hadronic calorimetry is non-compensating and makes use of two different technologies, covering different range in η .

Remember the 5 orders of magnitude between atomic and nuclear size mentioned in Chapter 1!

5.2.1 Tile

The Tile calorimeter uses steel absorbers and scintillating polystyrene tiles as active material, read out with photomultiplier tubes via wavelength shifting fibres bringing the light from UV to the visible range. Figure 15 illustrates this. It has a barrel and an extended barrel part,

Fe: $Z = 26$. Plastics are organic molecules, containing much hydrogen.

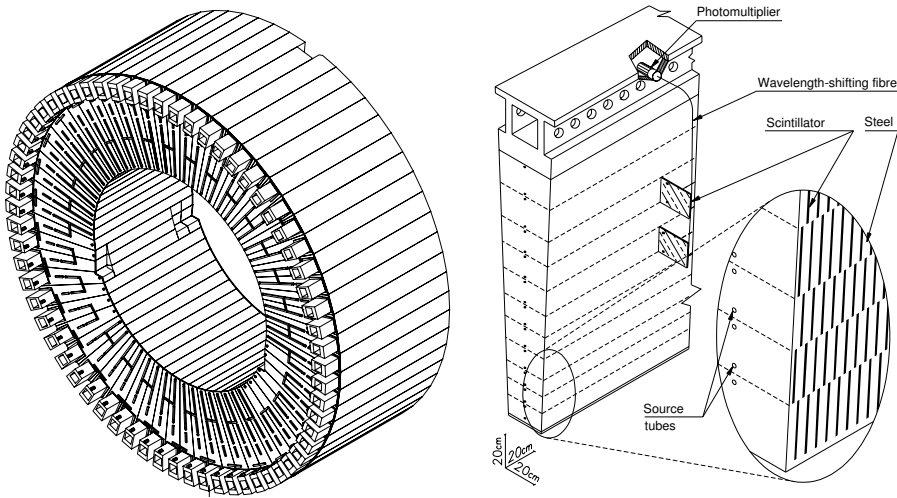


Figure 15: A sketch of a the Tile calorimeter, showing the overall layout and the scintillator tiles and steel plates as well as the readout fibres and photomultipliers. Particles enter from the centre (left) and bottom (right) [38].

reaching out to $|\eta| < 1.7$. The average radial depth is $7.4\lambda_0$, and its main purpose is to measure the energy and directions of hadronic jets.

5.2.2 LAr forward calorimeters

Cu: $Z = 29$

The Hadronic End-Cap (HEC) and Forward Calorimeter (FCal) are LAr calorimeters, housed in the same cryostats as the EMEC. The HEC uses copper absorber plates instead of lead, while the FCal uses both copper and tungsten plates: copper for EM calorimetry in the innermost layer and tungsten in the outer two for hadronic. The HEC has a depth of $\sim 12\lambda_0$ while FCal, sitting in a region of very large activity at small angles to the beam, has a total depth of $\sim 10\lambda_0$ and $\sim 200X_0$. The challenging radiation environment led to a coaxial electrode design, enabling smaller LAr gaps than in the barrel,¹ to avoid problems with ion build-up while retaining high material density. In addition, the signal is faster than in the barrel due to the shorter drift time in the LAr gap.

5.3 RESOLUTION: ENERGY AND GRANULARITY

Not only is the task of the calorimeter to fully contain the energy from high-energy particles: as the name suggests, they also measure it. Unlike for tracking detectors, which rely on trajectory bending for momentum resolution, the calorimeter energy resolution gets better with incident energy. The relative energy resolution can be expressed as

$$\frac{\sigma}{E} = \frac{a}{E} \oplus \frac{b}{\sqrt{E}} \oplus c, \quad (17)$$

where the terms are in turn referred to as the *noise term*, the *sampling term*, and the *constant term*, respectively. We will discuss noise soon enough. The sampling term depends on material choice and thickness. The constant term is what dominates at high energy, and it is governed by the detector layout and geometry: how many radiation or absorption lengths and how uniform it is, if there are cracks and dead (uninstrumented) material, etc. This term is reduced by inter-channel calibration. In the other end of the energy range, the noise term dominates, but its importance decreases the fastest with E .

¹ 0.2–0.5 mm instead of 2 mm

5.3 RESOLUTION: ENERGY AND GRANULARITY

The incident particle energy resolution of the ATLAS calorimeter, neglecting the noise term which (as we will see later) is subject to large variations depending on the LHC pile-up conditions, is shown in Table 4.

Calorimeter segment	Energy resolution σ_E/E
EMB	$\frac{10\%}{\sqrt{E}} \oplus 0.7\%$
EMEC	$\frac{10\%}{\sqrt{E}} \oplus 0.7\%$
HEC	$\frac{50\%}{\sqrt{E}} \oplus 3\%$
FCal	$\frac{100\%}{\sqrt{E}} \oplus 10\%$
Tile	$\frac{50\%}{\sqrt{E}} \oplus 3\%$

Table 4: Energy resolution in the ATLAS calorimeters.

The coverage and granularity of the calorimeters is detailed in Table 5. It shows that the cells grow larger farther from the IP. In Fig. 16, the coverage in both $|\eta|$ and material is represented visually in terms of number of absorption lengths of each calorimeter system.

CALORIMETRY

	EM calorimeter	
	Barrel (EMB)	End-cap (EMEC)
$ \eta $ coverage	0 – 1.4	1.4 – 3.2
Depth samples		
presampler	1	-
calorimeter	3	3
Granularity $\eta \times \varphi$		
presampler	0.025×0.1 ($ \eta < 0.8$)	-
	0.003×0.1 ($ \eta > 0.8$)	-
calorimeter	0.003×0.100	0.003×0.100 ($ \eta < 2.4$)
	0.025×0.025	0.025×0.025 ($ \eta < 2.4$)
	0.025×0.050	0.025×0.050 ($ \eta < 2.4$)
		0.050×0.050 ($ \eta > 2.4$)
Readout channels		
presampler	7800	1500
calorimeter	100000	62000
<hr/>		
	LAr hadronic end-cap (HEC)	
$ \eta $ coverage	1.5 – 2.2	
Depth samples	4	
Granularity $\eta \times \varphi$	0.1×0.1 ($ \eta < 2.4$)	
	0.2×0.2 ($ \eta > 2.4$)	
Readout channels	5600	
<hr/>		
	LAr forward calorimeter (FCal)	
$ \eta $ coverage	3.1 – 4.9	
Number of layers	3	
Granularity $\eta \times \varphi$	$\sim 0.15 \times 0.15$	
Readout channels	3500	
<hr/>		
	Tile hadronic calorimeter	
	Barrel	Extended barrel
$ \eta $ coverage	0 – 1.0	1.0 – 1.6
Depth samples	3	3
Granularity $\eta \times \varphi$	0.1×0.1	0.1×0.1
	0.2×0.1 (last sample)	0.2×0.1 (last sample)
Readout channels	5800	4100

Table 5: The $|\eta|$ coverage, typical granularity in η and φ and number of readout cells of the ATLAS calorimeters, per segment and layer [38].

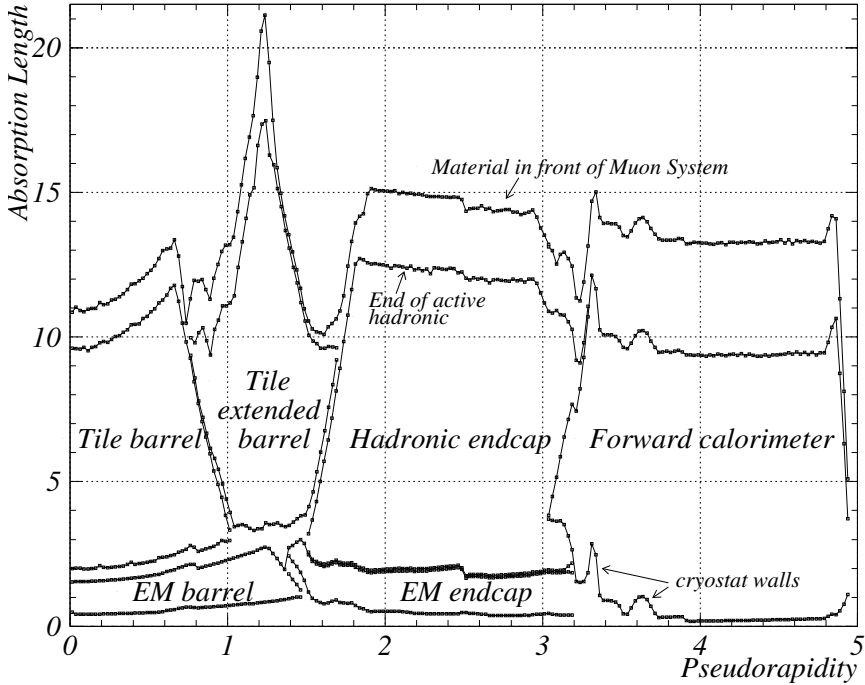


Figure 16: The $|\eta|$ coverage and number of absorption lengths of the ATLAS calorimeter system [38].

5.4 ENERGY MEASUREMENTS

The strength of the signal from a cell is a measure of the energy deposited in it. The conversion from ADC counts to signal current in μA , or charge in pC, is known from calibration, where a known charge is injected. The correspondence between signal current and energy is known from electron beam tests. After shaping, the amplitude of the pulse, which carries the energy information, is found through pulse fitting filtering algorithms. This will also give the timing of the pulse,

used both to assign the signal to a BCID and for data quality purposes. The amplitude of the un-amplified pulse at the triggered BCID is used to dynamically choose the amplifier gain² used for the channel at that given triggered BCID, avoiding saturation but optimising the signal-to-noise ratio.

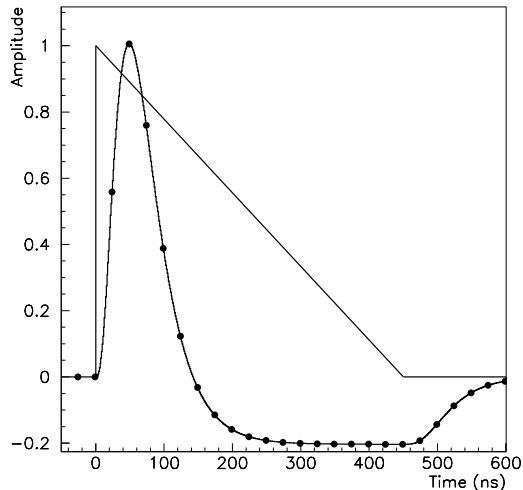


Figure 17: The amplitude of the LAr raw triangular pulse, drift current versus time, overlaid with the that from the bipolar shaping. 25 ns spaced sampling points, corresponding to BCIDs, are also shown. [38].

In LAr, the triangular pulses undergo bipolar shaping, as shown in Fig. 17, giving them a net integral of zero. The positive part is short and high, followed by a shallow negative tail of longer duration. It is clear from this figure that the baseline is not restored until after 600 ns (this example is from the EMB — the exact timing varies between LAr subdetectors but it is of the same order), which corresponds to 24 bunch crossings in 25 ns running. The limiting factor here is the drift

² There are discrete gain levels: low, medium, high for LAr; low and high for Tile.

time, which is not present in the Tile calorimeter, using a scintillating medium.

The pile-up sensitivity inherent in the slow readout of the LAr calorimeters is on average compensated for by the bipolar pulse shaping, where the zero integral on average cancels in-time and out-of-time contributions. The philosophy is that on average, there will be an equal rate of and signal amplitude from pile-up on top of the triggering signal as there is activity in the same cells outside triggered events. The comparatively short duration of the Tile readout allows it to be unipolar, with a pulse width of 50 ns. A pulse shape quality factor can be used to discriminate between signals affected and unaffected by pile-up from neighbouring BCIDs.

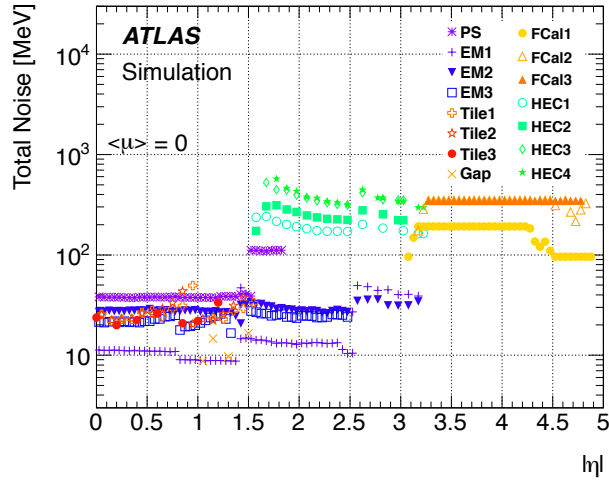
In general, the signal from an interacting high-energy particle is not contained within a single cell, as the showers spread both laterally and longitudinally in the calorimeter.

5.5 NOISE

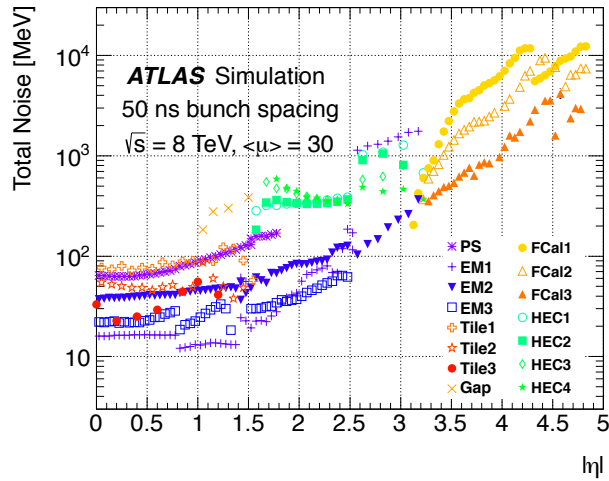
In every detector, there will be noise. Knowing the noise distribution is the first step towards setting up criteria for identifying signal. Figure 18 shows a simulation of the equivalent energy noise levels in the calorimeter under the conditions of 2012 data taking, with 4 TeV beam energy and 50 ns bunch spacing. Figure 18a shows the electronic noise, when there is no collision signal in the detector. There is a visible subdetector dependence, where the noise is the largest in the HEC and FCal detectors and smallest in the innermost layer of the EMB. The spread between detectors is also quite wide, about a factor 50. Figure 18b shows the noise when there is signal from multiple simultaneous proton collisions overlaid in the detectors. We see that the overlaid collisions contribute large fluctuations in the signal read out from the detector, as expected from having a large particle activity. Here a trend in η also emerges that is the most pronounced in the more forward region.



Note the logarithmic vertical scale



(a) On average no pp interactions



(b) 30 simultaneous pp interactions

Figure 18: The average equivalent energy cell noise shown for all the layers in the calorimeter subdetectors, for the case of (a) an average number of interactions of 0 and (b) an average number of 30 simultaneous interactions.

As mentioned in Chapter 3, the LHC operates in a mode where there are many simultaneous interactions, while most likely only one actually triggered the recording of the event. In that sense, the additional interactions become noise.³

5.6 TOPOCLUSTERING

The energy deposits in the calorimeter make *topoclusters* of contiguous cells, based on topological criteria, illustrated in Fig. 19. A topocluster is seeded by an energy deposit in a cell which is significantly above the noise level: in the so-called 420 scheme used, it needs to be at least larger than 4 standard deviations (σ) of the (electronic+pile-up) noise distribution. Once seeded, the topocluster grows by the addition of all neighbouring cells (in three dimensions) with a significance of at least 2σ . Finally all nearest neighbours are added (equivalent to a threshold of 0σ) [50].

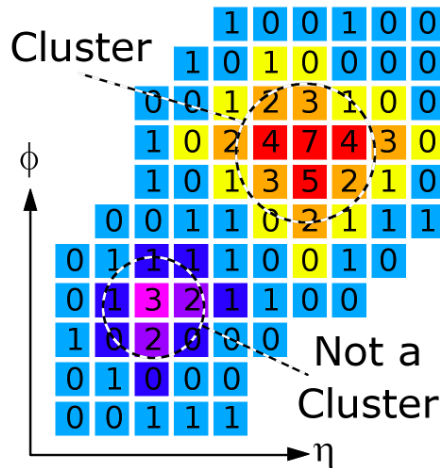


Figure 19: Illustration of the clustering algorithm, restricted to 2D [47].

³ The impact of overlaid interactions, which increases with integration time, is also well described by the established signal processing term *parallel noise*.

As also illustrated in Fig. 19, topoclustering introduces noise suppression, without setting a fixed threshold on the energy depositions.

5.7 ELECTROMAGNETIC AND HADRONIC SCALE

The calibrated calorimeter energy deposits clustered into topoclusters are used as input for identifying different physics objects. By this, we mean something that corresponds to measuring the interactions of theoretically defined objects, such as leptons, photons and other particles, with the detector. This is where the reconstruction of the processes in the event begins. But as mentioned before, the ATLAS hadronic calorimeters are non-compensating, meaning that the hadronic and electromagnetic energy scale — the measured energy of, say, a neutron and an electron carrying the same initial energy — will not be the same: the calorimeter *response* will be different. This can be compensated for on the topoclusters, using cluster shapes as a proxy for the shower evolution. Based on depth and location in the calorimeters, lateral shapes, etc., enough discrimination is achieved to assign clusters a hadronic or EM character, and calibrate them accordingly, using MC simulated and test-beam data.

There are two cluster calibration schemes used in ATLAS: the EM and the Local Cluster Weighting (LCW) schemes. For the first, the EM component of energy deposition is used, while in the LCW scheme, the lost energy in clusters classified as hadronic is compensated. In earlier iterations, even though the LCW energy scale was more correct compared to the true deposited energy — the energy response was better —, the energy *resolution* was worse. Since collision data and MC simulations are treated the same way, comparing data and MC on the EM scale will give an apples-to-apples comparison,⁴ even if

Remember: hadronic interactions also lead to EM depositions

⁴ This obviously relies on having a proper modelling of the particle composition in the shower! Thankfully, there exist decades worth of data on shower evolution and energy response in different materials and detectors, making the detector simulation remarkably robust. ATLAS has itself been contributing here by sharing test-beam and simulation results with the GEANT4 collaboration.

the absolute scale is slightly off.⁵ Many analyses have thus chosen to work on the EM scale. Recently, however, jet calibration methods taking differences in the hadronisation of quarks and gluons into account have improved the energy resolution of the LCW scale jets, making this a better choice in terms of response *and* equal in terms of resolution.

➤ In particular, the different ratio of charged to neutral components, is measured using charged particle tracks.

⁵ The scale can also be corrected back to the “true” particle level using the knowledge of the response from MC simulation.

JET FINDING

In order to reconstruct what we theoretically mean by a jet — a collimated spray of particles of partonic¹ origin — we need a means to localise this spray in our detector. The procedure is to look for localised higher density of energy deposits. In an event display, visualising energy deposits in $\eta - \varphi$ space, our brains have no problem identifying the general regions of interest. For the analysis of a very large number of events, visual inspection is not feasible (not to mention, probably a bit too arbitrary). What is currently used are criterion based algorithms. The requirements on these are that they should reproduce the calculable results in QCD; more precisely, they need to be *infra-red (IR) and collinear safe*. IR safety means that an additional soft emission cannot change the conclusions of the algorithm. Collinear safety means that a small-angle splitting cannot change the conclusions of the algorithm. Both processes are ubiquitous in QCD — ensuring these properties is a big deal! As an example, measuring the p_T spectrum of leading particles, or using a hard lower energy threshold in the jet finding algorithm tends to be IR-unsafe: soft emissions shift the spectrum and move jets below threshold. Similarly, a fixed “cone” size in $\eta - \varphi$ space tends to be collinear unsafe. There



This is a form of pattern recognition, that it would be interesting to pursue in for instance the realm of computer vision.

¹ τ leptons are heavy enough to also decay hadronically, producing jets. We will not consider these further as this process is much less likely than jets produced in QCD

is however a family of algorithms, the sequential recombination algorithms [51], that is nowadays completely dominant precisely because of its IR- and collinear safety. These algorithms will be briefly outlined in the following.

The reader is warned that we will now abandon thinking about jets purely from the perspective of a partonic hadron shower originating from a hard scatter. From here on, we use an instrumental definition of jets: a jet is the collection of objects which is the outcome of a jet finding algorithm. Where a connection to the more parton-oriented definition is needed, we will refer to *hard-scatter jets*.

6.1 SEQUENTIAL RECOMBINATION ALGORITHMS

For a pair of objects $i \neq j$ with transverse momenta p_{Ti} and p_{Tj} , a set of relative distance measures is defined as

$$d_{ij} = \min(p_{Ti}^{2p}, p_{Tj}^{2p}) \frac{\Delta R_{ij}^2}{R^2}, \quad (18)$$

$$d_{iB} = p_{Ti}^{2p}, \quad (19)$$

where R is the distance parameter of the algorithm, $\Delta R_{ij}^2 = (\Delta\eta_{ij})^2 + (\Delta\phi_{ij})^2$ and the choice of $p = -1, 0, 1$ defines the k_t [51, 52], Cambridge/Aachen [53, 54] and anti- k_t [55] algorithms, respectively. The squares ensure all distance measures are positive. The subscript B stands for Beam but should not really be interpreted in the proton beam sense.

The algorithm steps are:

1. for all the possible pairs (i, j) , compute d_{ij} and d_{iB}
2. find the minimum of these
3. if the minimum relative distance is a d_{ij} , combine the four-vectors of i and j into a proto-jet
4. if the minimum relative distance is a d_{iB} , the four-vector of i becomes a jet and is not considered further

5. repeat until there are no more objects j for which $d_{ij} < d_{iB}$.

Once this procedure is done, the event has been clustered into a set of jets, all having four-vectors, from which the jet p_T , direction, E etc can be calculated. In particular, using the relation

$$m^2 = E^2 - p^2, \quad (20)$$

the jet mass m can be calculated.

The choice of p as positive, negative or zero means that the object p_T enters as a numerator (k_t), denominator (anti- k_t), or not at all (Cambridge/Aachen). The distance parameter regulates how far from the jet axis clusters can be considered for addition: if $\Delta R_{ij} > R$, the ratio is larger than unity, which makes it less likely that $d_{ij} < d_{iB}$. Keep in mind that the proto-jet axis is recalculated for every addition, and that this will be dominated by the high- p_T region of the proto-jet. Depending on how much of the proto-jet p_T was added in the previous step, this axis may wander, meaning that the total angular reach of a jet algorithm may exceed R .

6.1.1 k_t

With $p = 1 > 0$, the smallest p_T object will be the starting point for jet finding. This also means, that the jet axis may start to migrate as higher p_T objects are added into the proto-jet.

6.1.2 *Cambridge/Aachen*

With $p = 0$, all p_T measures, in particular d_{iB} , are unity. Thus, finding the angular separation is all there is to this algorithm. Again, the jet axis is still sensitive to the location of the high- p_T depositions within the jet, and can migrate.

6.1.3 *Anti- k_t*

With $p = -1 < 0$, the highest p_T object will be the starting point for jet finding. This also means, that the jet axis is largely fixed from the

start, and the distance parameter R largely governs the angular reach of a jet. Since more objects will be added into the highest p_T proto-jet, clustering continues to add all possible constituents within R , before it continues to the highest p_T object outside this jet. Thus, in a dense environment, any locally hardest jet will have circular boundaries,² while the ones of lower- p_T jets close by will be crescent shaped.

6.2 JET CATCHMENT AREAS

Having thus defined a set of IR- and collinear safe algorithms, we proceed to the concept of the jet catchment area [56]. As pointed out in the original paper introducing the concept, a jet consists — at least theoretically — of point-like particles, making an area ill-defined.

The picture is the following: the jet area is the region in $\eta - \varphi$ space into which a very soft particle would need to fall in order to become clustered with that particular jet. Hence the “catchment” area. This region can be probed by placing *ghosts* of infinitesimal momentum placed at different points in $\eta - \varphi$ and noting to which jet they are clustered. With an IR safe algorithm, the jet finding isn’t affected by the addition of a ghost particle, or even by a larger number of them, as long as their momenta are infinitesimal. One can thus lay out a dense grid of ghosts in $\eta - \varphi$ without affecting the jet finding.

There are thus two imaginable cases for calculating the jet area: one where the jet areas are probed with a single ghost, and one where a dense grid of ghosts is laid out before jet finding starts, participating in the clustering on equal footing (apart from the very different p_T) with the four-momenta of energy depositions from the event. This gives rise to the notion of *passive* and *active* areas, which will be defined more precisely below.

² Exceptions exist, for instance where there are two objects within R that are of comparable p_T .

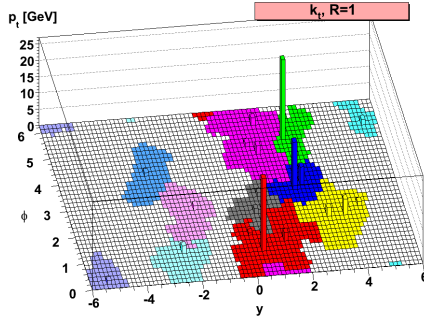
6.2.1 Active area

With an event producing a set of particles to be clustered into jets, and a specific set of ghosts $\{g_i\}$ with a density in $\eta - \varphi$ of ν_g , we can express the scalar area of jet j as

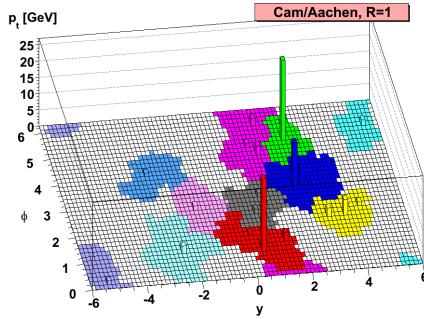
$$A_j = \frac{N_g}{\nu_g} \quad (21)$$

where N_g denotes the number of ghosts associated to the jet. Since the ghost distribution in $\eta - \varphi$ is random, the area boundaries may differ between different ghost sets. In its full definition, the area is taken as the limit when $\nu_g \rightarrow \infty$, averaged over a large number of ghost set iterations; in practice, $\mathcal{O}(1)$ iterations give precise enough results in relation to the computational cost. Allowing the ghosts to participate in the clustering means that they can cluster among themselves, making pure ghost jets with infinitesimal momentum.

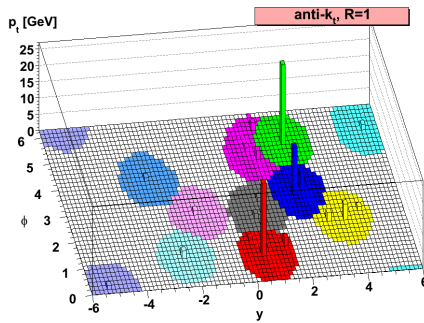
The features of the resulting *scalar* active areas for the three different algorithms described above are exemplified in Fig. 20. The different jets are drawn in different shaded regions, and the p_T of its constituents are reflected in the height of the bars, quantified on the vertical axis. The figure shows the irregular shapes of the k_t and Cambridge/Aachen jets, and the circular and crescent shaped anti- k_t jets. Furthermore it shows the low- p_T dominance in the k_t case (a) compared to the p_T agnostic Cambridge/Aachen (b): the highest p_T jets (red, green, dark blue) are almost invaded by low- p_T neighbours (magenta, grey) in the k_t case.



(a) k_t



(b) Cambridge/Aachen



(c) anti- k_t

Figure 20: The jet scalar active areas found in the same simulated event, clustered with (a) k_t , (b) Cambridge/Aachen and (c) anti- k_t . The vertical axis shows the jet p_T , and pure ghost jets are omitted for clarity. The same distance parameter $R = 1.0$ is used for all clustering algorithms. [55]

If one instead uses the ghost four-momenta $\{g_{\mu,i}\}$ one can define a *four-vector area* as

$$A_{\mu,j} = \frac{1}{v_g \langle g_t \rangle} \sum_{g_i \in j} g_{\mu,i}, \quad (22)$$

where $\langle g_t \rangle$ is the average ghost transverse momentum component, and again, the randomness of the ghost distribution is to be taken properly into account. The transverse component of $A_{\mu,j}$ tends to the scalar area A_j for small R .



Small R is $R \lesssim 0.4$.

6.2.2 Passive area: the Voronoi area

As we have seen, the k_t algorithm is very sensitive to soft radiation, and will cluster this first. Thus, when a single ghost is added, it will be associated to one of the particles making up a jet j before any of the pair-wise particle clustering happens. This means that for k_t , we can probe the passive area of each non-ghost jet *constituent* independently and add the constituent areas to make up the jet area. It also implies, that the computational cost can be reduced by assigning the geometrical construct of the *Voronoi cell*.

Defined in words, every point inside a constituent's Voronoi cell is closer to that constituent than to any other constituent in the event.³ The boundaries of the event's Voronoi cells thus indicate the transition points where a ghost would get clustered together with one constituent rather than another. For k_t , the distance parameter also enters in the shape of a radius, and the constituent's passive Voronoi area becomes the intersection of the two:

$$A_i^V = V_i \cap C_{i,R}, \quad (24)$$

³ Mathematically, the definition of a Voronoi cell V_k associated with point P_k is expressed through the points x in some space X as

$$V_k = \{x \in X | d(x, P_k) \leq d(x, P_j), \forall j \neq k\}, \quad (23)$$

where k, j are indices ordering the points to which we are assigning Voronoi cells. In our application, $P_{k,j}$ is a jet constituent while the x locations would be probed by a ghost.

where V_i is the Voronoi cell of constituent i and $C_{i,R}$ is the circle around it given by the distance parameter R . Then the jet Voronoi area is simply

$$A_j^V = \sum_{i \in j} A_i^V. \quad (25)$$

An illustration is given in Fig. 21.

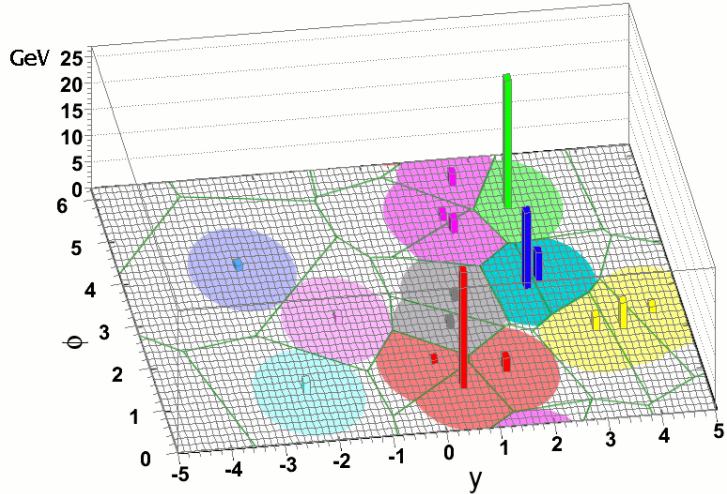


Figure 21: The jet Voronoi areas in the same simulated event as in Fig. 20, calculated using $R = 1$, indicated in shaded regions. The green lines are the boundaries of the Voronoi cells. The vertical axis shows the jet p_T . [56].

The great virtue of the Voronoi area is its much shorter computation time; in the limit of a sparse environment, it is however not a very precise approximation of the active area of a jet, as can be seen from comparing Fig. 20a to Fig. 21.

6.3 JETS IN ATLAS

ATLAS uses charged tracks or positive massless topoclusters at the EM or LCW scale as jet finding input, forming the jet constituents.

The jet clustering framework FASTJET [57] is used to find the jets and calculate their active area, using one set of ghosts.⁴ This is done for a range of *jet definitions* — combinations of jet algorithms and distance parameters — but the ones where baseline calibration is provided are anti- k_t jets with $R = 0.4, 0.6$.

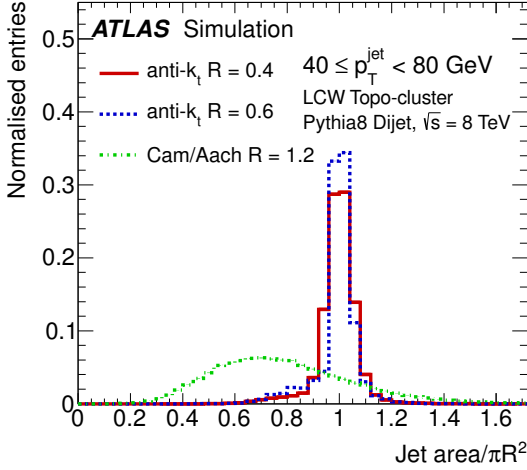


Figure 22: The area in units of πR^2 for anti- k_t jets with $R = 0.4, 0.6$ and Cambridge/Aachen jets with $R = 1.2$. The circular tendency of anti- k_t centres those distributions around $\mathbb{1}$, while the Cambridge/Aachen jets have a large spread.

Figure 22 shows the area distributions expressed in units of πR^2 for three jet definitions: two choices of R for anti- k_t , and one for Cambridge/Aachen. For circular jets, the distribution should be centred around $\mathbb{1}$. This is the case for anti- k_t , with a long tail to smaller areas from crescent-shaped jets. The irregular area for Cambridge/Aachen jets is seen here in terms of a very wide distribution.

Apart from making up pure track jets, individual tracks can also be matched to jets using a *ghost association* scheme [58]. Here the track

⁴ Computation time would scale at best linearly with number of iterations, while the resolution improves roughly with the square root of that number.

“infinitesimally” small:
 $p_T = 1 \text{ eV}$

momenta are temporarily set infinitesimally small, and the association of tracks to a jet is made using the same techniques as for active area calculation. This matching scheme has an advantage over cone-based association (“ ΔR ” matching from the jet axis) when the jet shape is non-circular. The matched tracks can be used for instance to improve jet calibration or selection and for flavour tagging.

6.3.1 Jet calibration

All experimental objects are composite, as they are reconstructed from a large number of signals. The energy calibration of an object is thus a bit more involved than the calibration of a single detector signal.

Since jets are complicated composite objects, jet calibration is a procedure involving a sequence of steps. It will only be briefly explained here, and the interested reader is referred to Ref. [59] and references therein. The result of the calibration is that the jet is brought to the *Jet Energy Scale* (JES).

The first step is the topocluster energy calibration mentioned in Sec. 5.7. Then jet finding results in a set of jets at the EM or LCW constituent energy scale. An origin correction makes the jets point back to the primary vertex rather than the detector origin. The jet four-vectors are then corrected for pile-up effects. This is a step where I have contributed much work, and it will be discussed in some depth in Chapter 7. After pile-up correction, a MC based energy scale correction is applied, which brings the jets to particle-level energy. Since MC modelling can’t be trusted to provide a perfect representation of data, this correction has been validated using *in-situ* techniques where the calibrated jet p_T is compared to the p_T of a balancing reference object. The reference objects can be photons, Z bosons, or other jets, and are selected using criteria ensuring that a p_T balance is indeed expected in these events. This step will affect both the energy and the direction of the jet, i.e., the full jet four-vector. Once the scale is corrected, a correction improving resolution is applied: it uses tracking to adjust for flavour dependent effects in the energy measurement. In addition, it corrects for energy leakage when a jet “punches through” the calorimeter and deposits energy in the muon spectrometer. This correction is based on the number of muon segments behind a calorimeter jet. In practice, punch-through is a

Remember the different response for charged and neutral hadrons

rare phenomenon, but it is enhanced for the highest energy jets, in the central regions of the calorimeter where the detector material is the thinnest in terms of radiation and absorption lengths. Finally, a residual η dependent correction, the η *intercalibration* [60], is applied to data only, using dijet balance to ensure a uniform energy response between different regions of the detector. The relative uncertainty associated with the jet calibration is summarised in Fig. 23.

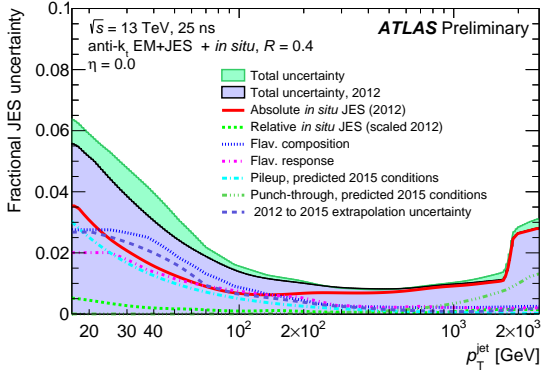
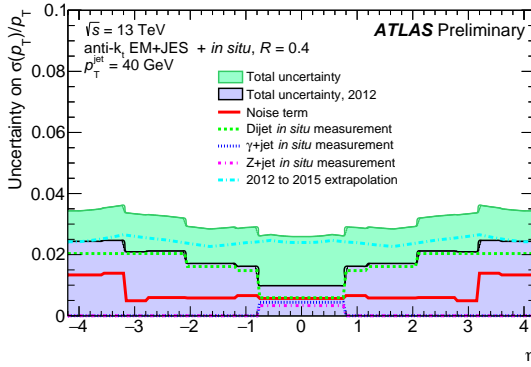
(a) JES uncertainty vs jet p_T (b) JES uncertainty vs jet η

Figure 23: The relative uncertainty on the jet energy scale shown as function of (a) jet p_T for central jets and (b) jet η for jets at $p_T = 40$ GeV [59].

The uncertainty has been derived using the aforementioned *in-situ* methods. As one would expect from the general properties of calorimeters, the relative uncertainty decreases with jet p_T , as seen in Fig. 23a. However, at ~ 2 TeV it rises sharply and becomes flat in p_T . The increased uncertainty is due to large statistical uncertainties in the *in-situ* methods. The uncertainty also varies with η , as shown in Fig. 23b. Note that the uncertainty shown here is for jets at $p_T = 40$ GeV, which has comparatively large relative uncertainty.

6.3.2 Jet cleaning

Once we have a set of calibrated jets, jet *cleaning* [61] is applied to ensure that “fake” jets originating from for instance beam-induced or cosmic ray backgrounds, or calorimeter noise bursts, are not included. The selection criteria are designed to capture these rather diverse signatures and are based on, among others, the fraction of the jet energy deposited in the HEC, calorimeter pulse quality factors, the fraction of EM energy, and the amount of negative energy in the cells of the jet.

While it is individual jets that are induced by non-collision sources, to avoid introducing a bias, cleaning is applied as a rejection of whole events. An event is discarded if any of the two highest p_T jets are deemed fake, or any other jet carrying more than 30% of the second highest p_T is. It was established that below this fraction, the impact from non-collision sources would not introduce changes in the ordering of jets.

PILE-UP IN JETS

The work described in this chapter is also partly documented in Refs. [8, 9]. It describes the adaptation of a pile-up subtraction technique for jets, proposed and validated in the absence of a detector [62], for use within ATLAS. The work was largely done during 2012, using simulated 7 and 8 TeV collisions, and the method is the new standard jet pile-up correction used in ATLAS since the end of that year.

7.1 PILE-UP OBSERVABLES

As described in Sec. 5.4, the calorimeter signal readout is longer than one bunch crossing. The shaped LAr signal is 450-600 ns long, corresponding to 18 – 24 bunch crossings at 25 ns spacing. It was concluded that this makes in particular the LAr calorimeter pulses sensitive not only to overlaid signal from other interactions in the same BCID, *in-time pile-up*, but from neighbouring bunch crossings as well, and in fact to activity in the fairly distant history, *out-of-time pile-up*.

Although the bipolar shaping is designed to on average cancel the in-time and out-of-time pile-up contributions to the signal, in reality there will be large fluctuations leading to imperfect cancellation. In order to quantify the impact, we introduce two quantities describing the

number of pile-up interactions in an event: the *number of reconstructed primary vertices* N_{PV} , and the *number of simultaneous inelastic collisions*, μ :

$$\mu = \frac{L_0 \sigma_{inelastic}}{n_c f_{rev}}, \quad (26)$$

Note the resemblance to Eqn. 15

where L_0 is an instantaneous luminosity, $\sigma_{inelastic}$ is the cross section for inelastic pp interactions, n_c is the number of colliding bunch pairs and $f_{rev} = 11.245$ kHz is the revolution frequency of the LHC. As we have seen, in practice instantaneous bunch crossing luminosity is not measured, but averaged over a lumiblock. We are thus restricted to using the average, $\langle \mu \rangle$. The actual number of interactions in an event follows a Poisson distribution with mean $\langle \mu \rangle$, measured for the corresponding lumiblock.

In contrast, N_{PV} is an event-by-event quality. A primary vertex is defined as a vertex reconstructed from at least two tracks with $p_T > 400$ MeV, consistent with the LHC beam spot. The hard-scatter primary vertex, the one considered to be associated to the interaction triggering the event, is defined as the primary vertex with the highest $\sum_{tracks} (p_T^2)$.

These two quantities are highly correlated, with the average relation in 2012 data of $N_{PV} \approx 0.5\mu$. But there are large fluctuations:

- the number of interactions is not known for the individual event, only $\langle \mu \rangle$ for the lumiblock
- even for a well-defined μ , there can be fluctuations in for instance the vertex reconstruction efficiency, leading to fluctuations in N_{PV} .

N_{PV} is a measure of the in-time pile-up contributions only, since the tracking detectors are fast and readout is completed before the next bunch crossing. On the other hand, $\langle \mu \rangle$ encompasses both: the number of interactions in the previous bunch crossing belongs to the same Poisson distribution as the number in the current one, with the same $\langle \mu \rangle$, and we can thus expect about the same level of pile-up in the

non-triggered bunch crossing as in the triggered one. Using both observables, they can be decorrelated to isolate the impact of in-time and out-of-time pile-up, by fixing one while letting the other vary.

7.1.1 Impact of pile-up on jets

The impact on jets from pile-up can be divided into three categories:

- response: energy is added to or subtracted from the measured hard-scatter jet energy,
- resolution: the jet energy measurement is smeared,
- multiplicity: additional jets from pile-up are reconstructed in the event.

This defines the measures we'll use in the following to quantify the impact of pile-up on jets:

- the slope of the jet p_T or mass response with respect to N_{PV} or $\langle\mu\rangle$: $\partial p_T/\partial N_{PV}$ and $\partial p_T/\partial\langle\mu\rangle$, and correspondingly for mass m ;
- the jet p_T or mass resolution expressed as the RMS of $p_T^{\text{reco}} - p_T^{\text{true}}$ or $m^{\text{reco}} - m^{\text{true}}$;
- the number of jets in an event above a certain p_T threshold.

The previous pile-up correction method in ATLAS used a parameterisation in N_{PV} and $\langle\mu\rangle$, derived from the dependence on these observed in MC, to correct for pile-up in jets. That method was an average correction, restoring the average jet response to be independent on pile-up. In the following we shall outline the current method, which measures the amount of pile-up on an event-by-event level, thus improving also the resolution in the presence of pile-up.

7.2 JET-AREA BASED CORRECTION

The current method implemented in ATLAS is based on the area concepts discussed in Sec. 6.2. The idea is, that the jet area is a

measure of how susceptible a given jet is to pile-up, as it reflects the extent in $\eta - \varphi$ space within which a soft particle would be associated to the jet. IR and collinear safety ensures that we can measure that susceptibility without worrying that the p_T spectrum and distribution in $\eta - \varphi$ of the pile-up would distort our identification of the jet boundaries. It is assumed here that pile-up is diffuse, soft radiation.

The other ingredient is measuring the pile-up p_T density in the given event. Consider an event with a few hard-scatter jets and some number of overlaid interactions, contributing diffuse radiation across the $\eta - \varphi$ cylinder of the detector. Once the event is clustered with a jet finding algorithm, this activity will be contained in a set of jets with a given p_T and area. These are used to calculate a median p_T density ρ :

$$\rho = \text{median} \left(\frac{p_T^j}{A_j} \right). \quad (27)$$

The median is taken to avoid a large influence from the hard-scatter jets, which will contribute a high-density tail to the distribution.

If for a given jet, the area is multiplied with the p_T density, one obtains a measure of how much of that jet's p_T was contributed by pile-up. The jet-area based correction amounts to precisely this subtraction from the jet four-vector. Note that the individual jet constituents remain the same: only the final four-vector is corrected.

7.2.1 The ρ calculation

Algorithm choices

There is no need for the clustering for the ρ calculation to return regular jets dominated by the hard scatter — on the contrary, it should be dominated by the low- p_T energy deposits from pile-up. The possibility to use the Voronoi area (introduced in Eqn. 24) makes k_t an attractive choice, and this is used for the ρ calculation.¹ A distance parameter

¹ Later, a so-called *grid method* has been implemented in FASTJET, which simply slices the event up in pieces of equal size, making the calculation of ρ even faster. This has not yet been implemented in ATLAS.

$R_{kt} = 0.3 - 0.4$ was found to be the optimal compromise between an increased sensitivity to the hard-scatter activity in the limit of few jets, and a large number of very low p_T jets making ρ tend to 0 in the limit of sparse events. For some studies, $R_{kt} = 0.3$ was used, but the final choice was $R_{kt} = 0.4$.

η range

Figure 24 shows the average ρ in simulated dijet events, calculated using a slice in η of width $\Delta\eta = 0.7$, sliding in steps of $\delta\eta = 0.1$ across the full η range of the ATLAS detector. Curves for different values of $\langle\mu\rangle$ are overlaid. There is a visible dependence on $\langle\mu\rangle$ in the central region, while the curves all drop outside $|\eta| = 2.0$. At higher η , ρ is mostly 0, largely independent on $\langle\mu\rangle$.

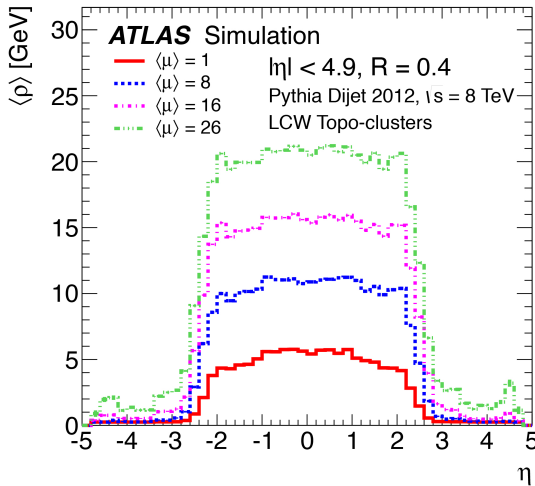


Figure 24: ρ calculated using in a window in η of width $\Delta\eta = 0.7$, sliding in steps of $\delta\eta = 0.1$, shown as function of the η of the midpoint of the window. Curves for different values of $\langle\mu\rangle$ are shown.

As we shall see, this behaviour is not caused by an absence of pile-up in the forward region. Instead, it is a matter of granularity.

As described in Chapter 5, the ATLAS calorimeters are far from uniform in η : gaps or other transition points are largely washed out in this sliding window measurement, but the effect of granularity is not. To understand it, we need to consider the noise conditions for topoclustering. In Sec. 5.6, we saw that a signal equivalent to 4σ of the noise distribution is needed to seed a cluster. This condition is the same across all calorimeters, even if the absolute size in MeV of 4σ varies, as shown in Fig. 18b. But, the probability of registering at least one instance of a large deviation is smaller with few samplings of a given distribution, than with a large number. The fine granularity of the central calorimeters corresponds to a large number of samples, while the segmentation of the forward region is much coarser (cf. Table 5). Calculating optimistically, there are 16 times fewer cells per unit area in $\eta - \phi$ in the forward region than in the central.

☞
 An analogy: compare the probability of finding at least one crying baby at home compared to in a nursery school (thanks Ariel!).

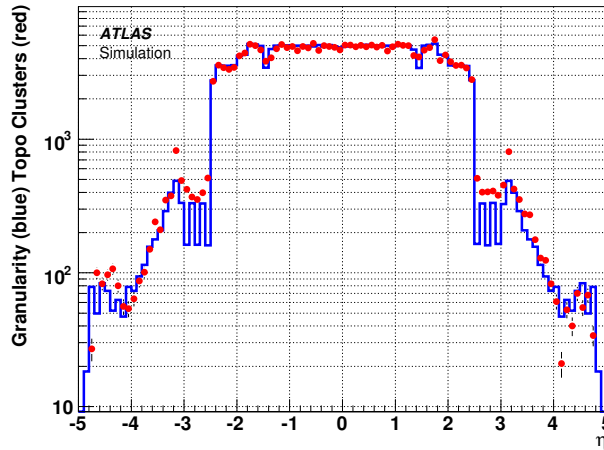


Figure 25: The profile in η of the calorimeter cell granularity, overlaid with the cluster distribution. A close correspondence is seen.

This reasoning is confirmed in Fig. 25, which shows an overlay of the granularity and cluster distributions in η . The shapes of the two curves follow each other closely, as well as the η profile of ρ in Fig. 24.

In conclusion: there is very little information to be gained from measuring ρ beyond $|\eta| = 2.0$; rather, there is a risk of diluting the information by measuring mostly empty regions except for when there is hard-scatter activity seeding clusters. The range used for the ρ calculation is thus the entire event within $-2.0 \leq \eta \leq 2.0$.

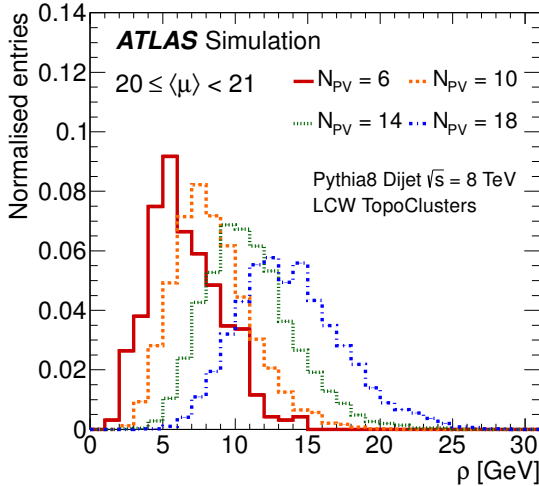


Figure 26: ρ for different N_{PV} , at fixed $\langle \mu \rangle$. The figure shows the fluctuations in the pile-up density captured by ρ but not fully by the N_{PV} and $\langle \mu \rangle$ variables.

Figure 26 shows example distributions of ρ thus obtained, for different N_{PV} at a fixed $\langle \mu \rangle$. It is clear that even for a given N_{PV} and $\langle \mu \rangle$, there are large fluctuations in the pile-up activity, which are captured in the ρ calculation.

7.3 METHOD PERFORMANCE

The following section outlines the assessment of how well jets can be corrected for pile-up using the jet-area based method. Even if its event-by-event character includes event-level fluctuations, the only local

fluctuations taken into account are those reflected in the individual jet area. This section will describe both the properties of ρ and the impact of the correction on several observables, keeping in mind the main effects listed in Sec. 7.1.1.

7.3.1 Response

Using the four-vector area rather than the scalar area, the full jet four-vector can be corrected. This means that not only the jet p_T but also the mass is affected in the correction. The impact on these two variables will be addressed in turn.

p_T response

Most figures in this section are based on graphs like the one shown in Fig. 27. It shows the dependence of a jet quantity ($\langle p_T^{\text{reco}} - p_T^{\text{true}} \rangle$) on a pile-up measure (N_{PV}), before and after the $\rho \cdot A$ correction, in some region of phase space (here, a p_T and $|\eta|$ range). It also shows a linear fit to the trend, which captures the dependence very well.

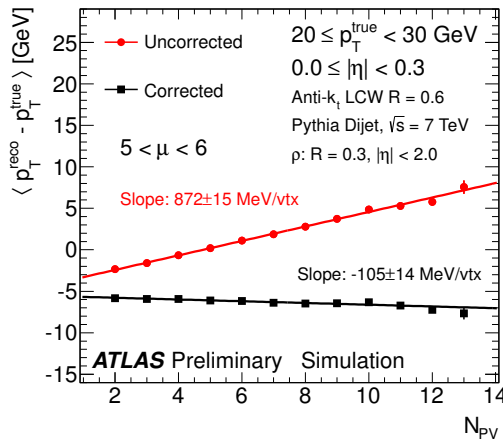


Figure 27: $p_T^{\text{reco}} - p_T^{\text{true}}$ vs N_{PV} for a fixed $\langle \mu \rangle$ representative for 2011 data taking, before and after $\rho \cdot A$ subtraction.

7.3 METHOD PERFORMANCE

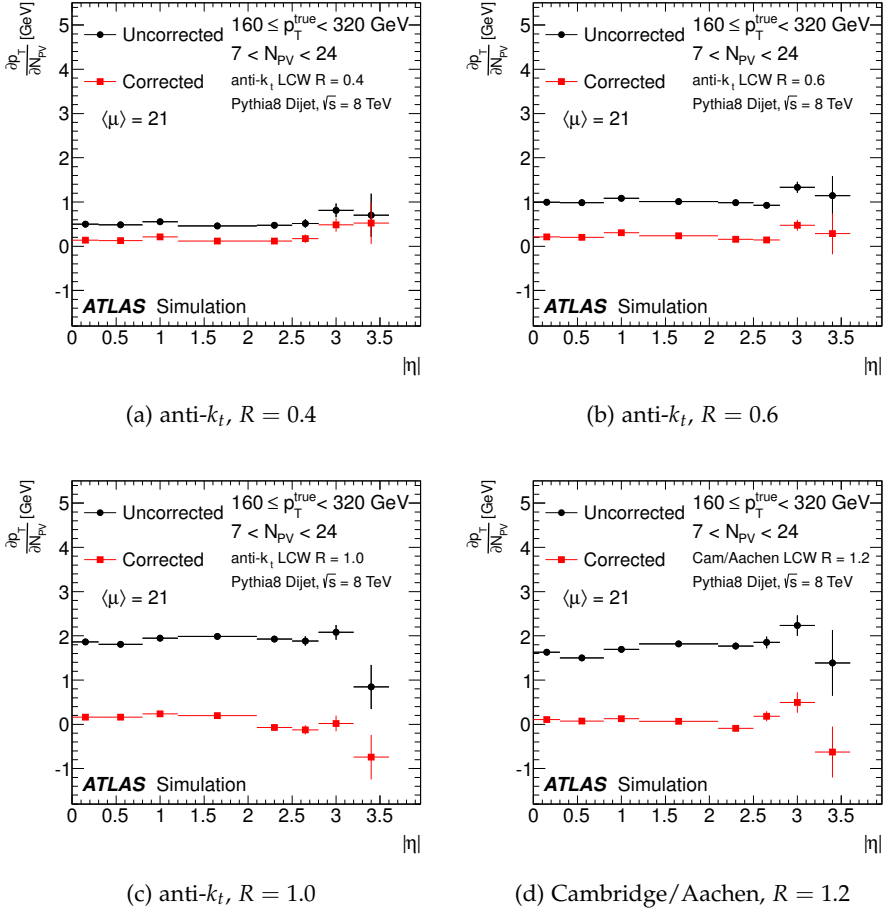


Figure 28: The dependence of jet p_T on N_{PV} as function of $|\eta|$, before and after $\rho \cdot A$ subtraction for jets clustered with (a) anti- k_t , $R = 0.4$, (b) anti- k_t , $R = 0.6$, (c) anti- k_t , $R = 1.0$, (d) Cambridge/Aachen, $R = 1.2$.

Figure 28 is based on this type of graph, and the subfigures show the behaviour in $|\eta|$ for four different jet definitions, keeping the p_T range fixed. The y -axis shows the slopes of the linear fits of $p_T^{\text{reco}} - p_T^{\text{true}}$

vs N_{PV} . $\langle\mu\rangle$ is kept fixed at its average value for 2012 data taking to isolate the impact of in-time pile-up.

The uncorrected slopes, in black, depend strongly on the jet area, which is one of the assumptions of the method. As shown earlier in Fig. 22, there is no simple πR^2 behaviour for Cambridge/Aachen jets. The increased R doesn't automatically give a larger slope in Fig. 28d. The corrected slopes, in red, show no area dependence. There is a small residual slope of $\mathcal{O}(100)$ MeV/vertex, of similar size for all jet definitions, and some features in η are seen. Most strikingly, the shape in $|\eta|$ before and after correction are the same: the correction merely introduces a downward shift. This is explained by ρ and A both being independent on jet η .

Here we can make the observation that in the presence of a jet, there is indeed pile-up in the forward region, even if the cluster multiplicity there is mostly independent on $\langle\mu\rangle$. This is explained by the hard-scatter jet seeding the clusters. The in-time pile-up thus adds energy to clusters that would already have been there. We also see that the η dependence of the in-time pile-up is moderate.

Turning to the dependence on out-of-time pile-up, the equivalent $|\eta|$ dependence figures are shown for three jet definitions in Fig. 29. N_{PV} is kept fixed at its average for 2012 data taking to isolate the dependence on out-of-time pile-up. Before correction, there is only a small positive slope in the central region, and it quickly drops off at higher $|\eta|$. After correction, the p_T dependence has in most cases become non-zero and negative. This means that a quantity with positive dependence on out-of-time pile-up ($\rho \cdot A$) is subtracted from a quantity with no or negative dependence. As before, there is no η dependence in ρ , so the correction merely introduces a shift, preserving the shape in $|\eta|$. Figures 29a–29b show $R = 0.4$ anti- k_t jets at $30 \leq p_T < 40$ GeV and $100 \leq p_T < 120$ GeV, respectively. Comparing these two, there is a clear p_T dependence in the uncorrected (black) curves: both an offset across all $|\eta|$, and a quicker drop-off at higher $|\eta|$ for higher p_T . Figures 29c–29d shows $R = 0.6$ anti- k_t jets in the same two intervals. Comparing the two R choices for the same p_T range, there is not much area dependence of the out-of-time pile-up impact at high $|\eta|$, while there is a little in the central region. The correction of course depends

•
The area of a circle with radius $R = 0.4$ is half as large as with $R = 0.6$.

strongly on area, making the shift in the corrected points larger for $R = 0.6$.

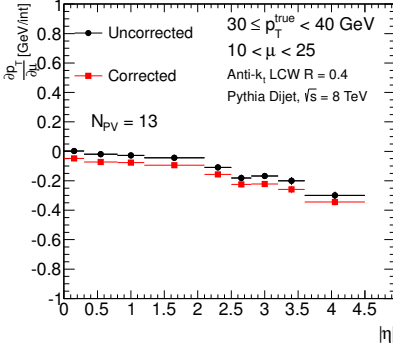
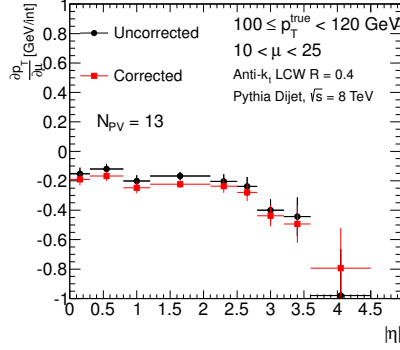
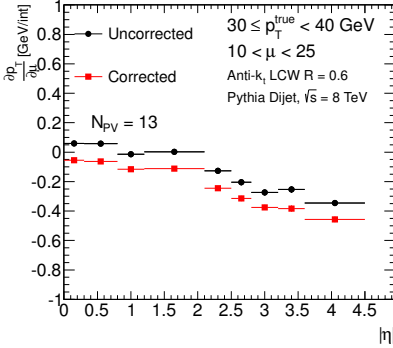
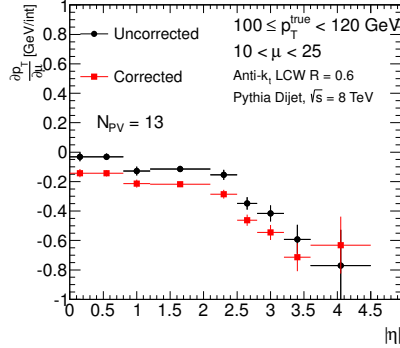
(a) anti- k_t , $R = 0.4$, low p_T (b) anti- k_t , $R = 0.4$, high p_T (c) anti- k_t , $R = 0.6$, low p_T (d) anti- k_t , $R = 0.6$, high p_T

Figure 29: $\langle \mu \rangle$ dependence of jet p_T vs $|\eta|$, before and after $\rho \cdot A$ subtraction for (a) anti- k_t $R = 0.4$ jets with $30 \leq p_T^{\text{true}} < 40$ GeV, (b) anti- k_t $R = 0.4$, $100 \leq p_T^{\text{true}} < 120$ GeV, and (c), (d) anti- k_t $R = 0.6$ jets in the same p_T intervals. The slopes before correction depend strongly on jet p_T , but only in the central region, and weakly, on the jet area.

The p_T dependence of the impact of both in-time (left) and out-of-time (right) pile-up is shown in Fig. 30, for two choices of $|\eta|$: very central (top) and more forward (bottom). The dependence is positive in N_{PV} and mostly negative in $\langle\mu\rangle$, and more pronounced at higher $|\eta|$.

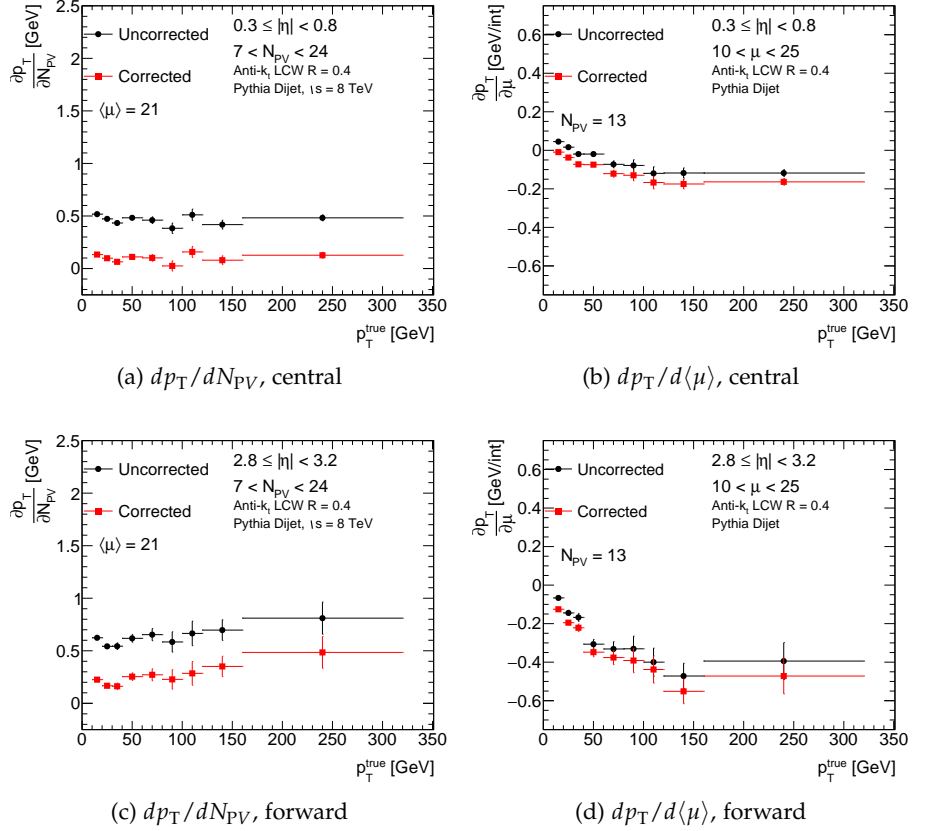
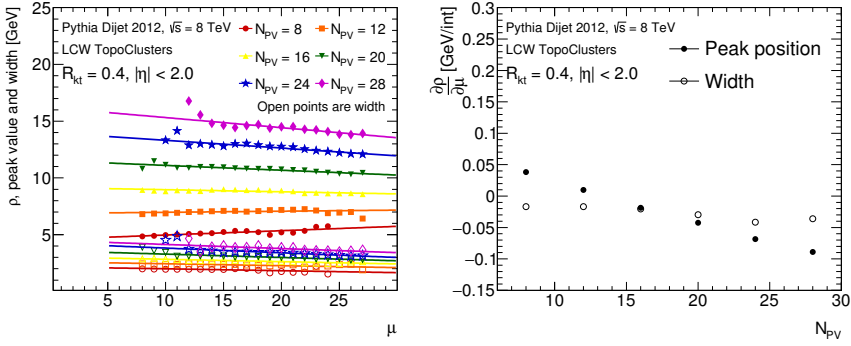


Figure 30: The dependence of p_T on (a),(c) N_{PV} and (b),(d) $\langle\mu\rangle$, as function of p_T , before and after $\rho \cdot A$ subtraction, for jets clustered with anti- k_t , $R = 0.4$. The top row shows central $|\eta|$ and the bottom more forward.

The key to understanding these features is the interplay of granularity, overlap, the LAr bipolar pulse shaping and topoclustering. Looking at ρ is instructive; in particular, its dependence on the in-time and out-of-time cluster occupancy. Figure 31a shows the mean and width of fits to the peak of ρ distributions like those shown in Fig. 26, while Fig. 31b in turn summarises the slopes vs $\langle\mu\rangle$ in Fig. 31a as function of N_{PV} . The fitted distributions have been binned in $\langle\mu\rangle$ and the true N_{PV} , the number of primary vertices from the generator truth record rather than after reconstruction. This number gives a better account of the in-time occupancy in the events than the reconstructed N_{PV} , since the vertex reconstruction efficiency is often less than unity, and non-linear with pile-up activity, as shown in Fig. 32.



(a) Peaks and widths of ρ binned in $\langle\mu\rangle$, vs N_{PV}

(b) Slopes of fits vs $\langle\mu\rangle$

Figure 31: Mean and width of Gaussian fits to the peak of distributions like in Fig. 26, but using the true N_{PV} . (a) Linear fits to the evolution in $\langle\mu\rangle$ for a given N_{PV} . (b) The slope vs N_{PV} of the linear fits in (a).

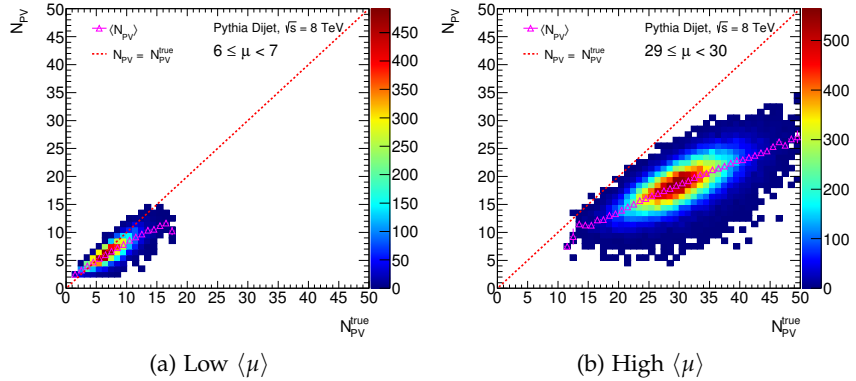


Figure 32: The relationship between the number of reconstructed and true primary vertices, for two regimes of $\langle \mu \rangle$. The reconstruction efficiency is less than unity, and decreases with N_{PV}^{true} .

ρ is calculated from positive clusters in the central region, where there is high granularity and generally small overlap between the clusters. Figure 31 shows that when there is small in-time occupancy, ρ has a positive dependence on $\langle \mu \rangle$ — meaning, on out-of-time pile-up. This must then come from energy deposited in the very neighbouring bunch crossings, where the LAr pulse shaping produces positive energy contributions. As the in-time occupancy increases, the slope with $\langle \mu \rangle$ becomes smaller and even negative: energy is being *subtracted* by the out-of-time pile-up. Now, a higher in-time occupancy translates to larger overlap between out-of-time pile-up and the in-time pile-up clusters included in the ρ calculation. We thus see that when the overlap increases, the net effect is energy subtraction. The negative energy comes from the negative tail in LAr, which is much longer than the positive part. Overlap with the negative-energy part is thus more probable. In turn, this means that the positive slope in the low-occupancy case *cannot* come from overlap — this causes an overall subtraction of energy — so it must come from isolated positive out-of-time clusters.

To summarise: when an energy deposition overlaps with out-of-time pile-up, this leads to energy subtraction. Out-of-time pile-up can contribute positive energy if there is enough room for it to make isolated positive clusters. Given the η dependence of the calorimeter granularity, this immediately introduces an η dependence in the impact of out-of-time pile-up. In the central region, it will often be positive. In the forward region, it will only be seen if there is an overlapping seeding positive energy contribution, and as an energy subtraction.

Mapping this to jets, there is in the central region often enough room to allow for non-overlapping out-of-time clusters, especially for large distance parameters. This gives a non-negative or even positive dependence on $\langle\mu\rangle$: cf. Fig. 29a and (c). Comparing these two, which are the same events clustered with different distance parameters, we see that the negative dependence comes from the core of the jet (making up a larger fraction of the area of narrower jets): there is a positive dependence in the central region only for the larger jets. In the forward region, we have seen that the large cells make the cluster occupancy outside jets mostly zero, and only the overlaps contribute, making the jet out-of-time pile-up dependence negative. Here there is no strong area dependence, since negative clusters are not included in the jet clustering. The area dependence of the positive slope with in-time pile-up in the forward region saturates for larger R , as shown for the full $|\eta|$ range in Fig. 33. For $R = 1.0$, the positive slope is reduced at higher $|\eta|$. This must then mean that the area dependence for $R = 0.4 - 0.6$ in this region comes from the hard-scatter jet radiation seeding clusters, while as the area increases even more, the pile-up contribution doesn't, as in-time pile-up only rarely contributes additional clusters and mostly contributes positive energy on the fringes of seeded clusters.

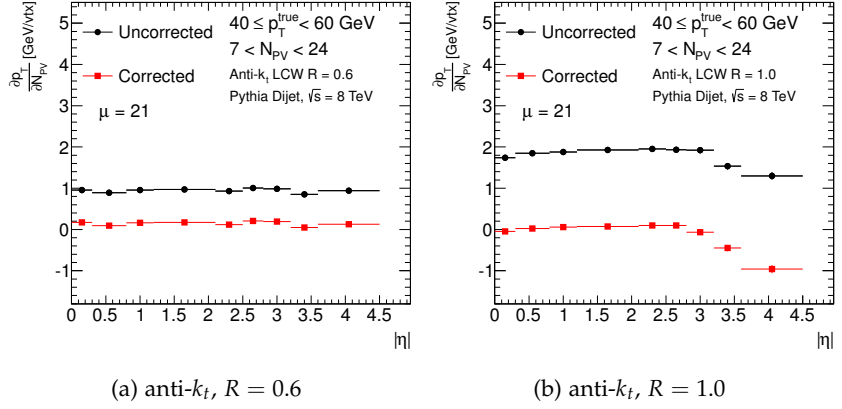


Figure 33: The dependence of p_T on N_{PV} , as function of $|\eta|$ before and after $\rho \cdot A$ subtraction for jets at $p_T^{\text{true}} = 40 - 60$ GeV, clustered with anti- k_t using (a) $R = 0.6$ and (b) $R = 1.0$. The slopes before correction depend strongly on jet area in the central region, but only weakly in the forward region.

In fact, Fig. 33 can raise a question mark as to the validity of the anti- k_t area as a measure of the catchment area of the jet in the coarse granularity environment of the forward region, at least in the limit of larger R . We will return to this later.

Figure 34 shows the distribution of negative and positive clusters in the vicinity of the leading jet, for different $|\eta|$, p_T^{lead} and $\langle \mu \rangle$. First of all, the positive cluster distribution gets narrower at higher p_T and $|\eta|$, making the jet increasingly dominated by the core. This explains the out-of-time pile-up dependence. It is also clear that on the periphery, the cluster density grows with $\langle \mu \rangle$, while at the core it is 0 in the forward region, and small in the central. This is of course inherent in the selection, where $dR = 0$ means that we are on the jet axis, and there is no room for negative clusters since the jet is built from positive clusters, where the jet axis dominated by the highest p_T depositions.

Leading: carries the highest p_T

7.3 METHOD PERFORMANCE

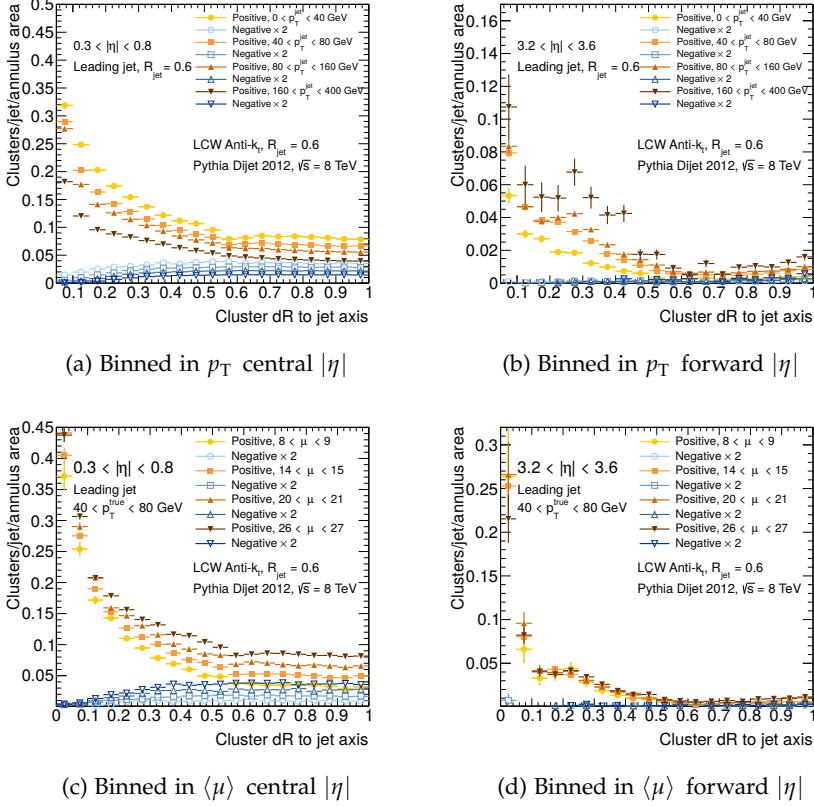


Figure 34: The distribution of positive and negative clusters in with respect to the leading jet axis, for different p_T^{lead} , $|\eta|$ and $\langle\mu\rangle$. (a) Jet axis in the central and (b) forward detector, for different p_T^{lead} . (c) Jet axis in the central and (d) forward detector, for different $\langle\mu\rangle$.

The residual in-time dependence after correction reflects the different sensitivity of ρ and jets, coming from the core (independent on area). The over-correction with respect to out-of-time dependence does too: overall it's a small over-correction on top of a large initial negative dependence. Since ρ reacts differently to out-of-time pile-up than jets do, this dependence needs to be dealt with outside the

method, and an additional residual correction is used, which uses a parameterisation in N_{PV} and $\langle\mu\rangle$, derived from MC. This is the same method as the one previously used in ATLAS, with the difference that the parameterised correction is smaller after $\rho \cdot A$ correction. It is substantial only in the forward region, where the out-of-time dependence is large. The performance of the residual correction is exemplified in Fig. 35, showing that the dependence of jet p_T on both N_{PV} and $\langle\mu\rangle$ is removed.

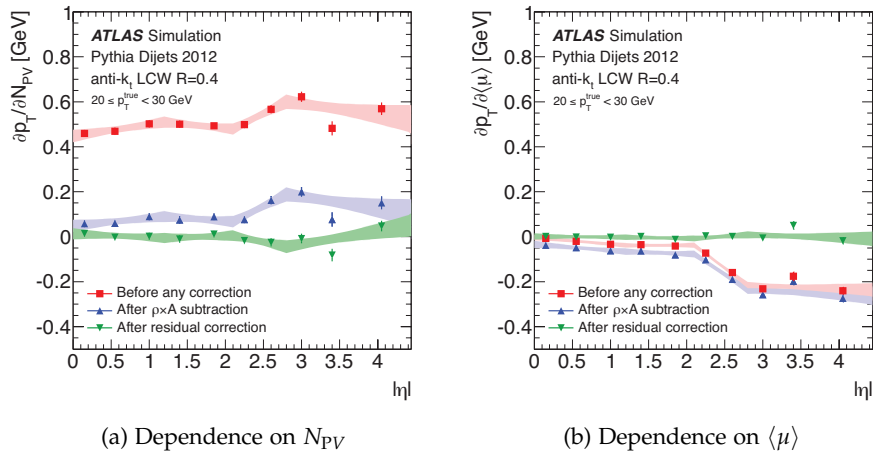


Figure 35: The dependence of p_T on (a) N_{PV} and (b) $\langle\mu\rangle$, as function of $|\eta|$, before and after $\rho \cdot A$ subtraction, for jets clustered with anti- k_t , $R = 0.4$. A residual correction removing the remaining dependence after $\rho \cdot A$ correction is also shown.

Correcting a dependence of p_T on p_T itself gets less accurate in data, where only the biased p_T is known.

The p_T dependence of the pile-up sensitivity is well described by a logarithmic fit, with positive dependence on N_{PV} and negative on $\langle\mu\rangle$. This is however not taken into account in the residual correction, but taken as a systematic uncertainty of the method, contributing to the total JES uncertainty. Apart from uncertainties on N_{PV} and $\langle\mu\rangle$, which

enter in the residual correction, a topology uncertainty is included to take bias in ρ from hard jet activity² into account.

Mass response

For a given p_T , jet mass m increases with the amount of wide-angle radiation. With respect to pile-up, the jet mass is predominantly sensitive to the added clusters from in-time pile-up; in fact it is largely insensitive to out-of-time pile-up. For mass in particular, the area plays a large role. Typical slopes of p_T with N_{PV} are shown in Fig. 36. There is a factor 2 smaller slope in m than in p_T , but it scales with area as given by the two R choices, as before.

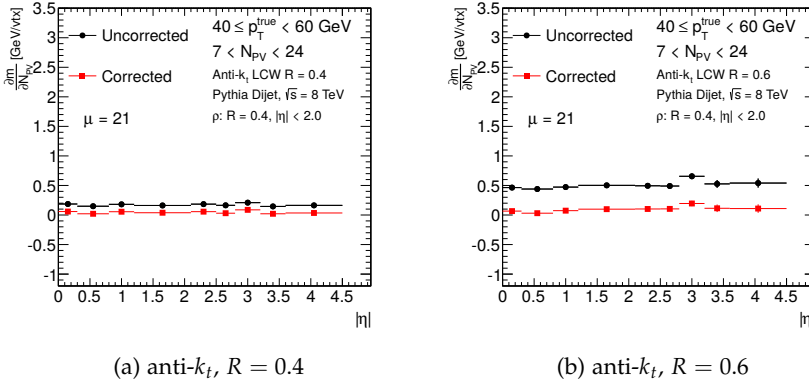


Figure 36: Dependence on N_{PV} of the jet mass m , shown vs $|\eta|$ for anti- k_t jets in the range $40 \leq p_T^{\text{true}} < 60$ GeV, with (a) $R = 0.4$ and (b) $R = 0.6$.

² For instance, a $t\bar{t}$ event typically has more high- p_T jets than a $Z \rightarrow \mu\mu$ event.

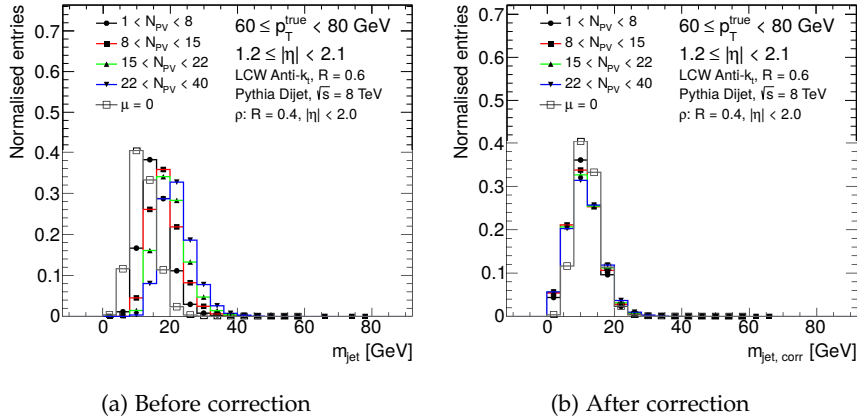


Figure 37: Example distributions of m_{jet} for different N_{PV} , before (a) and after (b) correction of the jet four-vector.

The impact of in-time pile-up on the mass distribution is shown in Fig. 37. We see in this and the previous figure that the mass of QCD jets can be made independent on pile-up. However, this quantity is foremost interesting as a background in studies of jets stemming from the decay of a massive object, such as a top quark (t) or W decay. This was briefly studied using a simulation of fully-hadronic decays of the suggested beyond the SM particle Z' , as $Z' \rightarrow t\bar{t}, t \rightarrow Wb, W \rightarrow q\bar{q}$. Depending on the boost, governed by $m_{Z'}$, and the R used for clustering, this can produce a combination of t -jets, or a W - and a b -jet, or two light quark jets and a b -jet. Here, $m_{Z'} = 1$ TeV. The identification of hadronically decaying top hinges on reconstructing the t mass from the resulting jets. Here pile-up smearing will reduce the reconstruction efficiency. Figure 38 shows the impact of pile-up on the jet mass distributions, and the result after correction. Two peaks are seen, from W and t jets, respectively.³ The two peaks are fitted

A Z' being a heavy Z ,
decaying to the same
SM particles

³ Since pile-up correction is done before the rest of the calibration steps, it was derived on uncalibrated jets. Since the uncalibrated response is less than unity, the jet masses are not expected to completely reach the tabulated particle masses of Table 2.

with Gaussians, to loosely identify the 'top' and 'W' jet masses. The evolution of the location of the mean with N_{PV} is shown in Fig. 38c. It shows that an initial dependence on N_{PV} of the jet mass is removed by the correction.

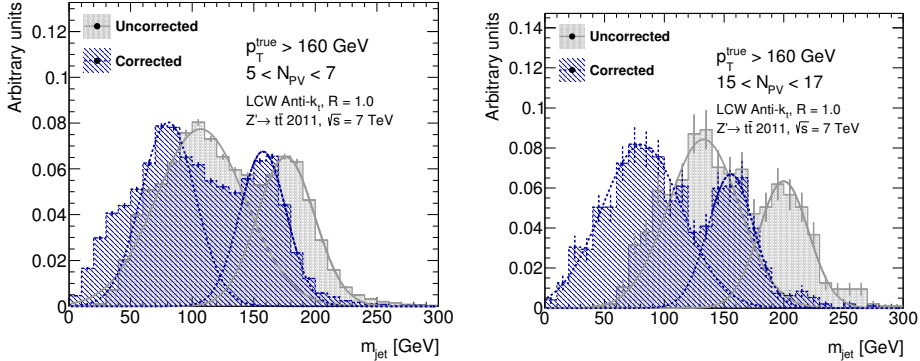
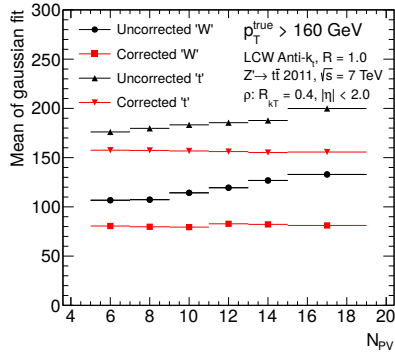
(a) Distribution, low N_{PV} (b) Distribution, high N_{PV} (c) Mean vs N_{PV}

Figure 38: The distributions of m_{jet} in hadronic top decays, for (a) low and (b) high N_{PV} , before and after correction. (c) The evolution vs N_{PV} of the mean of the Gaussian fits in the top row.

7.3.2 Resolution

 p_T resolution

The larger sensitivity to fluctuations in pile-up activity in ρ compared to N_{PV} and $\langle\mu\rangle$ manifests itself as a better recovery of the jet p_T resolution compared to the previous method. This is demonstrated in Fig. 39. However, quite some dependence on pile-up remains, which is explained by local fluctuations in the pile-up environment in the vicinity of the jet, which are not reflected by ρ .

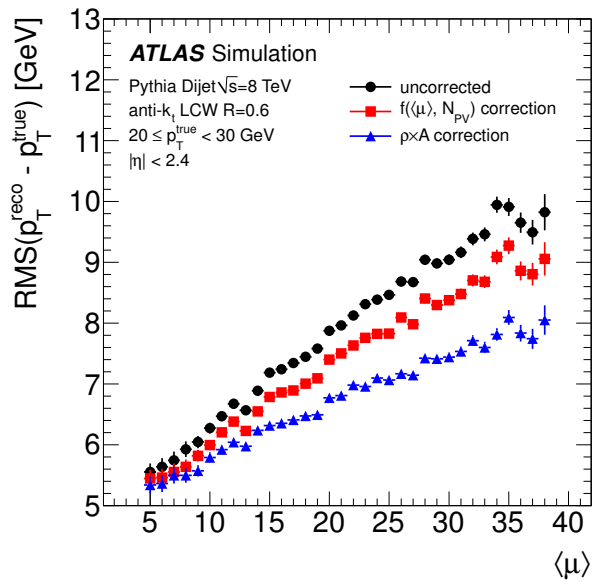


Figure 39: The dependence on $\langle\mu\rangle$ of the p_T resolution, before any correction, with the previous parameterisation method $f(\langle\mu\rangle, N_{PV})$ and after $\rho \cdot A$ subtraction.

Comparing the two p_T regions shown in Fig. 40, we see that the inherent p_T resolution is as expected p_T dependent, but that the pile-up correction reduces the smearing from pile-up equally well in both cases. The detector features in $|\eta|$ are also seen here. It is clear that

the pile-up activity fluctuations captured by the centrally measured ρ also hold for the forward region.

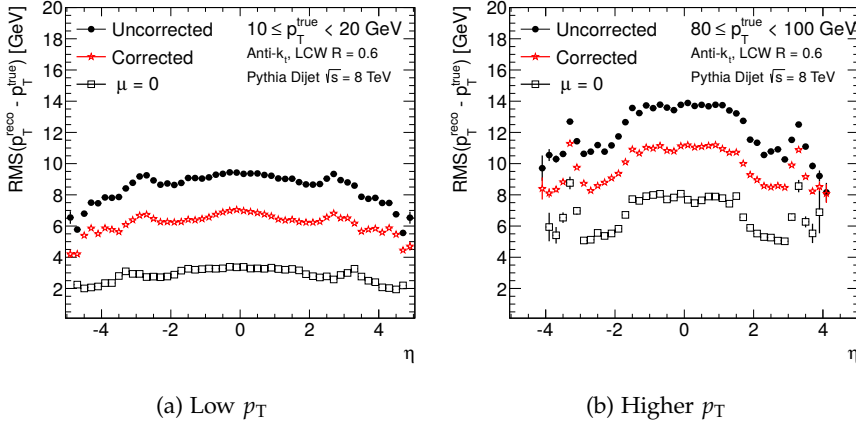


Figure 40: p_T resolution vs η , before and after $\rho \cdot A$ subtraction, compared to the resolution in absence of pile-up ($\langle\mu\rangle = 0$), for (a) $10 \leq p_T^{\text{true}} < 20$ GeV and (b) $80 \leq p_T^{\text{true}} < 100$ GeV.

Mass resolution

Just as for p_T , the mass resolution is deteriorated in the presence of pile-up, and partly restored by the correction. This is shown in Fig. 41. The improvement is the largest for low- p_T jets. Again an approximate factor two is seen between the pile-up impact on jet mass and p_T .

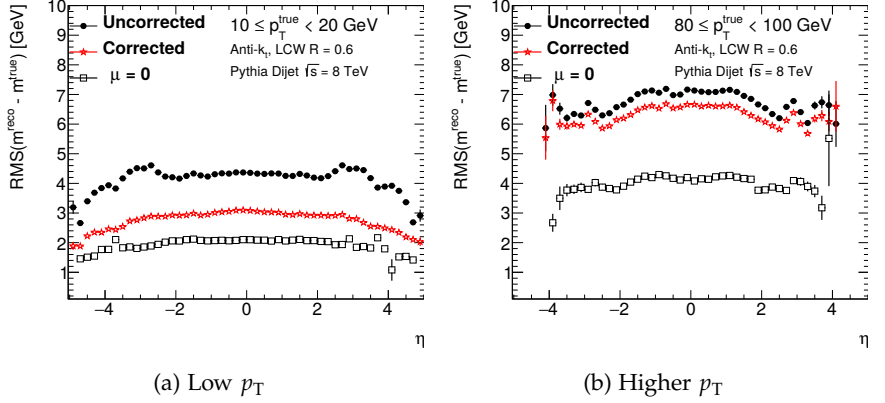


Figure 41: Mass resolution vs η , before and after $\rho \cdot A$ subtraction, compared to the resolution in absence of pile-up ($\langle \mu \rangle = 0$), for (a) $10 \leq p_T^{\text{true}} < 20$ GeV and (b) $80 \leq p_T^{\text{true}} < 100$ GeV.

From the shape of the corrected m distributions in Fig. 37b, a slight overcorrection can be seen. In fact, there is a fraction of jets, excluded from the above figures, getting negative m^2 after correction. This is flagged as negative m from a setting in FASTJET:

$$\sqrt{m^2} = \begin{cases} -\sqrt{|m^2|}, & m^2 < 0 \\ \sqrt{m^2}, & m^2 \geq 0 \end{cases} \quad (28)$$

where $m^2 < 0 \Rightarrow E^2 < p^2$. Closer studies revealed a few differences between the jets with $m^2 < 0$ and $m^2 \geq 0$. Firstly, jets at the same p_T^{true} and truth jet mass, similar ρ , N_{PV} and $|\eta|$ were compared. For jets getting the same reduction in p_T , the ones with negative corrected mass showed about a factor 2 larger mass correction than the positive mass ones. This points to a different topology in the ghosted four-vector area of the jets with negative corrected mass. Secondly, the number of constituent clusters per unit area has a different dependence on N_{PV} as function of $|\eta|$ in the negative- and positive-corrected mass jets: the number decreases with $|\eta|$ as expected for the well-behaved

jets, but shows very little $|\eta|$ dependence in the negative-mass ones. Thirdly, the p_T fraction carried by the two highest- p_T clusters in the jet is smaller in the jets with negative corrected masses than in the others. This is illustrated in Fig. 42.

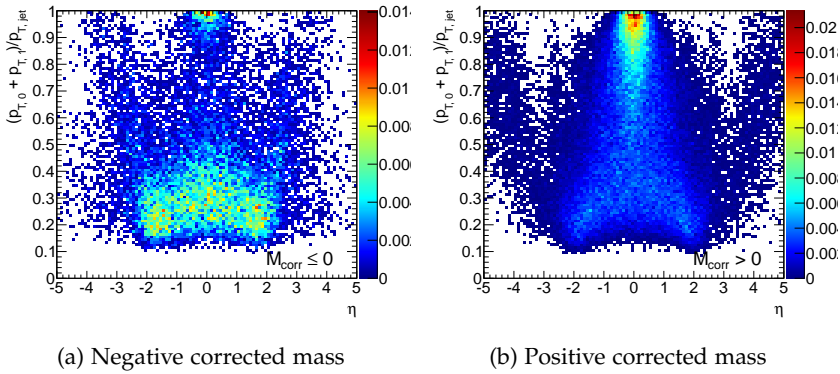


Figure 42: The fraction of the jet p_T carried by the two hardest clusters in the jet vs η , for jets with (a) negative and (b) positive pile-up corrected jet mass.

Further studies of the jets with negative corrected masses shows that their fraction grows with $|\eta|$ and decreases with p_T .⁴

To summarise, it looks as though there are more clusters in these jets, especially at high $|\eta|$, where the impact of pile-up on these jets seems to be different. Something makes the jet area four-vector model the jet four-vector poorly; for instance the high cluster density could relate to differences in the jet area. One conjecture is that these are pile-up jets, possibly from combination of contributions from different pile-up vertices. The problem was not resolved and it was decided to not correct the jet mass using the four-vector area, but to continue using a scale factor relating p_T , E and m , based on the size of the p_T correction from the $\rho \cdot A$ subtraction.

☞ This would explain the p_T regime and different topology.

⁴ At high p_T , the impact of pile-up and pile-up correction gets relatively smaller.

7.3.3 Jet multiplicity

The final category where pile-up alters observables, is the jet multiplicity. Pile-up can add additional hard-scatter jets originating from a pile-up primary vertex, or diffuse radiation clustered into a pile-up jet, or simply bring jets above some threshold by increasing their p_T . Figure 43 shows the distribution of the number of jets N_{jets} above 20 GeV in PYTHIA8, in the central region of the detector, in an environment of no pile-up ($\langle\mu\rangle = 0$), compared to jets in a pile-up environment before and after $\rho \cdot A$ subtraction. The distribution is almost completely restored by the correction, with only a small shift towards higher N_{jets} . The residual pile-up dependence is shown in Fig. 44, which shows the

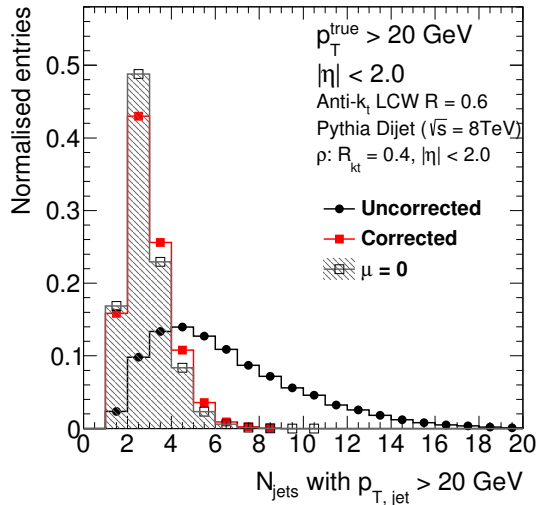


Figure 43: The distribution of the number of jets N_{jets} with p_T above 20 GeV within $|\eta| = 2.0$, in the case of no pile-up ($\langle\mu\rangle = 0$), before correction (black) and after $\rho \cdot A$ subtraction (red).

same quantity as a function of $\langle\mu\rangle$, in $Z \rightarrow \mu\mu$ events in both data and MC. The residual dependence is ~ 0.02 jets/vertex, amounting to a reduction by a factor 25. The agreement between data and MC is much

improved after correction. This reflects the fact that the additional soft radiation from pile-up is inherently non-perturbative and harder to model than the hard scatter process.

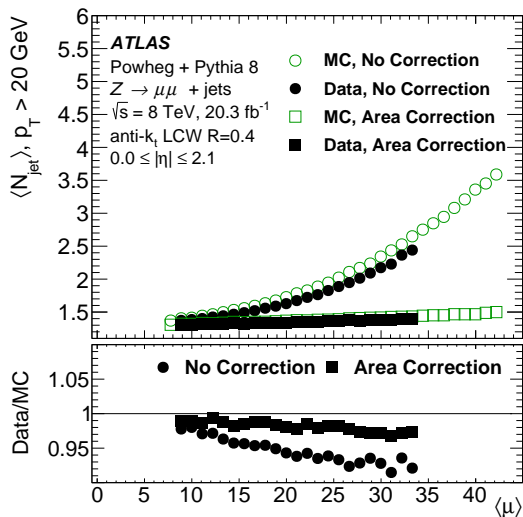


Figure 44: The dependence on $\langle \mu \rangle$ of the average number of jets $\langle N_{jet} \rangle$ with p_T above 20 GeV within $|\eta| = 2.1$, in $Z \rightarrow \mu\mu$ events in data (filled markers) and MC (open markers), before correction (circles) and after correction (squares).

In the central region, the multiplicity of jets depends on pile-up until a lower p_T threshold of 50 GeV. In the forward region, the dependence on pile-up of the jet multiplicity is weaker, and vanishes already at a threshold of 40 GeV.

7.4 POTENTIAL FOR IMPROVEMENTS

The pile-up correction method is already supplemented at low p_T by the use of tracks, where several observables exist that identify jets with a large fraction of their tracks associated to pile-up primary vertices. This helps remove the pile-up dependence of jet multiplicity at lower

p_T in the central region, where tracking information exists. In the forward region, the need is reduced, but there are strong use cases for jets at low p_T at high rapidity. One example is H boson production through vector boson fusion, producing H bosons with large rapidity boost. At high rapidity, a substantial part of the correction comes from the residual correction parameterised in N_{PV} and $\langle\mu\rangle$, which we know does not capture fluctuations very well. Improving the $\rho \cdot A$ correction in the forward region is thus desirable.

For the forward region, out-of-time pile-up is a substantial challenge. Being able to measure the out-of-time history of an event would be useful here, but storing information on the activity in un-triggered bunch crossings would be impossible considering output rate and event size. However, there is information about the pile-up history in the calorimeter cells themselves — this is what we see as out-of-time pile-up. The information in the negative clusters, that are also formed in topoclustering, has not been exploited for this purpose in the corrections so far. I explored using a ρ_{neg} , calculated using negative clusters as input, instead of positive. A combination $\rho = \rho_{pos} + \rho_{neg}$, where $\rho_{neg} < 0$, did reduce the negative $\langle\mu\rangle$ dependence in the forward region. However, the negative clusters aren't calibrated, so using them would require further validation. Considering the interplay of the impact of negative energy and granularity, it might be advantageous to include negative clusters in the region $|\eta| \gtrsim 2.5$ only.

Another possibility would be to implement a correction parameterised in the ratio of negative clusters in the core of the jet to the periphery. This would give jet-by-jet information about the local out-of-time activity, assuming that the negative clusters on the periphery of the jet are a proxy for the amount of overlapping negative energy in the jet core. The $|\eta|$ dependence of this ratio does resemble the impact of out-of-time pile-up on jets (as hinted in Fig. 34). The distributions shown in Fig. 34 are simple geometrical distributions; one could explore ghost association of negative clusters for a refined matching. Furthermore, splitting the correction into a core-part and an area-dependent part may accurately capture the different regimes of pile-up sensitivity in a jet.

The other obvious candidate for improvement is to resolve the issue with the negative corrected jet masses. In the central region, tracking information can be used to find out if these are hard-scatter jets. For the forward region, exploring the use of a different area definition may be interesting, as the coarse granularity and topoclustering may imply that the catchment area of an anti- k_t jet is smaller than the πR^2 expectation from this jet algorithm.

Finally, I note that a jet-level pile-up correction can only go part of the way. The optimal pile-up correction would be a constituent-level correction, removing pile-up clusters, and recalibrating the cluster energy for the impact of overlap with out-of-time energy deposits, before jet finding is done. If the impact of pile-up at the calorimeter-level is understood, the need for additional higher-level corrections is reduced — not to mention the increased pile-up robustness in other variables like E_T^{miss} and isolation calculations. While topo-clustering does part of the job, the challenge here is to take the cluster seeding of jets and the negative energy overlap properly into account.

Part III

DIJET ANGULAR DISTRIBUTIONS AS A
PROBE OF BSM PHENOMENA

At this point, we have constructed the concept of jets and understood the process of making statements about them based on energy depositions that we read out from our detector. We have seen some of the tools used in jet finding, encountered calorimeter readout and the subtleties arising from overlaid energy stemming from different proton interactions, and appreciated some of the fine details in the many steps of jet calibration.

Now, here we stand with our calibrated jets. It is time to make use of them in a measurement.

DIJET MEASUREMENTS

8.1 DIJET OBSERVABLES

Once we have an event with a pair of jets, we can form the so-called *dijet* by four-vector addition of the two jet four-vectors. From this new four-vector, we extract the *dijet mass* m_{jj} , again using the relation

$$m_{jj}^2 = E_{jj}^2 - p_{jj}^2, \quad (29)$$

where the subscript jj means that all quantities are dijet four-vector quantities. From here on, we will assume that the dijet is formed from the two jets with the highest p_T in the event — the *leading* and *subleading* jet.

The invariant mass is particularly interesting precisely because it is invariant — it is a conserved quantity in the case of a particle decay into two jets, for instance. It also probes the energy scale of the collision. These two aspects make the invariant mass an important dijet observable, as an excess of events at a certain m_{jj} can hint at the production of a new heavy particle (possibly seen as a *bump* in a dijet mass spectrum), or generally that we have reached an energy regime where new phenomena become accessible.

The dijet mass spectrum analysis is a sister analysis to the angular distribution analysis, with substantial overlap in phase space and

search philosophy. The analysis of the two distributions have often been performed by the same team within ATLAS. While the main focus of this thesis is to analyse the angular distributions, we will come back to the dijet mass spectrum analysis approach and results as we proceed.

8.1.1 *Dijet kinematics*

I am indebted to Nele [63] for the clear explanations of the kinematics and its implications — and for leaving it to me to work out the details...

In the following we will consider a $2 \rightarrow 2$ process, and assume that we have reconstructed two jets from it. For the kinematics derivation however, we will refer to the partons, and assume that we can transfer the findings to the jets afterwards.

For massive objects, like jets, rapidity as defined in Eqn. 11 is used, rather than pseudorapidity. In Chapter 3, we introduced y_B , the boost of the collision centre-of-mass frame with respect to the detector frame. Denoting the outgoing parton rapidities as y_1, y_2 , this is expressed as

$$y_B = \frac{y_1 + y_2}{2} \quad (30)$$

— simply the average rapidity of the two partons. Similarly, we can construct

$$y^* = \frac{y_1 - y_2}{2}, \quad (31)$$

where $\pm y^*$ is the rapidity of the two partons in the centre-of-mass frame. The centre-of-mass scattering angle is related to y^* through $\cos \hat{\theta} = \tanh y^*$.

The two outgoing partons must be perfectly balanced in the centre-of-mass frame, where by construction all incoming momenta add up to zero. If initial transverse momenta are neglected, the outgoing partons in a $2 \rightarrow 2$ process will from momentum conservation also balance in p_T and azimuth in the detector frame, with the longitudinal boost, as we saw, giving the transformation between the two frames. From Eqs. 30–31 it is clear that the rapidity difference is independent on choice of longitudinal boost.

8.1.2 Angular distributions, χ

For the same $2 \rightarrow 2$ process with massless particles, we introduce the Mandelstam variables, letting 1 and 2 denote the outgoing parton indices:

$$\begin{aligned}\hat{s} &= (p_1 + p_2)^2 \\ \hat{t} &= -\frac{\hat{s}}{2} (1 - \cos \hat{\theta}) \\ \hat{u} &= -\frac{\hat{s}}{2} (1 + \cos \hat{\theta})\end{aligned}\tag{32}$$

from which we see that $|\hat{t}| \leq \hat{s}$, $|\hat{u}| \leq \hat{s}$. Being the centre-of-mass energy squared, \hat{s} is related to the proton-proton (pp) collision centre-of-mass energy and incoming parton Bjorken x as $\hat{s} = x_i x_j s$.

At leading order, the QCD $2 \rightarrow 2$ scattering process is dominated by t -channel exchange, where a gluon is exchanged, resulting predominantly in small scattering angles (where $\hat{t} \rightarrow 0$, $\hat{u} \rightarrow -\hat{s}$). The differential partonic cross section can be expressed in terms of \hat{t} and \hat{s} as

$$\frac{d\hat{\sigma}}{d\hat{t}} \propto \frac{1}{\hat{s}^2} \overline{\sum} |M|^2,\tag{33}$$

where in the notation for matrix element squared, $\overline{\sum}$ implies that colour and spin indices are averaged and summed over for the initial and final states, respectively.

For the dominant process at high p_T , $qq' \rightarrow qq'$, one finds that

$$\overline{\sum} |M|^2 \propto \alpha_s^2 \cdot \frac{\hat{s}^2 + \hat{u}^2}{\hat{t}^2} \sim \alpha_s^2 \cdot \frac{\hat{s}^2}{\hat{t}^2}.\tag{34}$$

Using this in Eqn. 33, we see that

$$\frac{d\hat{\sigma}}{d\hat{t}} \propto \frac{\alpha_s^2}{\hat{t}^2}.\tag{35}$$

This equation can be rewritten in two ways to make it more enlightening. Firstly, expressing it in terms of $\cos \hat{\theta}$, and using the expression

cf. the PDFs in Fig. 4

for \hat{t} from Eqn. 32, we recover the angular behaviour of Rutherford scattering:

$$\begin{aligned} \frac{d\hat{t}}{d \cos \hat{\vartheta}} &= \hat{s}/2 \\ \frac{d\hat{\sigma}}{d \cos \hat{\vartheta}} &\propto \frac{\alpha_s^2 \hat{s}}{\hat{t}^2 2} = \frac{2\alpha_s^2}{\hat{s}(1 - \cos \hat{\vartheta})^2} = \frac{\alpha_s^2}{2\hat{s} \sin^4(\frac{\hat{\vartheta}}{2})} \end{aligned} \quad (36)$$

Introducing the rapidity difference measure χ ,

$$\chi = e^{|y_1 - y_2|} = e^{2|y^*|} = \frac{1 + |\cos \hat{\vartheta}|}{1 - |\cos \hat{\vartheta}|} \sim \frac{1}{1 - |\cos \hat{\vartheta}|} \quad (37)$$

for t -channel processes, using the last equality in Eqn. 37, the differential cross section becomes

$$\begin{aligned} \chi &\sim -\frac{\hat{s}}{2\hat{t}} \Rightarrow \frac{d\chi}{d\hat{t}} \sim \frac{\hat{s}}{2\hat{t}^2} \\ \frac{d\hat{\sigma}}{d\chi} &\propto \frac{\alpha_s^2/\hat{t}^2}{\hat{s}/\hat{t}^2} = \frac{\alpha_s^2}{\hat{s}} \end{aligned} \quad (38)$$

We thus see that for a fixed \hat{s} — or experimentally: m_{jj} — the differential production cross section $d\hat{\sigma}/d\chi$, is flat as a function of χ for t -channel exchange. This is thus what we expect from lowest order QCD.

A more isotropic event will in turn be independent on $\hat{\vartheta}$, implying that $\frac{d\hat{\sigma}}{d \cos \hat{\vartheta}}$ is constant. Using the previous relations, we can derive the following expressions for the differential cross section:

$$\begin{aligned} \frac{d\hat{\sigma}}{d\hat{t}} &\propto \frac{1}{\hat{s}} \\ \frac{d\hat{\sigma}}{d\chi} &\propto \frac{\hat{t}^2}{\hat{s}^2} \propto \left(\frac{1}{\chi}\right)^2, \end{aligned} \quad (39)$$

meaning that the cross section peaks at low χ .

Many new phenomena are expected to have isotropic distributions: for instance, the distribution of decay products of a new particle produced in the collision. Furthermore, a phenomenon that can be

produced at the LHC must couple to partons in some way, meaning, that it can produce partonic final states, which lead to jets. This makes deviations in the dijet angular distributions a good indicator of phenomena beyond the SM. As mentioned in Chapter 1, this possibility has been explored at a range of energies; I have searched for such deviations using the two highest energy data sets to date, with $\sqrt{s} = 8$ and 13 TeV. These two analyses are the focus of the remainder of this thesis.

8.2 TOOLS IN THE ANALYSIS OF ANGULAR DISTRIBUTIONS

At LO, we can equate

$$m_{jj}^2 = \hat{s} = 4p_T^2 \cosh^2(y^*). \quad (40)$$

Noting that all quantities are positive, and that $\cosh(x) = \cosh(|x|)$, the relationship between p_T , m_{jj} and χ becomes

$$\begin{aligned} m_{jj} &= 2p_T \cosh(|y^*|) = p_T(e^{|y^*|} + e^{-|y^*|}) \\ &= p_T \left(\sqrt{\chi} + \frac{1}{\sqrt{\chi}} \right), \end{aligned} \quad (41)$$

which provides a very useful intuition: for a given m_{jj} , the higher p_T jets are found at low χ .

Going to the hadron level, the differential cross section $\frac{d\sigma}{d\chi}$ is traditionally referred to as the angular distribution. The hadron level cross section is obtained through integration over the momentum fractions and PDFs multiplied by the partonic cross section:

$$\frac{d\sigma}{d\chi} = \int dx_1 \int dx_2 f_1(x_1, Q^2) f_2(x_2, Q^2) \frac{d\hat{\sigma}}{d\chi} \quad (42)$$

To isolate the partonic cross section, $dx_1 dx_2$ can be expressed in terms of $d\tau dy_B$, letting $\tau = x_1 x_2 = \hat{s}/s$, $y_B = \frac{\ln(x_1/x_2)}{2}$. So, χ , \hat{s} and y_B are an equivalent set of parameters for expressing the hadronic cross section. Keeping \hat{s} fixed — experimentally, m_{jj} —, the value in a given χ bin is thus given solely by the partonic cross section, which is

☛ The physics does not depend on the choice of reference frame.

independent on the varying y_B . However, y_B encodes the convolution with the PDFs, which does not affect the partonic cross section but re-weights the distribution. As discussed in Chapter 2, the PDFs are not calculable directly in QCD, while the partonic cross sections are. Since possible new phenomena modify the partonic cross section, it is desirable to maximise the sensitivity to deviations from QCD predictions, and thus to minimise the influence of the convolutions with the PDFs. Thus a narrow range in y_B is preferable.

8.2.1 Comparing the angular distributions to prediction

With the addition of higher orders (and non-perturbative effects), the angular distribution is no longer fully flat in χ , and it needs to be compared to a more elaborate prediction. We have seen that signs of new physics phenomena — angular distributions that are more isotropic than QCD — are expected to appear as deviations at low χ . The analysis of the angular distributions is a comparison of shape in data and SM simulation and relies on this ability to discern such deviations. To minimise the uncertainties in the modelling of the SM distributions, the angular distributions are normalised to have the same integral as data. In visualisation, all angular distributions are normalised to unit area. This highlights the shape and simplifies comparisons across m_{jj} regions.

Simulation

☛ More SM simulation details are given in Chapter 9.

The LO generator PYTHIA8 is used to obtain the QCD prediction of the angular distributions. It is a complete generator, simulating the whole process from matrix elements to hadronisation. The modelling of non-perturbative effects is subject to tuning of free parameters in QCD, such as $\alpha_s(M_Z)$, the amount of initial and final state radiation, etc. The tuning is made in comparison with experimental data, and thus the non-perturbative effects partly compensate the lack of higher order calculations.

Corrections

The LO predictions are brought to NLO accuracy using NLOJET++ [64–66]. This is not a complete generator, but a tool for calculating NLO cross sections for hard processes with up to three-jet final states. It can provide bin-by-bin correction factors obtained from running both LO and NLO calculations. The procedure is described in more detail in Sec. 8.4.

In addition to the QCD corrections, at high energies, EW corrections become important [67]. It can be thought of as the decreasing importance of the mass of the weak bosons: there are contributions from virtual exchange of soft or collinear weak gauge bosons, resulting in Sudakov-type logarithms, with the leading term evolving as $\alpha_W \ln^2(Q^2/M_W^2)$. Tree-level EW corrections of $\mathcal{O}(\alpha_s \alpha, \alpha^2)$ and weak loop corrections at $\mathcal{O}(\alpha_s^2 \alpha)$ are provided by the authors of Ref. [67], as bin-by-bin correction factors resulting from cancellation between (positive) tree-level and (negative) 1-loop effects. The tree-level effects are negligible for regimes corresponding to low Bjorken x , where gluons dominate. In addition, there is a strong angular trend, since the Sudakov regime requires both \hat{s} and \hat{t} to be large. As we have already seen, $\hat{t} \rightarrow 0$ for small scattering angles, i.e., high χ . It is shown in Ref. [67] that the tree-level contributions are also larger at low χ due to interference effects.¹

8.2.2 *Statistical analysis*

The statistical analysis is based on doing a shape comparison between SM prediction and data, obtained through normalising the SM prediction to have the same integral as data. The distribution used is the number of events N vs χ ,² for a given m_{jj} . From here, a test statistic can be formed, used to test the compatibility of the observed data

¹ The argument is that they are dominated by qq initiated processes. It is stated that the interference terms don't receive contributions from the squares of the t -, u - and s -channel diagrams, while these dominate the (forward) LO QCD contributions.

² Technical point: since the analysis framework expects equidistant binning, $\ln(\chi)$ is used.

with both the null hypothesis that it follows the SM prediction, and the alternate hypothesis that it follows the distribution predicted by a combination of SM and signal processes.

We can in general express the observed number of events in terms of a signal strength μ , with $0 \leq \mu \leq 1$, as

$$N = \mu S + B, \quad (43)$$

where S is the nominal number of signal events predicted by the signal model, and B is the number of background events, here the prediction by SM.

Statistics tool

The number of selected events coming from a potential new physics process of cross section σ is $N_{\text{new}} = L \times \sigma \times A \times \epsilon$, where L is the integrated luminosity and $A \times \epsilon$ is the product of the acceptance and efficiency of the event selection criteria. We note that in the nomenclature of Eqn. 43, $N_{\text{new}} = 1 \cdot S$, i.e., with $\mu = 1$. Upper limits on $\sigma \times A \times \epsilon$ relate the maximum N_{new} (or equivalently, μ) still compatible with the data at 95% confidence level.

From the input distributions for a given m_{jj} region, a Poisson likelihood model for the description of the event yield is constructed: if the expected number of signal and SM events in bin i are s_i and b_i , respectively, the likelihood for the distribution in n bins become

$$P(\text{data}|\text{SM} + \text{signal}) = \prod_{i=1}^n \frac{(s_i + b_i)^{n_i} (e^{-(s_i + b_i)})}{n_i!}, \quad (44)$$

where n_i is the number of events in bin i , and again s_i is related to the nominal signal prediction for that bin as $s_i = \mu S_i$. The corresponding SM-only likelihood is obtained with $s_i = 0$ ($\mu = 0$). The likelihood ratio q_μ can be formed as

$$q_\mu = \frac{P(\text{data}|\text{SM} + \text{signal})}{P(\text{data}|\text{SM})}. \quad (45)$$

The Modified Frequentist method (CL_s method) [68] is then used to extract the upper limit on q_μ . Here we will use the signal strength

throughout, but this could also be some other parameter of the model, for instance the cross section itself. Systematic uncertainties on predicted signal and background yields, as well as the (anti)correlation of their effects on the distribution shape, are taken into account by adding a nuisance parameter $\hat{\vartheta}$ for each source of uncertainty. In a profile likelihood, $\hat{\vartheta}$ is the value maximising the likelihood from a Gaussian likelihood $G(\text{data}|\vartheta, \sigma_\vartheta)$, and is obtained in a simultaneous fit of the prediction to data, along with all the nuisance parameters. The systematic uncertainties are described in Sec. 10.5.

For each tested value of μ , the variable

$$\begin{aligned} \text{CL}_s &= \frac{p_\mu}{1 - p_b} = \frac{P(q_\mu \leq q_\mu^{\text{obs}} | \text{SM} + \text{signal})}{P(q_\mu < q_\mu^{\text{obs}} | \text{SM})} \\ &= \frac{\int_{q_\mu^{\text{obs}}}^{\infty} f(q_\mu | \mu, \hat{\vartheta}_\mu) dq_\mu}{\int_{-\infty}^{q_\mu^{\text{obs}}} f(q_\mu | 0, \hat{\vartheta}_0) dq_\mu} \end{aligned} \quad (46)$$

is computed, as the ratio of the integrals from the observed value of the test statistic, q_μ^{obs} , to infinity, of the probability density functions $f(q_\mu)$ when the true value of the parameter of interest is either the tested signal μ (p_μ) or zero (SM-only hypothesis, p_b). The 95% CL limit on μ is then given by the solution to the equation $\text{CL}_s = 0.05$. The compatibility of the data with the null hypothesis is reported as $\text{CL}_b = 1 - p_b$, which from unitarity of probability corresponds to the integral in the denominator taken from q_μ^{obs} to positive infinity. Analytic asymptotic formulae describing the test statistic distributions f are used for the results shown in this thesis, as described in Ref. [69]. It has been verified that the asymptotic formulae give the same solution as a sampling of the test statistic distribution from toy experiments.

8.3 BINNING CONSIDERATIONS

8.3.1 χ binning

Following the calorimeter granularity, a rapidity binning in multiples of the typical Tile calorimeter cell width of 0.1 minimises smearing

and modulations from edge effects. Defining the location of the χ bin edge i as $\exp(0.3 \times i)$ was demonstrated to be optimal [63], using 11 bins with the last bin edge visually extended to $\chi = 30$, with the actual event selection cut at $y^* = 1.7$ ($\chi \approx 29.94$). Especially considering the wide bins used for χ , migrations due to the angular resolution of jets are negligible [70, Appendix X].

The definition of the χ binning makes the bin width grow exponentially. For visualisation, logarithmic horizontal axes are used for χ , highlighting the more interesting low χ region. One should however keep in mind that the distribution is dominated by the high χ region, for instance in the normalisation procedure, making signal bias negligible.

8.3.2 m_{jj} binning

Apart from stabilising the angular distributions, as shown above, introducing a binning in m_{jj} also gives a sensitivity to the scale of possibly emerging new phenomena at high m_{jj} . The $d\sigma/d\chi$ distribution is binned coarsely in m_{jj} using bins of $\mathcal{O}(100 \text{ GeV} - 1 \text{ TeV})$. The lowest possible m_{jj} is dictated by the p_T thresholds used in the event selection, which in turn are typically derived from the trigger efficiency, which has a turn-on curve. Only triggers at 99.5% or higher efficiency are used, which avoids efficiency corrections as well as matching schemes. A lowest order indication of the resulting m_{jj} threshold corresponding to a p_T threshold is given by Eqn. 41, inserting the maximum χ used, but in practice it is often slightly higher.

The width of the m_{jj} intervals used are subject to optimisation of the balance between statistical and systematic uncertainty, but also sensitivity to benchmark signals, and in the case of a first-data search, flexibility! The optimisation of the cut values is detailed in Chapter 10.

8.4 NLO QCD CORRECTIONS: k -FACTORS

PYTHIA calculates hard scattering processes to LO only, but since it is a complete event generator, some of the missing higher order processes

☞ For a fast search, the final data set is not known when the analysis design is laid out, and there needs to be room for later changes.

are partially made up for in the parton showering. It can be thought of as a “partial” NLO correction K_{part} which is already factored into the PYTHIA8 simulation. As NLO perturbative calculations are more precise, it is advantageous to correct the PYTHIA prediction to NLO by applying bin-wise K -factors.³ These corrections are derived as a ratio between the NLO and LO cross section for the hard process, calculated using NLOJET++. In the procedure to apply the NLO corrections, care must be taken to handle the non-perturbative contributions in PYTHIA correctly. For this a dedicated PYTHIA8 sample with only hard process and parton showering turned on, LO_{show}^{PYTHIA} , is used. One can then define an NLO corrected PYTHIA8 prediction as

$$PYTHIA_{corr} = \frac{(NLO/LO)^{NLOJET++}}{(LO_{show}/LO)^{PYTHIA}} \cdot PYTHIA_{reco}, \quad (47)$$

where we have identified $K_{part} = (LO_{show}/LO)^{PYTHIA}$ and divided the PYTHIA prediction by it. Assuming $LO^{NLOJET++} = LO^{PYTHIA}$, we define a K -factor from

$$PYTHIA_{corr} = \frac{NLO^{NLOJET++}}{LO_{show}^{PYTHIA}} \cdot PYTHIA_{reco} \equiv K \cdot PYTHIA_{reco} \quad (48)$$

The assumption that the two LO predictions are equal relies on recognising that these are the pure QCD matrix element predictions. The only thing which can introduce a difference between them is using a different choice of PDF and α_s in the calculations, so the calculation requires using the same PDF in NLOJET++ as in PYTHIA8. Note that the PDF sets have to match the order of the calculation.

The calculations for the $\sqrt{s} = 8$ TeV analysis are explicitly shown here. The CT10 PDF set is used, at the proper order in QCD, but there is a difference remaining in the choice for α_s . This is set differently in

³ For angular distributions, one example that would introduce deviations from the $2 \rightarrow 2$ kinematics could be an additional final state jet. This is an NLO hard-scatter process, but could also be achieved at LO by hard final-state radiation off of one jet in a $2 \rightarrow 2$ scattering. Both cases would modify the angular separation of the hardest two jets in the system from the back-to-back case.

The PYTHIA8 settings to stop after parton showering are given in Appendix A.

DIJET MEASUREMENTS

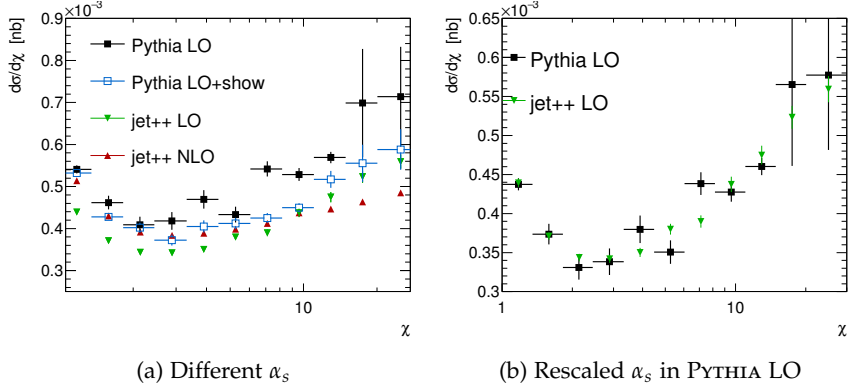


Figure 45: Predicted differential cross section $d\sigma/d\chi$ at $\sqrt{s} = 8$ TeV in the dijet mass bin $2000 \leq m_{jj} < 2600$ GeV, using (a) different α_s and (b) rescaling the PYTHIA prediction to the α_s value used in NLOJET++.

the calculations in the two generators, as they use the evolution of α_s at different orders: $\alpha_s^{\text{NLOJET++}}(M_Z) = 0.118$ and $\alpha_s^{\text{PYTHIA8}}(M_Z) = 0.135$.

To illustrate the impact of this difference, all components needed to obtain the correction factor in Eq. 47 are drawn in Fig. 45a, showing the differential cross section $d\sigma/d\chi$ in the dijet mass bin $2000 \leq m_{jj} < 2600$ GeV, as predicted from the LO matrix element calculations of both generators, as well as the NLO prediction from NLOJET++ and the PYTHIA8 prediction where non-perturbative effects are turned off. In Fig. 45b, the PYTHIA LO prediction has been rescaled by the square of the ratio of the two values of α_s , taken at $p_T^{\text{avg}} = Q = 350$ GeV, which following Eqn. 41 is the minimum p_T required for a dijet mass in this range. The running of α_s follows the LO evolution corresponding to the first term in Eqn. 9, with the number of light flavours n_f taken to be 5. The value of Λ_{QCD} is a matter of tuning, and known to be $\Lambda_{\text{QCD}} = 0.2262$ GeV in NLOJET++. It is left floating in the PYTHIA case to fit the set value of $\alpha_s^{\text{PYTHIA8}}(M_Z)$ used in the α_s evolution. The values obtained by this evolution are in agreement with those given in [71] for different values of Q .

It is clear from Fig. 45 that the difference in the two LO predictions is introduced solely from the difference in α_s , as it vanishes once the rescaling of PYTHIA LO is done. It is also clear, that this difference merely introduces a shift in the normalisation between the two predictions. As the final analysis uses distributions normalised to the data integral, the difference introduced by the different default α_s values vanishes, and one can safely neglect the LO predictions in the K -factor expression. For each m_{jj} region, a χ dependent K -factor is thus calculated as

$$K(\chi) = \frac{NLO^{NLOJET++}(\chi)}{LO_{show}^{PYTHIA}(\chi)} \quad (49)$$

It is also evident in Fig. 45a that the parton showering process in PYTHIA8 affects the shape of the χ distribution in a similar way as the addition of higher orders, but doesn't give the full answer. Comparing the shapes, we can expect K -factors with only a small dependence on χ . These are then applied to the default LO PYTHIA8 sample with hard process, parton showering, multiple interactions, and non-perturbative effects turned on. The result is a NLO partonic prediction that has been corrected with non-perturbative effects. These K -factors are applied before normalisation of the χ distributions.

Finally, the prediction from PYTHIA8 with K -factors applied is compared to a POWHEG [72–74] prediction of the angular distributions of QCD. POWHEG predicts the hardest emissions to NLO accuracy and is then interfaced to PYTHIA8 for showering. Albeit at NLO, it is not used as the default QCD prediction, since, firstly the CI signal prediction is obtained with PYTHIA⁴ (see Chapter 9 for more details on the signal samples) and secondly, the available $\sqrt{s} = 8$ TeV POWHEG sample was smaller which introduces large statistical fluctuations, particularly at high m_{jj} . Still, the POWHEG sample serves as a reference of what the NLO prediction would be. Figure 46 shows the comparison of the POWHEG and PYTHIA8 \times K -factors predictions at reconstructed level,

⁴ In particular, the signal has interference with QCD, which means having the same QCD prediction in both background and signal modelling is easier

DIJET MEASUREMENTS

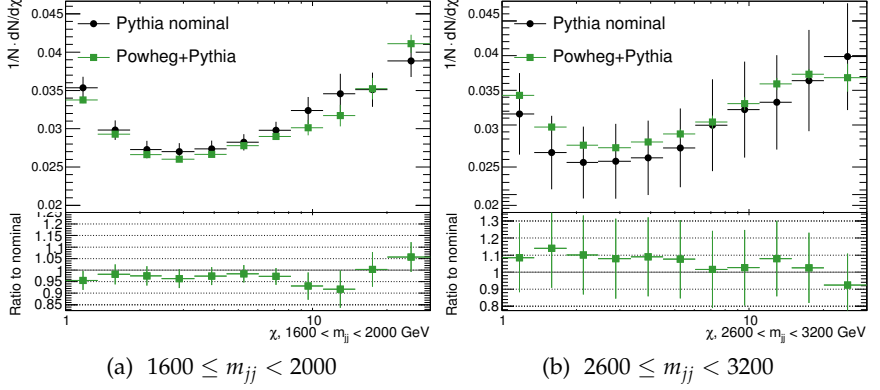


Figure 46: Comparison of the $\sqrt{s} = 8$ TeV differential cross section $d\sigma/d\chi$ (normalised to unit area) predicted by POWHEG to PYTHIA with K -factors, in the dijet mass bin (a) $1600 \leq m_{jj} < 2000$ GeV and (b) $2600 \leq m_{jj} < 3200$ GeV

for two example bins in m_{jj} . The ratio of the two is consistent with 1 within errors for all bins. The normalisation is somewhat driven by the last bin in χ , which is the widest, sometimes introducing large shifts between the predictions even though the general shape agrees.

8.5 DIJET MASS DISTRIBUTION

For the dijet mass distribution, the same kinematics hold, and the sensitivity to isotropic events is enhanced by selecting only low- χ events. Given the relation in Eqn. 41, this implies a lower reach in m_{jj} for a given p_T . The angular distributions thus probe the highest m_{jj} events produced, while the dijet mass distribution displays the m_{jj} evolution of the low χ region, which is expected to be the signal-enriched region in the angular distributions.

The underlying assumption in the design of a prediction for the SM dijet mass spectrum is that it is featureless: in the absence of new scales, it is simply smoothly — and rapidly — falling. This is exploited in a data-driven background estimate, fitting a smooth parameterisation

to the data. This gives a search with only one systematic uncertainty: the choice of fit function. The parameterisation and the method used to choose the fit will be described along with the distributions in Chapter 11.

The slight differences in the analysis strategy of the two distributions does entail differences in their sensitivity. Firstly, while the small systematic uncertainties in the SM prediction of the dijet mass distribution yields a large sensitivity to deviations from the prediction, the prediction itself may become sensitive to signal. For instance, the typical m_{jj} evolution of CI is an onset of a modified cross section that gets more pronounced with higher m_{jj} . This affects the tail of the m_{jj} distribution. A smooth fit of sufficiently many parameters would easily accommodate this change in shape. This makes the dijet mass spectrum particularly suited to search for narrow resonances, locally enhancing the dijet cross section, but less so for non-resonant phenomena. Secondly, the dijet mass measurement is a rate measurement, and it uses the lack of an increased rate expected from signal to set limits on the cross section of a hypothesised new process. This is different from analysing the angular distributions which is above all a shape measurement.⁵

⁵ Of course, the cross section does enter in the fact that a signal needs to be discernible even in the presence of SM processes.

SIGNAL MODEL SAMPLE GENERATION

This chapter describes the modelling of the SM prediction and the signals introduced in Sec. 2.8 in more detail.

9.1 QCD

The baseline SM prediction in the angular distributions is the NLO QCD and EW corrected PYTHIA8 prediction. Being a leading order generator, it implements the calculations outlined in Chapter 8, which provides a suitable starting point for dijet production simulation.

In the $\sqrt{s} = 8$ TeV analysis, the AU2 [75] underlying event tune and leading-order CT10 [19] PDFs are used. At $\sqrt{s} = 13$ TeV, ATLAS had moved to the A14 underlying event tune [76] and leading-order NNPDF2.3 [77, 78] PDFs.

It is known for both the $\sqrt{s} = 8$ and 13 TeV MC samples that the PYTHIA cross section prediction at high m_{jj} is 20 – 30% too large compared to data. This is attributed to a shift in the m_{jj} distribution (the spectrum is harder in MC than in data). However, the prediction from PYTHIA6.421 [79] with underlying event tune AUET2B [75] had shown better cross section and shape agreement with ATLAS data at $\sqrt{s} = 7$ TeV.

To investigate the cause of the shift, a set of PYTHIA8 truth-level samples with variations of for instance Λ_{QCD} and the amount of initial-state radiation [80–82] was compared to the prediction from PYTHIA6.423 [79] with underlying event tune AUET2B. It was verified that the baseline PYTHIA8 prediction at fully reconstructed level deviated only very slightly from the distributions at truth level, meaning that the truth-level tunes could be compared to reconstructed MC without loss of validity. The disagreement between cross section in data and MC was shown to be present already at parton level; the tune variations could not explain the difference seen between PYTHIA6 and PYTHIA8.

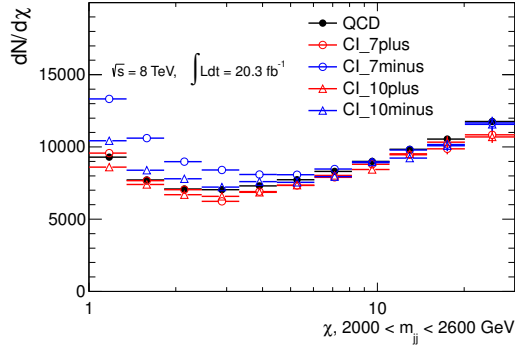
9.2 CONTACT INTERACTIONS

CI is used as benchmark signal in both the $\sqrt{s} = 8$ and 13 TeV searches. In the modelling of CI, only left-chiral colour singlet coupling is considered (corresponding to the subscript L in Eqn. 10), meaning $\eta_{LL} = \pm 1, \eta_{RR} = \eta_{RL} = 0$. This is a simplification whose predictions already cover most of the range obtained by considering also right-handed states. The signal is generated with PYTHIA8, along with QCD, modelling interference with the SM process $q\bar{q} \rightarrow q\bar{q}$. Thus the same PDF set and PYTHIA8 tune is used for CI as for QCD modelling. The branching ratio to quarks is 100%. Example χ distributions of these generated samples at $\Lambda = 7$ and 10 TeV are shown in Fig. 47. The signal strength increases with m_{jj} .

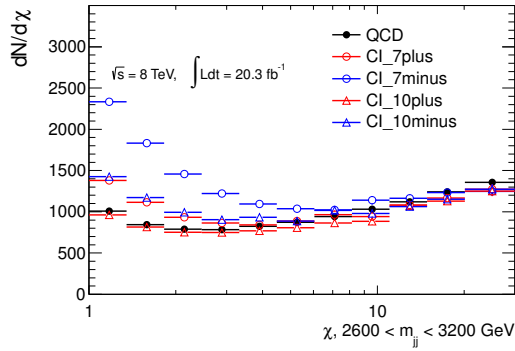
9.2.1 Λ scaling

Apart from the m_{jj} range at which it is probed, the total signal cross section depends on interference mode and the scale Λ , and a modelling of this evolution requires a scan in these 2 dimensions. However, the CI amplitude (from here on called “CI² term”) and interference term scale as $1/\Lambda^4$ and $1/\Lambda^2$ respectively, meaning that the cross section can be obtained at an arbitrary Λ by rescaling. A large sample for each interference mode was generated at $\Lambda = 7$ and 10 TeV, with

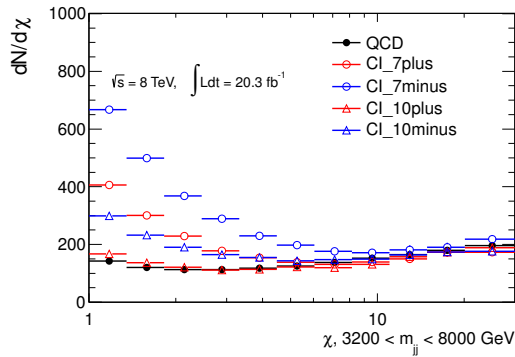
9.2 CONTACT INTERACTIONS



(a) $2.0 < m_{jj} < 2.6$ TeV



(b) $2.6 < m_{jj} < 3.2$ TeV



(c) $3.2 < m_{jj} < 8.0$ TeV

Figure 47: χ distributions of signal and QCD generated at $\sqrt{s} = 8$ TeV for different dijet invariant mass ranges.

the 10 TeV sample used for validation of the extrapolation procedure, which is as follows. By adding the resulting histograms from the two interference modes at a given Λ , the interference terms cancel, and only $2 \times (\sigma_{QCD} + \sigma_{CI^2})$ terms remain. Since the QCD term is known from the SM prediction MC, the CI^2 term can be isolated. Similarly, by subtraction of the two samples, the interference term is isolated. The obtained χ distributions of signal and interference terms for $\Lambda = 7$ TeV are shown for $3.2 \leq m_{jj} < 8.0$ TeV in Fig. 48.

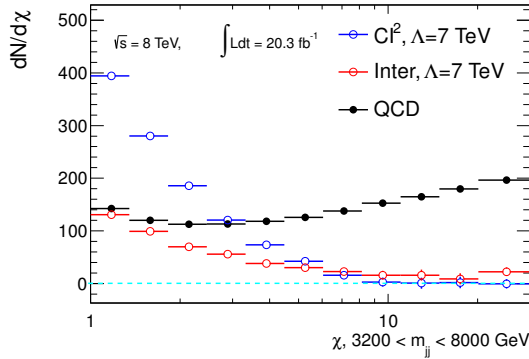


Figure 48: χ distributions of signal CI and interference terms for $\Lambda = 7$ TeV and $3.2 < m_{jj} < 8.0$ TeV.

Using the dependence on Λ for the two terms respectively, full rescaling of the simulated samples can be achieved for any value of Λ . The validity of this rescaling has been tested by comparing the $\Lambda = 10$ TeV distributions obtained from the rescaled $\Lambda = 7$ TeV samples, to those from the generated $\Lambda = 10$ TeV sample. The two versions agree to within 4% (with the largest deviations in the high- χ region, where the signal contribution is negligible and thus the statistical uncertainty is large), as shown in Fig. 49.

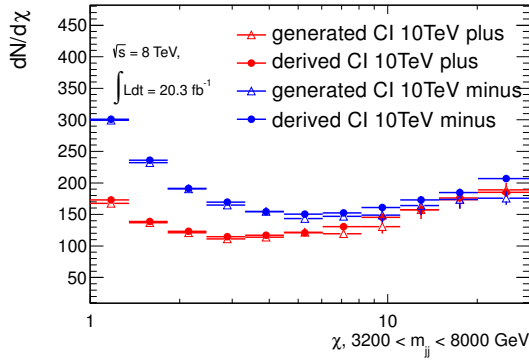


Figure 49: Comparison of signal distribution of $\Lambda = 10$ TeV between generated and derived signal prediction.

9.2.2 Signal K -factors

Also the signal is brought to NLO precision using K -factors. The LO and NLO cross section for each m_{jj} region and χ bin is derived using the CIJET package (v 1.0) [83] for the destructive and constructive interference term and for all the extrapolated values of Λ . As before, by adding and subtracting the LO (NLO) contributions from the positive and negative interference term, one can obtain the LO (NLO) contribution of the CI^2 term and the interference term separately for each bin. Dividing the NLO CI (interference) term by the corresponding LO contribution will give the K -factors for each bin, as shown in Fig. 50. This figure shows that the CI K -factors are overall less than unity, and that the interference term K -factor has the strongest χ dependence. After applying these K -factors, we obtain the final signal contributions at various Λ scales, shown in Fig. 51. There are no EW corrections for signal corresponding to those available for the QCD simulation.

The spacing between the curves in Fig. 50 evolves very smoothly with Λ . Indeed, when drawn for each χ bin as function of Λ , as shown for one region in m_{jj} at $\sqrt{s} = 13$ TeV in Fig. 52, a similar shape vs Λ is seen for all χ bins. A tentative parameterisation $K = p_0 + \frac{p_1}{\Lambda}$ (dashed line in the figures) shows good promise for finding an evolution with

The only difference is that there is no QCD term to be subtracted.

SIGNAL MODEL SAMPLE GENERATION

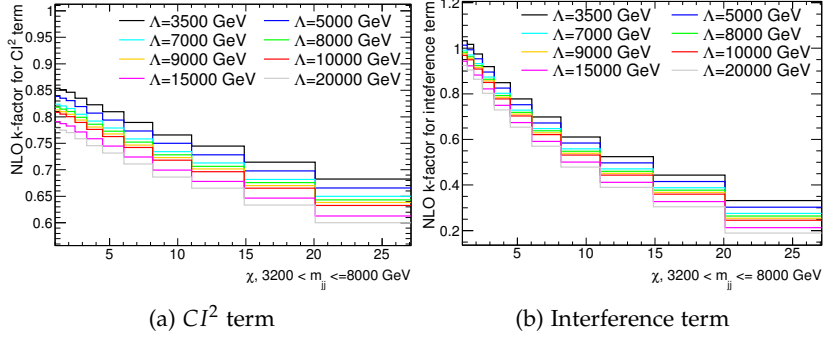


Figure 50: NLO K -factor vs χ for CI signal in $3.2 < m_{jj} < 8.0$ TeV, calculated for $\sqrt{s} = 8$ TeV.

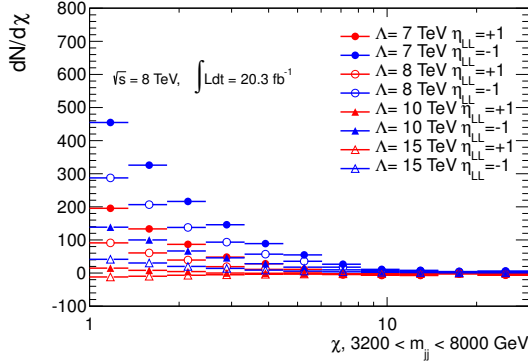


Figure 51: χ distributions of signal with NLO K -factor applied for various Λ scales.

Λ that can be used for both inter- and extrapolation, since running CIJET is time consuming. Such an approach would complement the flexibility in the signal template extrapolation described above.¹

¹ One can note, however, that the evolution with Λ is slow, so the gain in precision from short-range extrapolation is small.

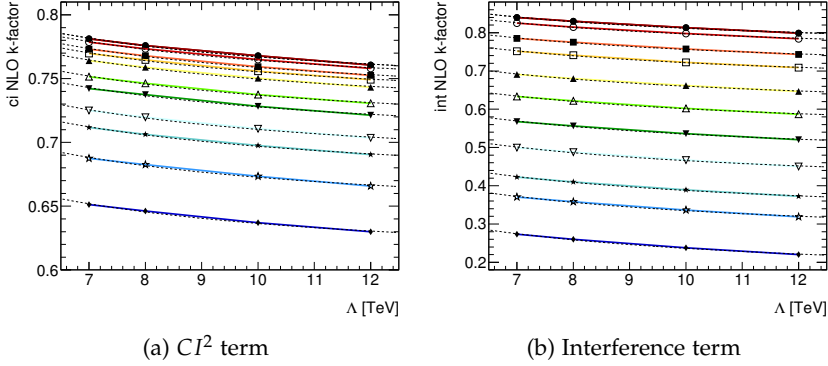


Figure 52: NLO K -factor vs Λ for CI signal in $3.4 < m_{jj} < 3.7$ TeV, calculated for $\sqrt{s} = 13$ TeV. Each curve corresponds to a bin in χ , with the lowest one at the top. The dashed line is a fit.

9.2.3 Normalisation

The CI prediction is generated along with QCD, and the QCD prediction from PYTHIA is subtracted. As we have discussed, the PYTHIA prediction of the cross section is too high compared to data. The cause of this is unknown, even after extensive tune studies for the 8 TeV MC prediction. However, since it is present already at parton level, and since QCD and CI are generated together, it is assumed that to lowest order, the over-prediction of the cross section in QCD is present also in the pure CI prediction. Thus the CI signal nominally corresponding to the integrated luminosity in the data is rescaled by the same factor $N_{\text{data}}/N_{\text{QCD MC}}$ as the QCD prediction.

9.3 QUANTUM BLACK HOLES

QBH is used as an example resonant phenomenon, with a broad peak in m_{jj} and still with a distinct angular distribution compared to the SM. The QBH signal is characterised by a wide resonance of large cross section, and can be discovered or excluded in a range beyond

the m_{jj} reach expected from the SM at a given integrated luminosity. Its cross section is large enough to make a visible signal also in a wide m_{jj} bin like the last m_{jj} region used for the angular distributions.

Two different realisations of the $n = 6$, ADD model black holes, produced at the threshold mass M_{th} equal to the fundamental scale of gravity M_D , are used as benchmarks in the analysis of the angular distributions recorded at $\sqrt{s} = 13$ TeV. They are implemented by two different generators: BlackMax [84] and QBH [85].

BlackMax implements a sophisticated decay model taking into account the possibilities of black holes with rotation from a non-zero impact parameter, or recoiling into the bulk; split-fermion branes (that quarks and leptons exist on different 3D branes); non-thermal or thermal decay, etc. Decays in the QBH generator, in turn, are dictated by the local gauge symmetries of the SM. Despite the modelling differences, the final m_{jj} distributions from the two generators largely have the same shape while the cross section differs. The branching ratio to states producing dijets is 96%.

9.4 EXCITED QUARKS

The narrow resonance benchmark model samples of q^* signal templates are generated for different masses m_{q^*} using PYTHIA8, with the A14 tune [76] and NNPDF2.3 PDF set [78]. The $qg \rightarrow q^*$ production model [35, 36] is used, with the assumption of spin 1/2 and quark-like SM coupling constants. The compositeness scale (Λ) is set equal to m_{q^*} . Only decays to a gluon and light (u and d) quarks are simulated, corresponding to a branching fraction of 85%.

Since the generator and model name are the same, we will use the convention to denote the model with QBH and the generator with QBH.

ANALYSIS OF ANGULAR DISTRIBUTIONS AT $\sqrt{s} = 8$ AND 13 TEV

This chapter describes the event and data quality selections needed for analysis, as well as the corrections to MC and its systematic uncertainties. Since they are very similar, the $\sqrt{s} = 8$ and 13 TeV analyses [12–14] are described in parallel. This also highlights the occasions where different choices have been made, and a motivation is given.

One might wonder about the motivation for doing the same search twice, shortly after each other. The integrated luminosity used in the two searches differs by an order of magnitude, with the more recent $\sqrt{s} = 13$ TeV data set being the smaller one. The answer is, that even with a small data set, we rapidly break new ground if the centre-of-mass energy increases. The reason is the increase in parton luminosity, as illustrated in Fig. 53. This figure shows the ratio of the calculated parton luminosities at the two centre-of-mass energies explored in this work, as function of the probed mass. Already at masses around 2 TeV, the penalty from the one order of magnitude smaller integrated luminosity in the $\sqrt{s} = 13$ TeV data set is overcome.

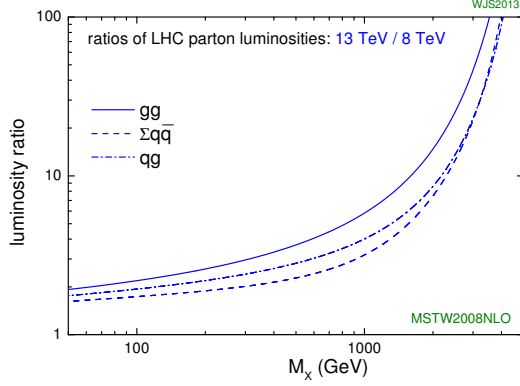


Figure 53: The ratio of parton luminosities at $\sqrt{s} = 13$ to 8 TeV [86].

10.1 EVENT SELECTION

The analysis idea is to measure the dijet angular distributions in events with two or more jets above a certain p_T threshold given by experimental considerations, in a rapidity range that allows a long enough lever arm in χ for the shape comparison between data and prediction. The different experimental conditions between the $\sqrt{s} = 8$ and 13 TeV analyses warrant a few differences that will be discussed separately below. The overall selection common choices are listed here:

- The highest $\sum_{\text{track}} p_T^2$ vertex has at least two tracks associated with it (primary vertex definition)
- Trigger: passes OR of the relevant Level 1 and HLT triggers
- at least two clean jets with $p_T > 50$ GeV
- Leading jet $p_T > p_T^{\text{thr}}$ specific to the two searches
- $|y^*| < 1.7$ ¹

¹ For m_{jj} distributions, this cut is at 0.6. In addition there is no cut on y_B .

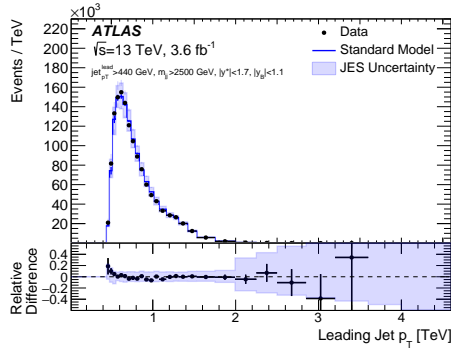
- $|y_B| < 1.1$
- $m_{jj} > m_{jj}^{\text{thr}}$ specific to the two searches

The p_T cut at 50 GeV is governed by pile-up considerations: the number of jets above this cut after pile-up correction is largely independent on pile-up. If the subsequent leading jet p_T cut is high, this lower cut has very marginal impact. It does however remove pathologically unbalanced topologies where the subleading jet p_T is very low, for instance where the leading jet originates from a noise burst or non-collision background. Similarly, the jet cleaning (see Sec. 6.3.2) removes very few additional events since the event selection itself, requiring two jets, removes most events with fake high- p_T jets.

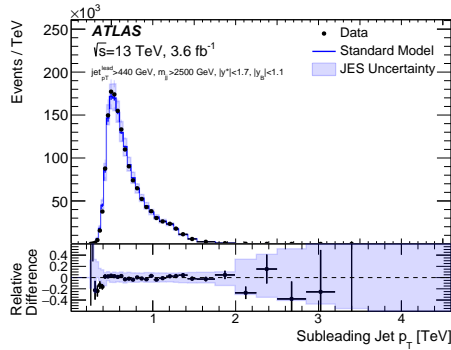
The choice of jet distance parameter differs between the $\sqrt{s} = 8$ and 13 TeV analyses: $R = 0.6$ in the analysis of $\sqrt{s} = 8$ TeV data, while in the analysis of $\sqrt{s} = 13$ TeV data, $R = 0.4$ was used. The larger distance parameter was intended to improve the mass resolution by catching more of the final-state radiation. However, in a study comparing the two distance parameters, no improvement in m_{q^*} resolution was seen. In the interest of harmonisation with other analyses in ATLAS, and based on the knowledge that anti- k_t jets with $R = 0.4$ would be the first jet collection where corrections and uncertainties would become available, it was decided to use the smaller distance parameter in the analysis of $\sqrt{s} = 13$ TeV data. In addition, since the trigger uses anti- k_t jets with $R = 0.4$, a smaller R gives fully efficient triggers at lower reconstructed p_T .

Figure 54 shows some key variables after the above selection in the 13 TeV data set and PYTHIA8 MC, where all distributions have been reweighted using the (χ, m_{jj}) dependent NLO QCD K- and EW κ -factors, and MC has been renormalised by a scale factor to match the number of events in data. This scale factor is 0.7, meaning that the MC cross section is $\sim 30\%$ too high in this region of phase space.

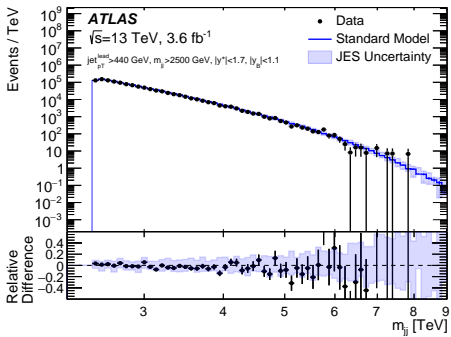
ANALYSIS OF ANGULAR DISTRIBUTIONS AT $\sqrt{s} = 8$ AND 13 TEV



(a) Leading jet p_T



(b) Subleading jet p_T



(c) m_{jj}

Figure 54: A few of the observables, shown in data and MC normalised to the data integral after the selection listed above: the (a) leading jet p_T , (b) subleading jet p_T , and (c) m_{jj} . The JES uncertainty, described later, is shown in shaded blue.

10.1.1 $\sqrt{s} = 13 \text{ TeV}$

The analysis of data at $\sqrt{s} = 13 \text{ TeV}$ was done twice: first with the subset of 2015 data that was collected, processed and available for analysis in time for the LHCP conference in August 2015 [13], and then with the full 2015 data set, published in December [14]. The only change in method between the two lies in the statistical analysis, where the full data set uses a more advanced method combining several m_{jj} regions. The earlier search follows the procedure used in the analysis of the $\sqrt{s} = 8 \text{ TeV}$ data, which will be described later.

Trigger

The focus of the data analysis at $\sqrt{s} = 13 \text{ TeV}$ was to produce a fast result giving the first look at the new energy regime opening up. Thus, for simplicity, the lowest un-prescaled single jet trigger was used, meaning that all events have an equal statistical weight. The conjecture was that the same hardware and high-level trigger would remain un-prescaled throughout 2015. The trigger p_T threshold at 360 GeV corresponds to full efficiency for anti- k_t $R = 0.4$ jets at 409 GeV, with minimal $|y^*|$ dependence. The corresponding m_{jj} efficiency curve is highly $|y^*|$ dependent, through the kinematic bias described by Eqn. 41. For $|y^*| < 1.7$, the minimum m_{jj} is $\sim 2000 \text{ GeV}$. However, considering the possibility that the trigger prescales could change, a safety margin was introduced, giving an m_{jj} cut at 2500 GeV.²

10.1.2 $\sqrt{s} = 8 \text{ TeV}$

The analysis of the 8 TeV data was done on a mature and final data set, with all conditions already well understood. It was done after the dijet mass resonance search had already been performed on a data set partially overlapping with the phase space of the angular distribution search (with a cut on $|y^*| < 0.6$, allowing for a lower m_{jj} cut, at 250 GeV). This data set was more fully explored, using

² For mass distributions, the corresponding cut is at $m_{jj} = 1100 \text{ GeV}$.

a combination of triggers reaching all the way down to the pile-up limitation on jet p_T . With full efficiency at $m_{jj} = 500$ GeV, the lower mass cut was set at 600 GeV.

Trigger

In practice this means that the actual leading jet p_T cut was slightly higher.

A lower p_T cut of 50 GeV was used for both leading and subleading jet. This is far down in the prescaled regime of the jet p_T spectrum, meaning that the events will have different weights, based on the prescale. For the combination of two triggers with different prescales, let's imagine we have trigger A with a prescale factor of 100, and trigger B with 10, where A is fully efficient at a lower p_T than B . Even though trigger A is fully efficient before trigger B , in the presence of prescales, it will not record the same events. If there are 100 events above the threshold of full efficiency of trigger B , it will have fired 10 times, while A has fired once, and this event may or may not be present also in the set that was triggered by B . In the event weight calculation, the probability that a trigger *didn't* fire is used to avoid double counting [87]. The weight is given by:

$$w = \frac{1}{1 - \prod_i (1 - \frac{1}{\langle p_i \rangle})}$$

If there were only one trigger, the event weight would be $\frac{1}{\langle p_i \rangle}$.

where the index i denotes one of the available fully efficient triggers and $\langle p_i \rangle$ is the average prescale of the single jet trigger i . The average prescale reflects the fact that prescales can change in the course of data taking, as the instantaneous luminosity delivered by LHC evolves over time.

In Run1, the offline computing capacity for storing and processing data promptly limited the EF output rate to approximately 400 Hz. The data stream resulting from all EF triggers, and recorded for prompt processing, is called the *normal stream*. In addition, at approximately 200 Hz, ATLAS stored events for later reconstruction. This is called the *delayed stream*, partly derived from a different set of triggers. In the analysis of $\sqrt{s} = 8$ TeV data, it was advantageous to use the delayed stream only, since the lowest un-prescaled trigger had a lower p_T threshold in the delayed stream than in the normal stream. This

stream was not active in the beginning of 2012 data taking, reducing the available integrated luminosity from 20.2 to 17.3 fb⁻¹.

10.2 CORRECTIONS

10.2.1 Theoretical corrections

The m_{jj} binning used in the derivation of the following corrections will be discussed shortly (see Sec. 10.4). Figure 55 shows the NLO

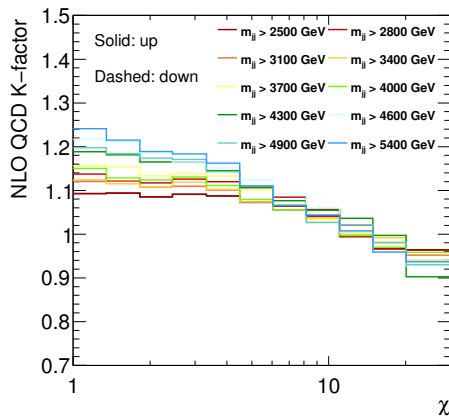


Figure 55: Shape K -factors for the χ distribution for all dijet mass regions in the analysis of $\sqrt{s} = 13$ data, obtained from distributions normalised to the same integral.

K -factors described in Sec. 8.4, derived for the $\sqrt{s} = 13$ TeV MC prediction as function of χ and for all dijet mass regions, in exclusive binning. The generator settings are given in Appendix A. The K -factors become increasingly important with m_{jj} . Although a large number of events were generated, there are statistical fluctuations in the K -factors which have been reduced by a smoothing procedure,³

³ The ROOT method TH1::Smooth() is used, which employs the 353QH smoothing algorithm, using the repeated median of intervals (3, 5, 3 bins wide) and also includes the smoothed residuals [88].

which brings outliers closer to the overall trend using medians of sequences. The edge points and statistical uncertainties are unaffected. The shift of points introduced by the smoothing is well within the statistical uncertainty for all points. The K -factor statistical uncertainty is taken as a flat systematic uncertainty, corresponding to the largest uncertainty assessed from NLOJET++.

Figure 56 shows the EW correction κ -factors, provided by the authors of [67]. They have a large effect on the shape of the distributions, bringing the low- χ region up. The m_{jj} dependence is again clear.

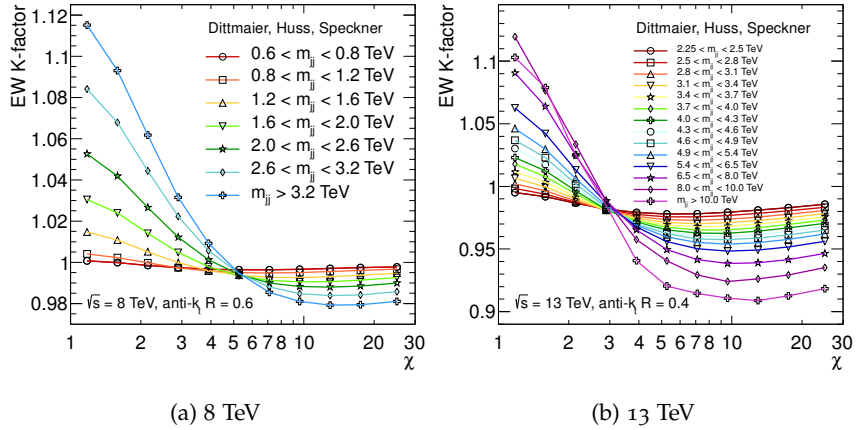


Figure 56: EW correction κ -factors for the χ distribution for all dijet mass bins for (a) $\sqrt{s} = 8$ TeV and (b) $\sqrt{s} = 13$ TeV. The lines are a linear interpolation, there to guide the eye only.

For both centre-of-mass energies, the κ -factors tend to pivot around the same χ point in all mass regions, around $\chi = 5$ and 3, respectively. That this pivoting point moves in χ relates to probing a different region of the PDF. The theorists providing the corrections call the pivoting an “accidental” cancellation. However, I note that indeed the \sqrt{s} ratio $8/13 \approx 3/5$, which is the relation we would expect if the location in χ can be mapped from $x_i x_j$.

The statistical uncertainty on the κ -factors has been made negligible by using large samples. Derived as a relative correction, using the same simulation settings as the nominal MC prediction, no additional systematic uncertainties are taken into account for the EW corrections.

10.2.2 *Experimental corrections: removal of masked modules*

During the course of 2012 data taking, some modules in the Tile calorimeter were, transiently or permanently, non-responsive. The corresponding cells were masked, meaning that the deposited energy was not read out, leading to a temporary or permanent hole in the solid angle coverage of the calorimeter. An algorithm was implemented to estimate the unrecorded energy based on interpolation between the neighbouring calorimeter cells. Unfortunately, this led to an overestimate of the energy deposited, which would bias the dijet mass measurement towards higher masses. Instead, all events were discarded where one of the two leading jets, or any other jet with $p_T > 0.3 \cdot p_T^{\text{sublead}}$,⁴ fell into a masked module. This procedure corresponds to a decrease in event rate, since the entire event was discarded. Figure 57 demonstrates the impact on the $\eta - \varphi$ distribution of the leading jet. However, the distribution in $|\eta|$ of masked modules was non-uniform, with a larger number in the central detector, affecting the overall angular distribution shape with a larger deficit at low χ . The effect thus had to be reproduced in MC.

cf. the $|\eta|$ coverage of the Tile calorimeter, Chapter 5

⁴ Like for cleaning, this is based on the finding that below this fraction, the maximum energy smearing in a masked module would not introduce changes in the ordering of jets.

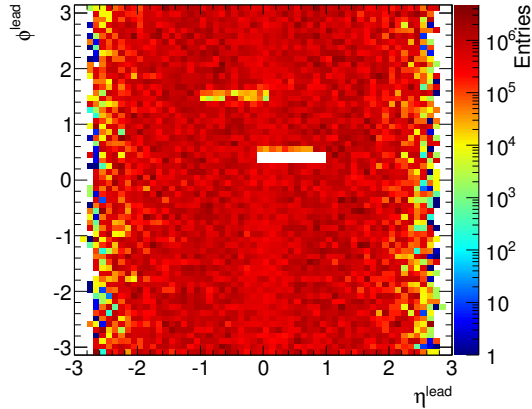


Figure 57: Impact of removing the masked modules on the leading jet $\eta - \varphi$ distribution. The two modules masked for the majority of the data taking are clearly visible.

The dijet event simulation was done before the 2012 data taking was concluded, and only the two permanently masked modules known at the time of MC sample production were included in the detector simulation. This also implies that the MC isn't fully unbiased by this effect, making a MC-based correction of data implausible. In data, more modules were masked with time, introducing a time dependence, translated to a fraction of the integrated luminosity being discarded due to each one of them. The impact of removing the masked modules is mimicked in MC by, for each simulated event, drawing a run number from a sampling distribution which reflects the integrated luminosity collected in each run in the data, and rejecting events where the simulated leading jets fall into those regions which have non-operational Tile modules in the corresponding data taking run. Using the integrated luminosity distribution as described ensures that a representative number of events is discarded in MC for each non-operational module in data.

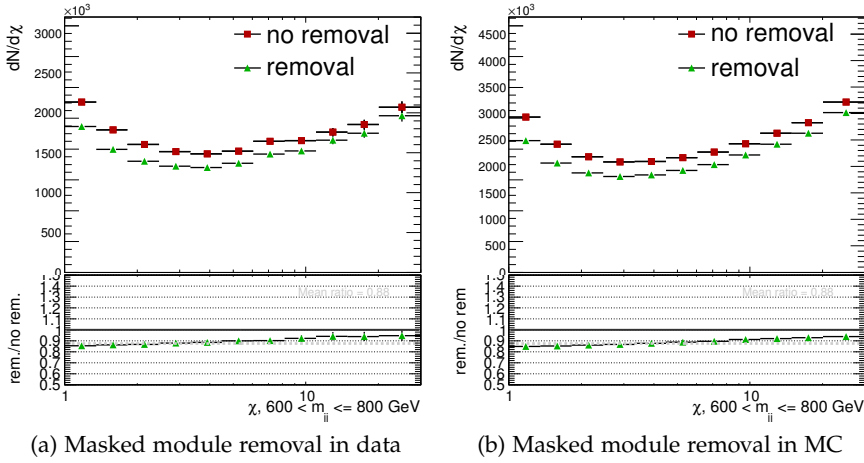


Figure 58: Overlay of the angular distribution for $600 < m_{jj} \leq 800$ GeV with and without removing the masked modules in (a) data and (b) MC.

Figure 58 shows the impact on an example angular distribution, for $600 < m_{jj} \leq 800$ GeV, of the removal of the masked modules. An average rate reduction of 10 – 15% is seen, affecting the shape⁵ of the angular distribution as more events are removed at low χ . The effect is very similar in data and MC, indicating that either the impact of the overcorrection relating to the masked modules is small, or that the two masked modules included in the detector simulation dominate.

10.3 STATISTICAL ANALYSIS

10.3.1 Input

As input for the statistical analysis, the distributions obtained in data, SM and signal predictions at the integrated data luminosity, and the

⁵ Although most of the shift is removed in the normalisation, and only the shape change remains, the rate decrease reduces the statistical power of the data.

corresponding uncertainties, are used. The pure CI signal distributions, including interference, are obtained for a range of Λ with the described extrapolation method, while for QBH, a range of M_{th} is probed. The signal histograms thus obtained corresponds to the expected number of signal events at signal strength $\mu = 1$. In addition to shifting the m_{jj} scale at which the phenomenon appears, the expected signal yield decreases with m_{q^*} , M_{th} and Λ , as exemplified for CI in Fig. 51.

10.3.2 Procedure

In practice, the statistical analysis proceeds using a HistFactory [89] and RooStats [90] framework, which uses the input histograms to find the best estimate of both the parameter of interest, μ , and the nuisance parameters, given data. Expected limits, which are a measure of the sensitivity of the search to a phenomenon, are derived from testing the compatibility of the signal + SM hypothesis with the SM-only histogram, finding the 95% CL limit of μ allowed by the statistical and systematical uncertainties. The limit on m_{q^*} , M_{th} or Λ corresponds to where we can exclude the nominal signal prediction, with $\mu = 1$, at 95% CL. In the event that there is no signal template exactly corresponding to this point, an interpolation between the signal strengths of the two simulated templates straddling $\mu = 1$ is done. For observed limits, the procedure is the same, but the compatibility of signal + SM with the data is tested.

•
The best estimate: the value maximising the likelihood.

10.4 BINNING OPTIMISATION

As described in Sec. 8.3.1, the binning in χ is governed by the detector granularity. The binning in m_{jj} instead has to be optimised with the search sensitivity in mind. Here it is important to remember that we don't know what awaits us; in a broad search for new phenomena like the one described here, one can't afford to tailor the event selection and m_{jj} binning too much towards a specific signal model.

The optimisation of the m_{jj} binning followed slightly different logic in the $\sqrt{s} = 8$ and 13 TeV searches, and will be outlined separately.

10.4.1 $\sqrt{s} = 8$ TeV

For the $\sqrt{s} = 8$ TeV search, initially two angular variables were explored: χ and F_χ ,

$$F_\chi(m_{jj}) = \frac{N_{|y^*| < 0.6}(m_{jj})}{N_{|y^*| < 1.7}(m_{jj})}, \quad (50)$$

where the m_{jj} binning of F_χ followed the dijet mass spectrum binning, in turn optimised with respect to the detector m_{jj} resolution. This distribution is thus finely binned in m_{jj} but coarsely in y^* (or, correspondingly, χ), which yields an enhanced sensitivity to resonant phenomena, but still follows the same logic of shape comparison and sensitivity to isotropic phenomena: an increase at low χ would give an increase in F_χ too. Thus the angular distributions in χ were made coarsely binned in m_{jj} , using the fine binning in χ (as described in Sec. 8.3.1), for complementarity. Ultimately, the analysis of F_χ was not pursued, from a lack of a statistical modelling compatible with the statistics tools used. We will come back to this later.

The analysis of $\sqrt{s} = 8$ data was done in two steps: first a partial data set, consisting of one quarter of the collected events and restricting the m_{jj} range to below 2 TeV, was used for analysis optimisation. This m_{jj} range defined the *control region*, while $m_{jj} \geq 2$ TeV was the “blinded” *signal region*. The signal region was split into three subranges in m_{jj} , with boundaries at 2.6 and 3.2 TeV. The $3.2 \leq m_{jj} < 8.0$ TeV range had shown an optimal sensitivity to CI signal, assessed through the expected limits with varied lower boundaries. Given its non-resonant behaviour, the CI signal increases with m_{jj} once it turns on, and optimal sensitivity in the highest m_{jj} region is expected. The remaining two regions were used for a separate assessment of the compatibility of data and SM prediction in each region (testing the null hypothesis), but not for obtaining limits on Λ . Once all analysis choices were settled, based on good agreement between data and MC

in the control region, all data were included, and a statistical analysis was performed in the signal region to establish their compatibility with the SM prediction and the benchmark models.

10.4.2 $\sqrt{s} = 13$ TeV

The analysis of $\sqrt{s} = 13$ TeV data was designed and all choices frozen before 2015 data taking started. This approach avoided the need for a control region and a blinded signal region, enabling immediate data analysis for the sake of speed. The optimal m_{jj} binning, however, depends on the size of the data set used, which was not known beforehand. Simulation studies showed that expected reach in m_{jj} was up to ~ 7 TeV with 10 fb^{-1} . Furthermore, with an expected integrated luminosity in the range $1 - 10 \text{ fb}^{-1}$, and with systematic uncertainties of the same size as in the $\sqrt{s} = 8$ TeV analysis, the size of systematic and statistical uncertainty would stay comparable in the last two bins using a bin width of ~ 300 GeV, except for at the highest m_{jj} where wider ranges were needed. Thus a preliminary narrow binning was chosen, with 300 GeV wide bins starting at the lower m_{jj} threshold of 2.5 TeV, but wider towards high m_{jj} . These were used in all derivations of systematic uncertainties and corrections.

The exact binning can be seen in for instance Fig. 56, showing the EW corrections.

Sensitivity studies showed that for a range of integrated luminosities up to 1 fb^{-1} , the best sensitivity to CI was obtained in the region from 3.4 TeV up. For the first result at $\sqrt{s} = 13$ TeV, only 0.80 pb^{-1} of data was used, making this the final bin used. For the analysis of the full 2015 data set, a statistical analysis using a simultaneous fit of 600 GeV wide bins starting at 3.4 TeV had been shown to give clear sensitivity improvements.

When correlating uncertainties across regions of different statistical power, such as low- m_{jj} regions where the statistical uncertainty is low and the large-uncertainty regions at high m_{jj} , one needs to verify that nuisance parameters don't get overconstrained by the region of high statistical power. That said, the regions with high statistical power can also provide information about the "true" value of a nuisance parameter, since the central value is optimised — *profiled* — in the fit. For

instance, it was seen in Fig. 23a that the region of highest jet p_T suffers from large statistical uncertainty, which inflates the JES uncertainty for these jets, starting after $p_T \sim 2$ TeV. A first measurement of this region of phase space can be used to constrain this nuisance parameter by comparing to the actual data, instead of relying on the JES uncertainty previously derived from a smaller population of jets at these energies. It was verified that correlating across regions of different statistical power did not introduce any overconstraints on nuisance parameters, but did move some of their central values slightly, in accordance with the direction of better agreement between data and MC.

The combined fit gives increased sensitivity to resonant phenomena, since it takes the evolution of signal with m_{jj} into account. Sensitivity to narrow resonances benefits from narrower m_{jj} ranges, since the signal is less washed out by the SM background. The sensitivity to resonant signals is exemplified using a q^* signal. Examples of results from a combined fit across the m_{jj} regions in the range 2.5 – 5.4 TeV is shown in Fig. 59.

Details in Appendix A.

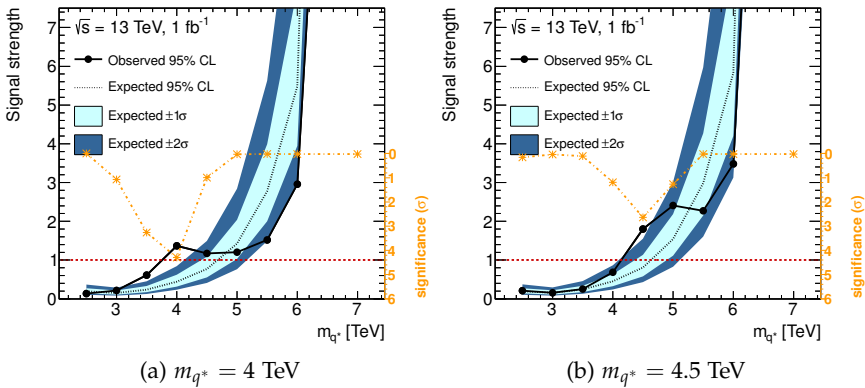


Figure 59: Sensitivity to injected q^* signal at (a) $m_{q^*} = 4$ TeV and (b) $m_{q^*} = 4.5$ TeV, as function of signal hypothesis m_{q^*} . The crossing of the expected limit and the line at signal strength $\mu = 1$ indicates the sensitivity in m_{q^*} of the experiment. The corresponding null hypothesis significance is indicated on the right-hand axis.

This type of figure encodes a lot of information. First of all, the left vertical axis, representing the signal strength, is the factor the signal needs to be multiplied by for the experiment to be able to exclude it at 95% confidence level. The horizontal axis denotes the m_{q^*} of the signal hypothesis probed in each CL_s fit. The resulting expected and observed upper limit on signal strength from each fit, along with 1σ and 2σ confidence level bands, are combined into this figure. The expected and observed lower limit on m_{q^*} is found where the corresponding lines cross the line at signal strength $\mu = 1$, where the expected limit is interpreted as the sensitivity of the experiment. Here, the sensitivity depends on the m_{jj} range used in the combined fit. Since this range stops at 5.4 TeV in this example, and the signal is narrow in m_{jj} , there is not much signal from higher m_{q^*} that makes it into this range, and the experiment reach in m_{q^*} stops at around 5 TeV. However, extending the m_{jj} fit reach would not improve the sensitivity much in this example, as the integrated luminosity also plays a role: at 1 fb^{-1} , neither the SM nor the signal are expected to produce enough events in the higher m_{jj} range, and including this range would simply contribute empty histograms.

The observed limit in this figure is obtained using pseudo-data drawn from the SM prediction with *injected* signal from the prediction for $m_{q^*} = 4 \text{ TeV}$ in Fig. 59a and $m_{q^*} = 4.5 \text{ TeV}$ in Fig. 59b. These two values were chosen as they are close to the lower limits on m_{q^*} obtained using Run1 data, and close to the expected limits at 1 fb^{-1} . The observed limits visibly deviate from the expected at precisely these values, meaning that only a larger signal than the nominal prediction for these values of m_{q^*} can be excluded — the nominal signal prediction is compatible with the observed distributions (here, by construction). Furthermore, this injected signal resembles the shape of the signal hypothesis at neighbouring m_{q^*} , giving a wider bump rather than a spike at the precise signal injection value. Finally, the null hypothesis p -value is represented in terms of significance⁶

Signal injection: add the signal prediction to the SM prediction.

Remember: the m_{jj} binning is 300 GeV

wide. ⁶ The p -value relates to this σ via the standard deviations of a Gaussian distribution: the p value is the probability to obtain a value $q \geq q_0$ where q_0 is the observed value, when sampling a Gaussian distribution $G(\mu, \sigma)$. The location of q_0 in G is indicated by the number of σ .

by the orange line, with values to be read off the right-hand axis. In particle physics, a 3σ significance is often reported in terms of “evidence” of a signal, while 5σ is an “observation”. In this particular example, the experiment would be able to claim discovery of q^* signal at $m_{q^*} = 4$ TeV.

10.5 SYSTEMATIC UNCERTAINTIES

This section describes how the systematic uncertainties, entering as nuisance parameters in the statistical analysis of data, are obtained. The main principle is to find a baseline $(\vartheta, \sigma_\vartheta)$ for the construction of the Gaussian likelihood for each nuisance parameter, for the number of interest in the analysis (such as the number of entries in a bin). While ϑ is the value of the nominal prediction, the width of the Gaussian is given by the best knowledge of the impact of a parameter on some variable of interest, for instance the N_{PV} dependence of jet p_T , in the assessment of a correction or calibration. It is typically derived from the degree of data/MC disagreement, or MC non-closure, or in the worst case, by the statistical uncertainty in the assessment of the method. Let’s call this width σ_{CP} .⁷ The method to find σ_ϑ is to vary each parameter by $\pm 1\sigma_{CP}$ to find the resulting variation in the distribution of interest. Since the angular distribution predictions are normalised to match the data integral, so are the varied predictions. This means that only the impact on the shape of the distribution enters. This is advantageous since for instance the absolute cross section prediction of MC can depend on non-perturbative parameters that need to be tuned, while it’s in the nature of this type of high- p_T regime search at the energy frontier that it hasn’t been explored much before.

The experimental uncertainties are the JES and luminosity uncertainty, while the theoretical uncertainties relate to the choice of PDF, renormalisation and factorisation scale, MC tuning and generator choice. For the PDF and scale choice uncertainties, NLOJET++ is used together with APPLgrid [91], which lays out a phase space grid for



In practice, this is not the wording that would be used, but something more model-agnostic.



Closure in a MC-derived correction means independence on the used variables by construction.



The systematic variations are a what-if-scenario, implying that they need to be treated in the same manner as the nominal prediction.

⁷ The calibrations etc are worked out in Combined Performance groups.

reweighting an input NLO cross section according to different PDF sets and scale settings.

10.5.1 JES

For a general jet measurement, the jet energy scale uncertainty introduced in Sec. 6.3 tends to be the dominant uncertainty, and much work goes into reducing it (the reduced pile-up uncertainty from the introduction of the method described in Chapter 7 is one example). The measured angular difference between two jets is not strongly affected by the energy scale, since the jet axis doesn't change. However, the binning in m_{jj} introduces migrations as the p_T shifts (cf. Eqn. 41).

The first 2015 data JES uncertainty was based on the calibration for 2012 data taking, with a cross-calibration term for the changed conditions (mainly changed bunch spacing and material change due to detector upgrade) [59]. As can be seen in Fig. 23a, the cross calibration term becomes negligible at $p_T \sim 300$ GeV.

Figure 60 shows the impact on the angular distribution in different m_{jj} regions from varying the JES according to a reduced nuisance parameter (NP) set, diagonalising the 67 components of the JES into three orthogonal NPs [92]. This is done in three different scenarios, expected to be equivalent, unless the phase space of the analysis is sensitive to correlations between the underlying components. The analysis results were indeed found to independent on the choice of reduction scenario.

10.5 SYSTEMATIC UNCERTAINTIES

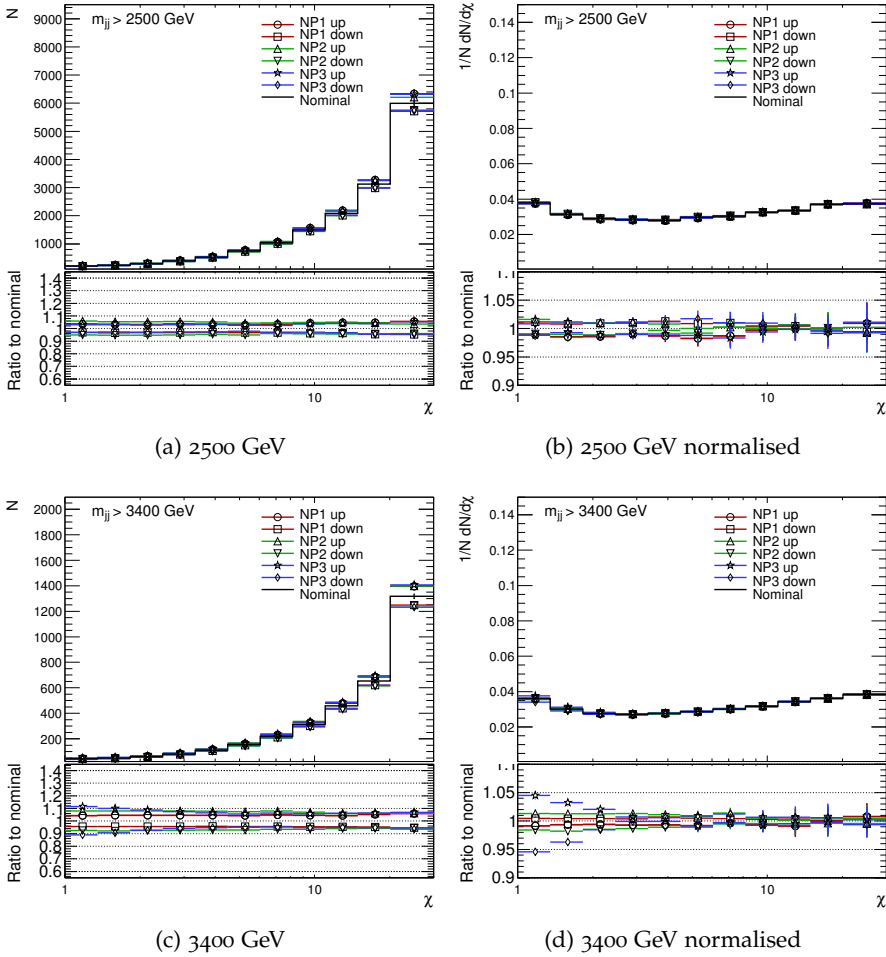


Figure 60: JES uncertainty breakdown into reduced nuisance parameters 1–3, for (a), (b) $2500 \leq m_{jj} < 2800$ GeV and (c), (d) $3400 \leq m_{jj} < 3700$ GeV. Figures (a) and (c) show unnormalised N vs χ distributions, and (b) and (d) show normalised angular distributions. Note the different vertical scales on the ratio panels.

Comparing Figs. 60a–(d), what differs is that Fig. 60a and (c) show the N vs χ distribution, while Fig. 60b and (d) show the normalised differential angular distribution. Differentiating does not affect the ratio, while normalisation does, as every distribution is normalised to unit area. Note that the vertical scales differ between the two versions. It is clear that the final uncertainty is reduced in the normalisation, which only preserves shape differences. The NP3 term dominates in Fig. 60d, and this holds also at higher m_{jj} . This is the NP set which contains the high- p_T term of the uncertainty, which as we have seen starts to become large at $p_T \sim 2$ TeV and is flat from there on. Here we see that an uncertainty on the jet p_T translates into an uncertainty on χ , owing to m_{jj} migrations.

$$\sqrt{s} = 8 \text{ TeV}$$


In the 2012 JES, a reduced parameter scheme of 14 parameters was used. In this analysis, the impact on the shape of the angular distributions was captured by the η intercalibration uncertainty term. The remaining 13 parameters were thus combined in a single term, and the two were used as independent systematic uncertainties.

10.5.2 Luminosity uncertainty

A luminosity uncertainty of $\pm 9\%$ is taken into account for the QBH and q^* signal, used in the analysis of $\sqrt{s} = 13$ TeV data only. For the SM and CI prediction, the normalisation to the data integral removes the uncertainty on the integrated luminosity.

10.5.3 PDF uncertainty

The PDF choice mainly affects the cross section seen in a given m_{jj} region. Thus, even though the PDF uncertainties are generally large at the largest x , probed by high- p_T jets, the effect on the normalised angular distributions is very small. This is illustrated in Fig. 61, which shows both cases. The uncertainty is calculated using inter- and intra-

 The details of the PDF uncertainty calculation are given in Appendix A.

variations from three different PDF sets, where one is the baseline PDF used in the SM prediction.

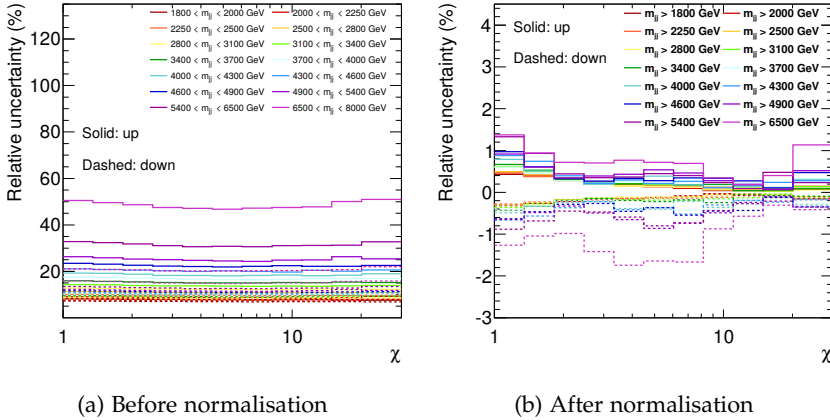


Figure 61: Relative PDF uncertainties in (a) unnormalised and (b) normalised angular distributions, for the analysis of $\sqrt{s} = 13$ TeV data.

10.5.4 Scale uncertainty

The scales for renormalisation and factorisation are typically set at Q , which is not exactly experimentally measured. As a proxy, $\mu_R = \mu_F = \frac{p_T^{\text{lead}} + p_T^{\text{sublead}}}{2}$ is chosen. To assess the uncertainty from this choice, μ_R and μ_F are independently varied up and down by a factor of 2 (which is an arbitrary but conventional choice). The resulting distributions are exemplified for one region of m_{jj} in Fig. 62.

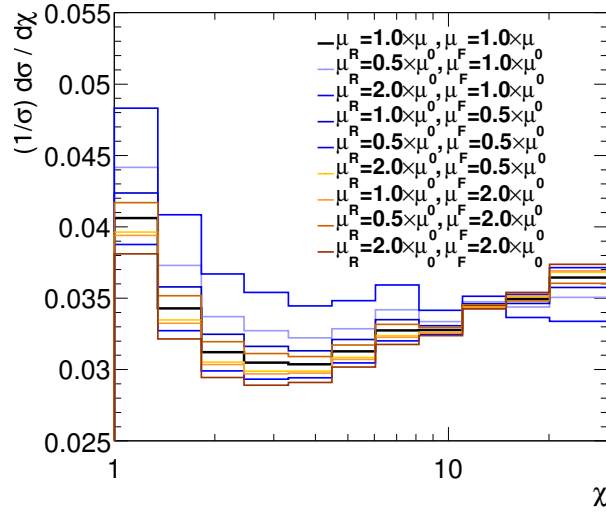
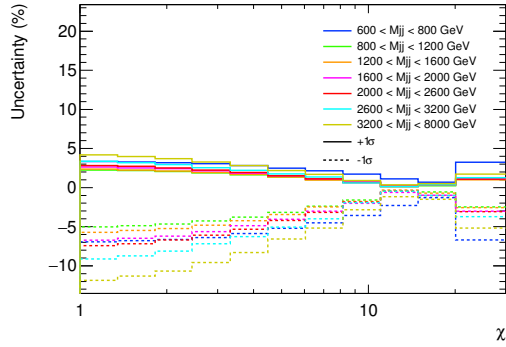


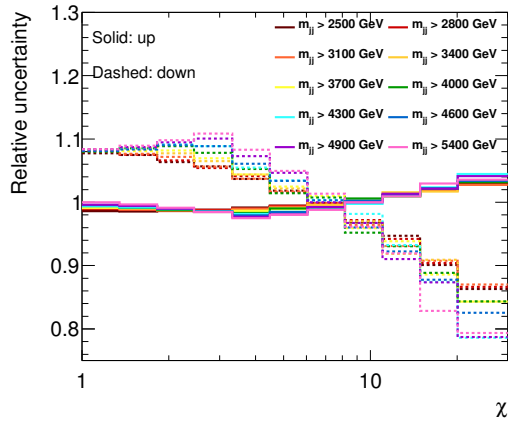
Figure 62: Angular distributions with scale variations, for $3700 \leq m_{jj} < 4000$ GeV, evaluated at $\sqrt{s} = 13$ TeV.

In the analysis of $\sqrt{s} = 8$ TeV data, the 1σ uncertainty on the scale choice was taken as the RMS of the distributions thus obtained, for each m_{jj} region. In the analysis of 13 TeV data, the 1σ uncertainty was instead taken as the envelope of the resulting distributions with anti-variations excluded. In both cases, the final uncertainty is assessed on distributions normalised as a last step. Figure 63 shows the resulting scale uncertainty from the two approaches. The shape differs, but also the magnitude, with the procedure used in the analysis of $\sqrt{s} = 13$ TeV data (Fig. 63b) giving larger uncertainty.

10.5 SYSTEMATIC UNCERTAINTIES



(a) $\sqrt{s} = 8$ TeV



(b) $\sqrt{s} = 13$ TeV

Figure 63: Relative scale uncertainties in normalised angular distributions, for several m_{jj} regions, for (a) $\sqrt{s} = 8$ TeV and (b) $\sqrt{s} = 13$ TeV.

10.5.5 Tune uncertainty

The uncertainty due to the tuning choice of parameters governing non-perturbative as well as perturbative processes is assessed by variations.

The non-perturbative processes are not expected to affect high- p_T jets very much.

8 TeV

No clear evidence of improved tune settings were seen in the studies outlined in Sec. 9.1. Instead the envelope of the distributions was used to calculate an asymmetric tune uncertainty. Data and MC agreed within this uncertainty at low m_{jj} . At ~ 2 TeV, the different tunes all converged to the baseline prediction, modulo statistical fluctuations, which were non-negligible.

Similarly, a generator uncertainty was derived by comparing the prediction of POWHEG showered with PYTHIA8.175 to PYTHIA8 brought to NLO with K -factors, and a showering uncertainty was obtained from the comparison of POWHEG+PYTHIA8 to POWHEG showered with HERWIG+JIMMY[93–96], [97], v6.520.2 and v4.31. These were both dominated by statistical uncertainties.

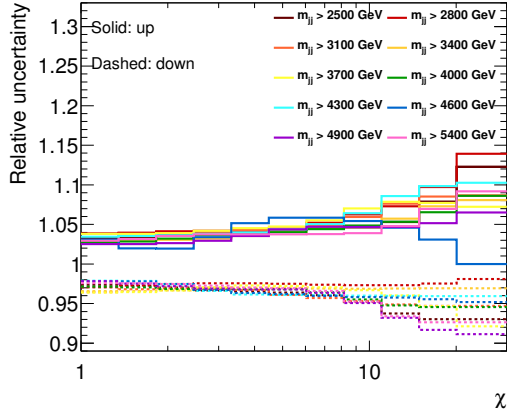
13 TeV

A central, large-statistics production of particle-level MC samples with Professor eigentune variations [76, 98] was used to obtain the envelopes of the varied distributions. The same smoothing procedure used for the K -factors was applied to remove an otherwise large impact of statistical uncertainty from points insignificantly deviating from the nominal prediction. The resulting tune uncertainty is shown before and after normalisation in Fig. 64. While the tune choice does affect the overall cross section, it does not give a strong angular shape dependence in the normalised distributions and is negligible compared to the JES and scale uncertainty.

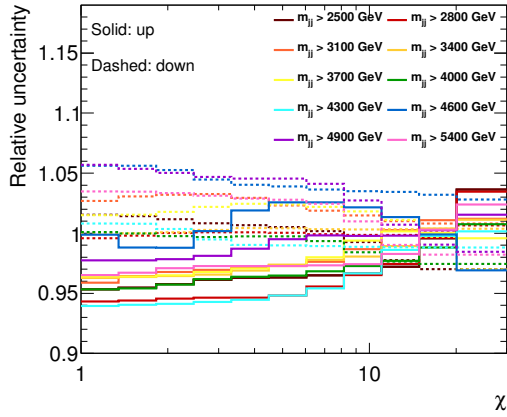


Shape effects are, as we have seen, a sign of both angular shifts and m_{jj} migrations.

10.5 SYSTEMATIC UNCERTAINTIES



(a) Before normalisation



(b) After normalisation

Figure 64: Relative tune uncertainties in the $\sqrt{s} = 13$ TeV angular distributions, for several m_{jj} regions, (a) before and (b) after normalisation.

10.6 TOTAL UNCERTAINTY

Examples of the total uncertainty in the regions used for statistical analysis, and a breakdown into the above components is shown below. Figure 65 shows all the evaluated components in the $\sqrt{s} = 8$ TeV analysis, for $m_{jj} > 3200$ GeV. Upward and downward variations are shown as solid and dashed lines, respectively.⁸ It is clear that the JES and scale uncertainties dominate. The PDF and K -factor uncertainties are hardly discernible.

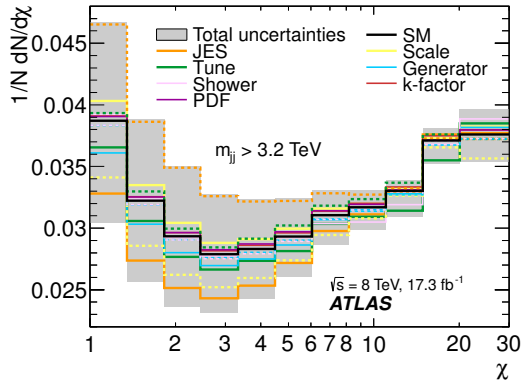
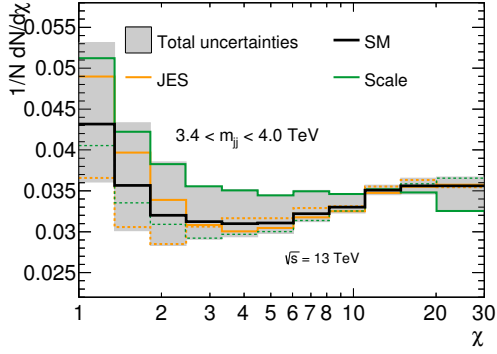


Figure 65: Breakdown of the total uncertainty in the $\sqrt{s} = 8$ TeV analysis, for the limit setting region $m_{jj} > 3200$ GeV. Upward and downward variations are drawn with solid and dashed lines, respectively.

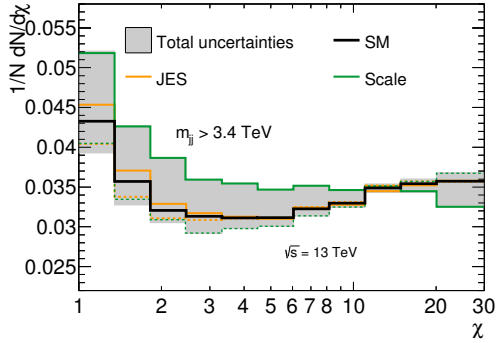
For the $\sqrt{s} = 13$ TeV analysis in Figs. 66a – 66c, only the two major ones are shown. The scale uncertainty is large at $m_{jj} = 3400$ GeV, while for $m_{jj} > 5400$ GeV, the JES uncertainty is much larger. The JES uncertainty is more symmetric than the scale uncertainty. Furthermore, at high m_{jj} it is flatter in χ , which is attributed to the high- p_T term of the uncertainty: this is flat in p_T from 2 TeV up, and starts making its way in from the low χ region, following Eqn. 41.

⁸ The generator and shower uncertainties are one-sided.

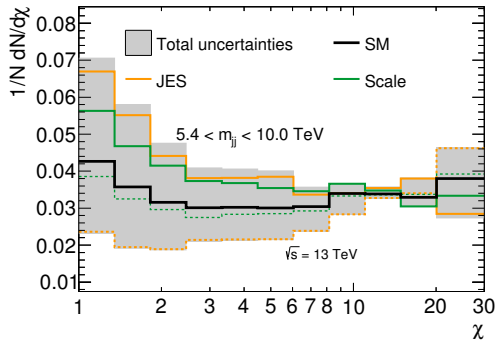
10.6 TOTAL UNCERTAINTY



(a) $3400 \leq m_{jj} < 4000$ GeV



(b) $m_{jj} > 3400$ GeV



(c) $m_{jj} > 5400$ GeV

Figure 66: Breakdown of the total uncertainty in the $\sqrt{s} = 13$ TeV analysis, for (a) $3400 \leq m_{jj} < 4000$ GeV, (a) $m_{jj} > 3400$ GeV and (c) $m_{jj} > 5400$ GeV. Upward and downward variations are drawn with solid and dashed lines, respectively.

RESULTS

In this chapter, we have finally reached the goal: all the pieces are in place to have a look at and interpret the physics message in the dijet angular distributions. Here I show the $\sqrt{s} = 8$ and 13 TeV results, discuss and compare them, and discuss some possible paths forward.

11.1 ANGULAR AND MASS DISTRIBUTIONS

11.1.1 8 TeV

Figure 67 shows the normalised angular distributions in the $\sqrt{s} = 8$ TeV data, overlaid with the MC SM prediction with and without EW corrections applied. Theoretical uncertainties are shown as a shaded band. Experimental uncertainties (meaning, the JES uncertainty) are shown as a dash on the vertical error bars, which represent the statistical and experimental uncertainties added in quadrature. The predicted CI signal for two combinations of Λ and η_{LL} is also shown.

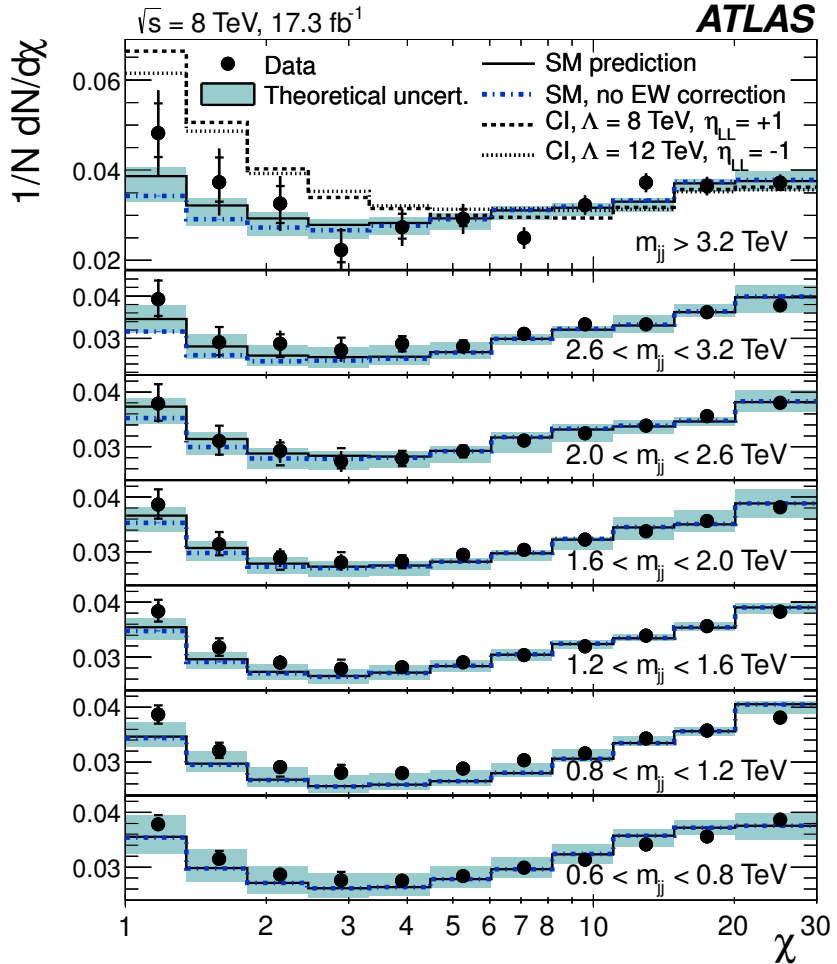


Figure 67: Normalised angular distributions in the $\sqrt{s} = 8$ TeV data, overlaid with the MC prediction with and without EW corrections applied. Theoretical uncertainties are shown as a shaded band. Experimental uncertainties are shown as a dash on the vertical error bars, which represent the statistical and experimental uncertainties added in quadrature. The predicted CI signal for two choices of Λ and η_{LL} is also shown.

It is clear that the EW corrections, used here for the first time in an ATLAS dijet search, improve the data/MC agreement significantly in the region of low χ , high m_{jj} . This is precisely the region where one would naïvely expect new phenomena to occur first; for instance this is the most sensitive region to the CI signal. This correction does bring a significant improvement also to the limits on new phenomena in the absence of significant deviations from the SM. Another clear feature is the data/MC discrepancy in the low m_{jj} region, covered by the tune uncertainty, and closing in the region where all tunes converge (around 2 TeV). The theoretical uncertainties dominate at low m_{jj} ; the JES uncertainty grows with m_{jj} , as does the statistical uncertainty, which is only noticeable in the last m_{jj} window.

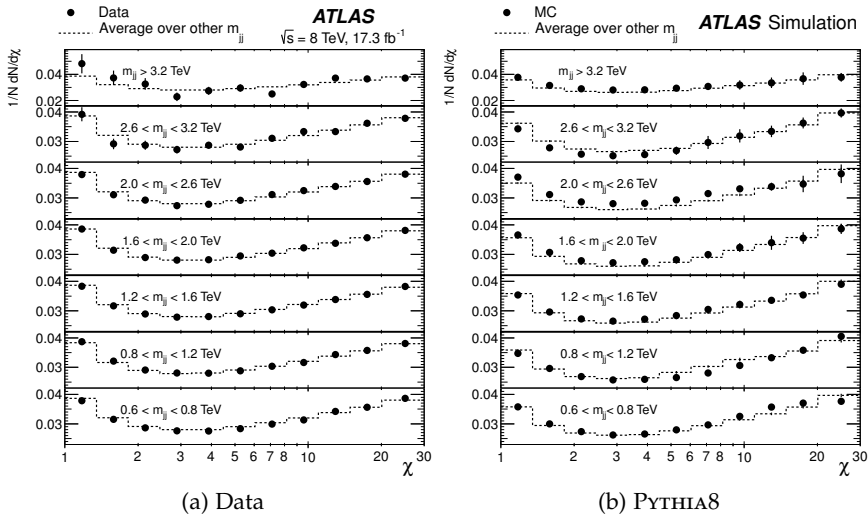


Figure 68: Comparison of the normalised angular distribution in each m_{jj} region to all the others, except the highest, in (a) data and (b) NLO QCD and EW corrected PYTHIA8.

Since all distributions are normalised to unit area, comparing the shape across m_{jj} regions is easily done. Figure 68 shows a comparison of the distribution in each m_{jj} region to the weighted average over all

the rest. This way of averaging means that the lowest m_{jj} distribution will dominate the comparison. It is striking in Fig. 68a that all m_{jj} regions in data except the last one agree very well with the average, meaning, that this dominance from the low m_{jj} doesn't matter much. In MC, shown in Fig. 68b, there are larger variations, but no general trend.¹ This variation is attributed to statistical fluctuations.

The impact of the corrections on the shape can also be visualised in the F_χ distribution. Neither final corrections nor systematic uncertainties were derived for this distribution. Since F_χ corresponds to the ratio of the number of events in the first four bins of the angular distributions to the total number of events, it can be recovered from the angular distributions, albeit in the coarse m_{jj} binning.

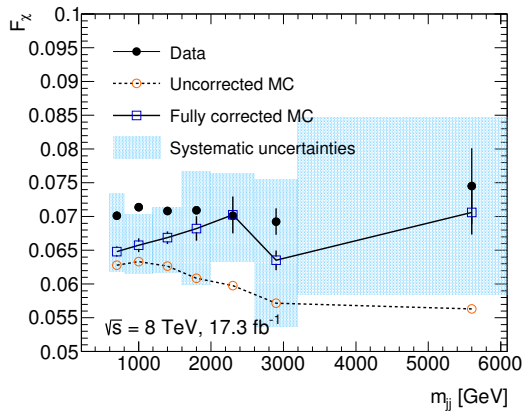


Figure 69: F_χ as derived from the angular distributions. Comparison of $\sqrt{s} = 8$ TeV data, pure PYTHIA8 and fully corrected PYTHIA8.

Figure 69 shows F_χ in data and MC, where both the pure PYTHIA8 prediction and the fully corrected SM prediction is shown. Total systematic uncertainties are included. It was verified for $\sqrt{s} = 8$ TeV data and uncorrected MC that the original F_χ finely binned in m_{jj} gives the same result as the one derived from the angular distributions.

¹ Without EW corrections, there is a clear systematic trend with m_{jj} in the shapes.

Since F_χ and the angular distributions carry the same information, Fig. 69 again shows that there is a difference in the shape of the angular distributions in data and MC, which decreases as m_{jj} increases. This is the region where the K - and κ -factors play the largest role. At low m_{jj} , as we have seen in the angular distributions, the uncertainty due to the choice of tune closes the gap between data and SM prediction. The high degree of m_{jj} independence in data is again obvious.

The dijet mass distribution is shown in Fig. 70.

In the uncorrected MC, the gap instead increases, which raised concerns about the ability to model F_χ in MC.

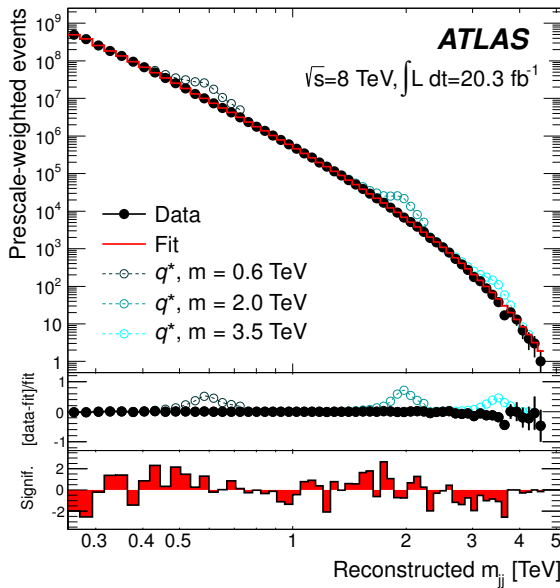


Figure 70: Dijet mass distribution in the $\sqrt{s} = 8$ TeV data, compared to the fit (red line) in the bottom panel, with signal prediction for three m_{q^*} overlaid.

In addition to the data, the fit obtained with a smooth functional form,

$$f(x) = p_1(1-x)^{p_2}x^{p_3+p_4\ln x+p_5(\ln x)^2}, \quad (51)$$

is shown. Here $x \equiv m_{jj}/\sqrt{s}$, the p_i are fit parameters and p_5 was set to zero. The ratio panel in the middle shows the relative difference

to the fit value in each bin, as well as the expected deviation in the presence of three different q^* signal hypotheses. The bottom panel shows the bin-by-bin significance in the comparison of the data and the fit, taking only statistical uncertainties into account.

The fit shows large oscillations, which are not present in a fit allowing a non-zero fifth parameter. The fit function choice was based on a blinded analysis, using a partial dataset.² With the larger statistical power of the full data set, an additional parameter would have been necessary to accommodate the level of detail resolved in the spectrum.

For the 2015 iteration of the analysis, a smaller data set was expected, covering a smaller range in m_{jj} owing to the use of only un-prescaled triggers. Thus, a lower-order parameterisation was chosen as a starting point, with the fourth and fifth parameter initially set to zero. A pre-defined figure of merit, based on hypothesis testing, was implemented. It uses the p -value from a log-likelihood ratio, the lower-order parameterisation being the null hypothesis, and the higher-order parameterisation being the alternate, to find the fit preferred by the data. If the p -value drops below 0.05 as more integrated luminosity is added, the lower-order parameterisation is discarded. This procedure automates the inclusion of higher parameters if needed as the integrated luminosity increases, removing the need for a blinded analysis, and enabling the flexibility missing in the analysis of $\sqrt{s} = 8$ TeV data.

11.1.2 13 TeV

Figure 71 shows normalised angular distributions in the $\sqrt{s} = 13$ TeV data, overlaid with the fully corrected MC prediction. Theoretical and total uncertainties are shown as lighter and darker shaded bands, while the vertical error bars represent the statistical uncertainty. The predicted CI signal for two choices of Λ and η_{LL} is also shown, along with a QBH prediction. In particular, the signal is shown for all the m_{jj} regions used in the combined fit, demonstrating the additional power in taking the signal evolution in m_{jj} into account. This will be discussed in more detail in Sec. 11.2.2.

² Also here, 1/4 of the data set was used for analysis optimisation.

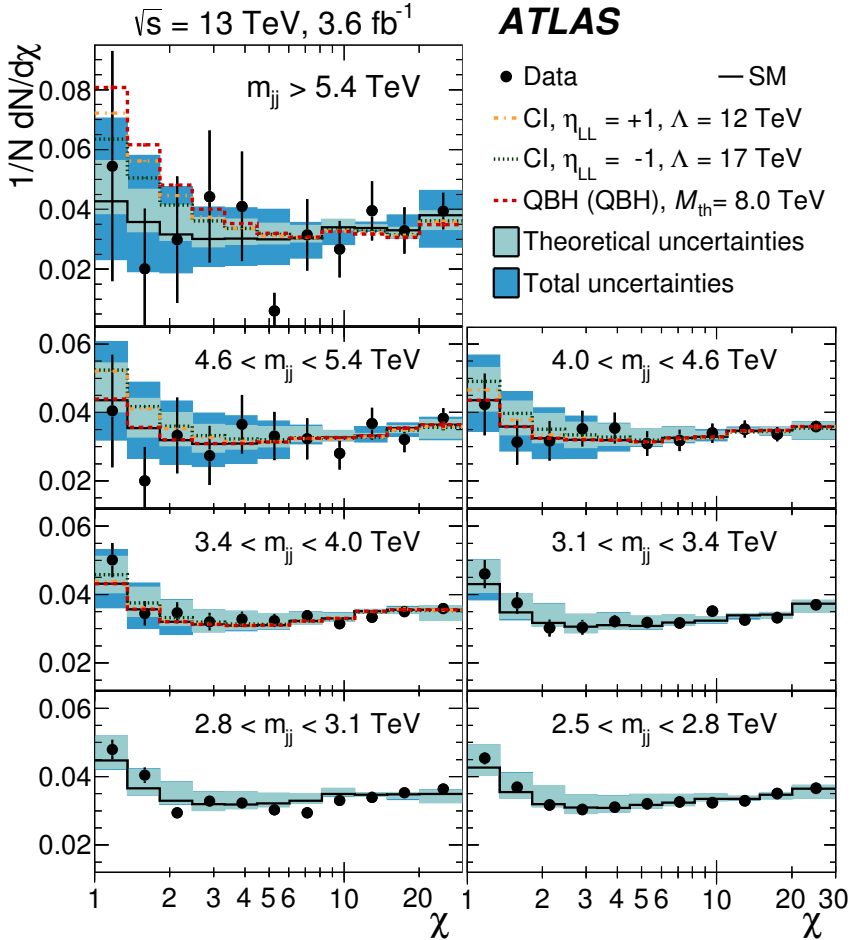


Figure 71: Normalised angular distributions in the $\sqrt{s} = 13 \text{ TeV}$ data, overlaid with the fully corrected MC prediction. Theoretical and total uncertainties are shown as lighter and darker shaded bands, while the vertical error bars represent the statistical uncertainty. The predicted CI signal for two choices of Λ and η_{LL} is also shown, along with a QBH prediction.

Once again, m_{jj} independence of the normalised angular distributions is observed. This is demonstrated for $\sqrt{s} = 13 \text{ TeV}$ in Fig. 72,

RESULTS

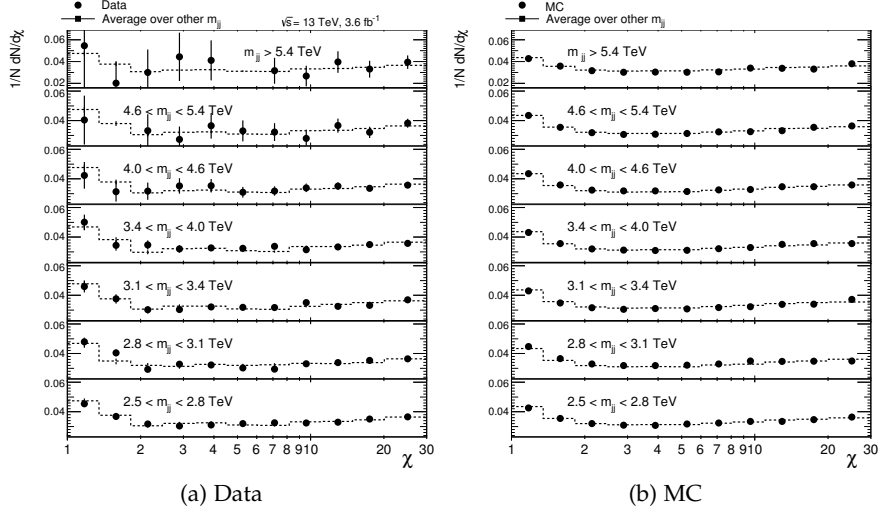


Figure 72: Comparison at $\sqrt{s} = 13$ TeV of the normalised angular distribution in each m_{jj} region to all the others, except the highest, in (a) data and (b) NLO QCD and EW corrected PYTHIA8.

obtained in the same manner as Fig. 68. The variation in MC is no longer present in Fig. 72b. This is attributed to smaller fluctuations in the K -factors due to larger samples used for their derivation. It is clear that the data and MC distributions are both internally consistent across m_{jj} . The data distributions show a small wiggle at intermediate χ not present in the MC prediction, which has a slightly flatter shape in χ than data.

The m_{jj} spectrum is shown in Fig. 73, together with the 3-parameter fit described by Eqn. 51 and overlaid signal prediction for q^* and QBH at two mass hypotheses. The q^* signal has been scaled up by a factor 3 for visibility. No higher-order parameterisation was needed to describe the data. The most discrepant range is at $m_{jj} = 1.5 - 1.6$ TeV, indicated by the two vertical lines, but no significant excess is observed. The middle panel shows the bin-by-bin significance of the deviations in the data from the fit, and the bottom panel shows the comparison

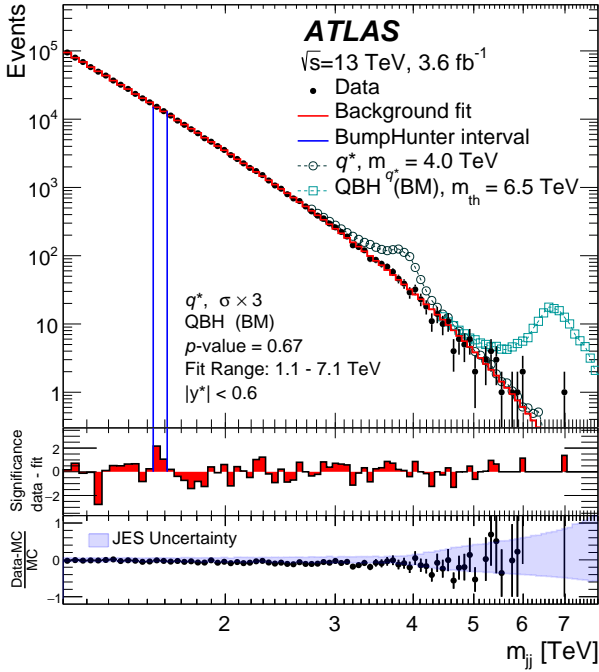


Figure 73: Dijet mass distribution in the $\sqrt{s} = 13$ TeV data, compared to the fit (red line) in the second panel, with signal prediction for three m_{q^*} overlaid. The bottom panel shows the comparison to NLO QCD and EW corrected PYTHIA8, along with the JES uncertainty.

of the data to the PYTHIA8 prediction, corrected with dedicated K - and κ -factors for the mass analysis event selection, and normalised to match the data integral. The JES uncertainty band is also drawn. Although data agree with the MC prediction within uncertainties, an overall trend can be observed where the shape in data falls off at higher m_{jj} . The trend in the agreement of data and MC points to several things. Firstly, we are probing an energy regime that has not been explored before. One should however note that we are far from the most extreme regions of the PDFs here (the dijet mass spectrum at $\sqrt{s} = 8$ TeV is closer to that regime), and it is likely that, with more data, tuning of parameters will improve. This comparison is however

a striking demonstration that for a “first search” like this one, using a data-driven SM prediction is very advantageous. Secondly, it is clear that the normalisation of MC to the data integral in each m_{jj} region removes effects like these from the angular distributions, and allows for focusing on the shape.³

11.2 STATISTICAL ANALYSIS AND LIMITS

We will now proceed to the quantitative analysis of the angular distributions and the implications for theories beyond the SM. Note that when interpreting the angular distribution figures, in particular with respect to normalisation impact or statistical analysis, one always needs to bear in mind that they are shown with a logarithmic horizontal axis and that the statistical power of the high- χ region is larger.

11.2.1 Fit control plots, analysis of $\sqrt{s} = 13$ TeV data

The constraints on a few example nuisance parameters obtained in the fit of the SM prediction to the data are shown in Fig. 74. The constraints in each m_{jj} region on the reduced JES NPs 1 and 3, as well as on the scale uncertainty, are shown as a deviation from the nominal θ and σ , where 1σ and 2σ are indicated by the green and yellow bands.

Figure 74a shows that there is not enough statistical power in this data set to constrain the JES NP1 uncertainty, since this is very small. The JES NP3, on the other hand, gets pulled and constrained in the fit across all m_{jj} , as seen in (b). This reduced NP contains the high- p_T uncertainty term, which is the dominant term in the JES uncertainty.⁴ We see that the data suggest a smaller high- p_T uncertainty. Finally,

³ An equivalent approach is to leave the normalisation as a free parameter in the fit. Once the overall normalisation is better modelled, fitting through varied nuisance parameters is even a tuning of sorts.

⁴ This has been verified in tests using the 3 other reduced NP scenarios. In all cases, the reduced NP containing the high- p_T term is dominant, and gets constrained similarly.

11.2 STATISTICAL ANALYSIS AND LIMITS

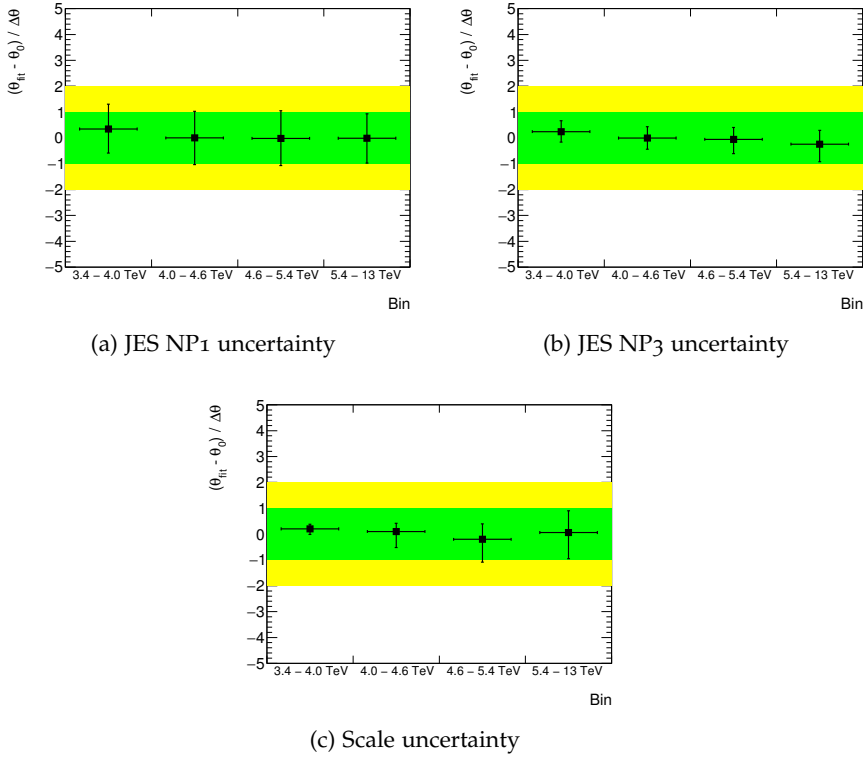


Figure 74: Constraints on nuisance parameters (a) JES, NP₁, (b) JES, NP₃ and (c) scale uncertainty, in the profile likelihood fit, shown for the different m_{jj} regions.

the scale uncertainty shown in Fig. 74c gets more constrained at lower m_{jj} , where it is clearly dominant, and less so at higher m_{jj} , where the JES uncertainty starts to dominate (cf. the m_{jj} evolution in Fig. 66).

To exemplify the interplay of the size of the statistical and systematic uncertainty, the shape of the scale and JES NP₃ uncertainties in the lowest and highest m_{jj} region is shown in Fig. 75. It is clear in (b) that the statistical precision in the data is not enough to constrain the scale uncertainty at high m_{jj} , while from the other three figures, one can

RESULTS

expect some constraint on the nuisance parameters from the fit to data.

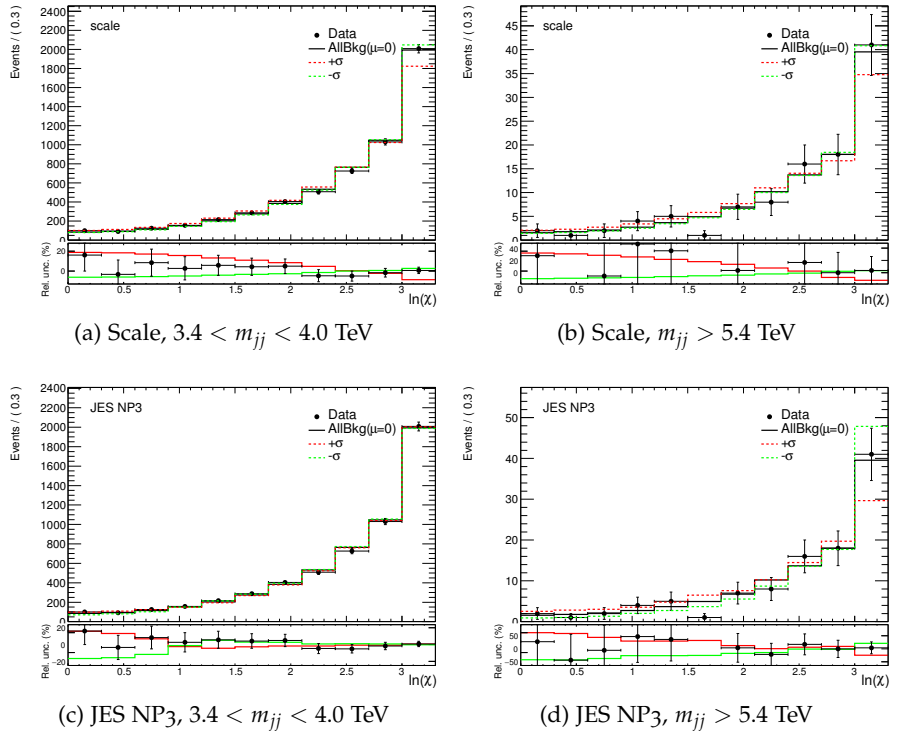


Figure 75: The uncertainty from the choice of renormalisation and factorisation scales overlaid with the data, for m_{jj} regions (a) $3.4 < m_{jj} < 4.0$ TeV and (b) $5.4 < m_{jj} < 13$ TeV, and for the same two regions for JES NP3 in (c) and (d), respectively.

11.2.2 Limits on the scale of new phenomena

The $\sqrt{s} = 8$ TeV data distributions analysed are in excellent agreement with the SM prediction in the $2.0 \leq m_{jj} < 2.6$ TeV region, with a null hypothesis p -value of 0.25 and 0.30, respectively, in the $2.6 \leq m_{jj} <$

3.2 and $m_{jj} \geq 3.2$ TeV regions. In the $\sqrt{s} = 13$ TeV data, the null hypothesis p -value is 0.35, obtained for the combined fit in the whole region $m_{jj} > 3.4$ TeV.

In the absence of significant deviations between the data and the SM predictions, limits on parameters of benchmark models can be derived from the level of agreement between data and MC, and the shape of any deviations.

$\sqrt{s} = 8$ TeV: CI Λ

The limits on Λ in the two modes of interference between CI and QCD modelled are shown in Fig. 76. The lower limits are placed at $\Lambda = 8.1$ and 12.0 TeV for destructive ($\eta_{LL} = +1$) and constructive ($\eta_{LL} = -1$) interference, respectively, the latter being the most stringent limit on constructive interference set by the end of Run1.

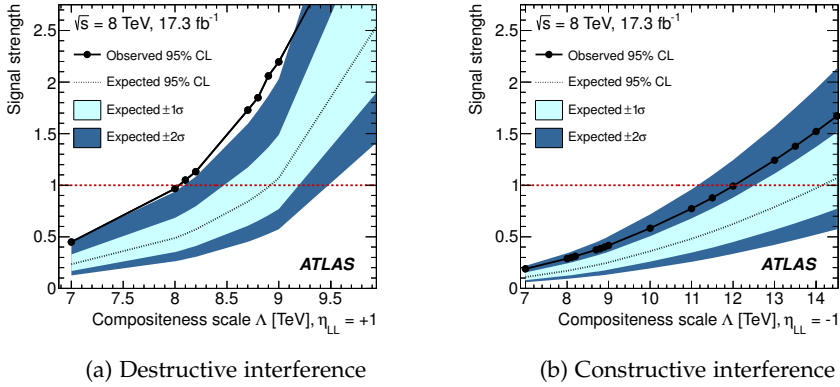


Figure 76: Lower limits derived from the $\sqrt{s} = 8$ TeV data analysis on Λ with (a) destructive ($\eta_{LL} = +1$) and (b) constructive ($\eta_{LL} = -1$) interference with QCD.

Since only one m_{jj} region is used, the observed limit is given by comparing one and the same shape in data to the shapes from adding in signal at varied signal strength. While the expected limit is given by systematic and expected statistical uncertainties only, the observed

See Fig. 67, the $m_{jj} > 3.2$ TeV region.

limit is based on the actual outcome in data. Data show an insignificant upward deviation at low χ in the used m_{jj} region, resulting in weaker observed than expected limits. The agreement between the expected and observed limits in the two cases is very different, but internally mostly consistent across Λ . Especially for constructive interference, the evolution with Λ is smooth: the resulting signal contribution quickly gets dominated by the interference term, which is proportional to $\frac{1}{\Lambda^2}$. This means that the shape between the different predictions scaled up by the needed signal strength will not vary much with Λ , and the same relation between the expected and observed limit holds. For destructive interference, at some Λ the signal manifests itself as a deficit, implying that the reach in Λ is always shorter for destructive interference. The shape of the signal is steeper in χ in the destructive case than the constructive.

In the region where QCD dominates but still overlaps with signal contributions, larger cancellation occurs.

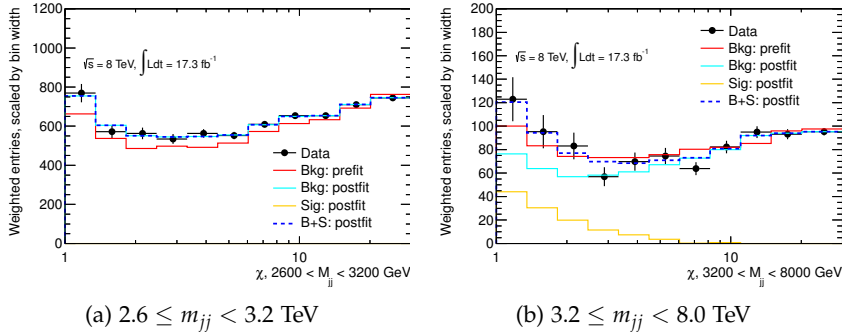


Figure 77: The SM and destructive interference CI signal prediction before and after the profile likelihood ratio fit, for (a) $2.6 \leq m_{jj} < 3.2$ TeV and (b) $3.2 \leq m_{jj} < 8.0$ TeV.

Some insight in the shape of the observed limit for destructive interference in Fig. 76a can be gained from comparing the SM and signal predictions before and after the fit to the shape observed in data, as shown in Fig. 77. We see in Fig. 77a that for a smooth discrepancy between data and SM prediction, that follows the shape of a nuisance parameter, no signal is needed to obtain a good fit. In the case of

a steeper excess, followed by a deficit as in the highest m_{jj} region of Fig. 67, a non-zero signal strength achieves a better fit than the prediction from SM only, as shown in Fig. 77b. Here, especially the steep shape in χ of the destructive interference signal can easily fill the resulting gap.

$\sqrt{s} = 13 \text{ TeV}$: CI Λ , QBH M_{th} and m_q^*

The limits expressed in $\sigma \times A \times \text{BR}$ on M_{th} in the predictions of BlackMax and QBH are shown in Fig. 78a. The sensitivity to QBH of angular distributions is, somewhat surprisingly, comparable to the sensitivity in the mass distribution, which has much smaller systematic uncertainties. Given the coarse binning, especially in the higher M_{th} region probed by these data, it is this signal's large cross section that makes it discernible in the angular distributions.

The limits on CI Λ are shown in Fig. 78b, with the same symbol conventions as before, but denoting signal strength with σ/σ_{th} , as a fraction of the theoretical cross section prediction. In the destructive signal case, there is an evolution in the agreement between observed and expected limit for different Λ , while for constructive interference there is a constant shift. At low Λ the interference term matters less, and the two signal shapes are more similar than at higher Λ . On top of the impact of the shape difference in a single m_{jj} region as described above, the combined fit introduces sensitivity to the evolution in m_{jj} , which is also different in the two interference modes, as seen in Fig. 71. Destructive interference CI grows more rapidly with m_{jj} than the constructive one: while destructive CI at the observed limit has zero signal at lower m_{jj} (3.4 TeV), and constructive is non-zero, the destructive interference signal is larger at high m_{jj} (5.4 TeV) than the constructive interference signal at the observed limit. This is not too surprising: when there is much QCD, destructive and constructive interference will result in less/more signal respectively, while as QCD dies off, the interference term makes less difference. Thus, the combined fit retains more information than the single bin



The highest m_{jj} region starts from 5.4 TeV while an 8 TeV QBH signal peaks at just above 8 TeV.

RESULTS

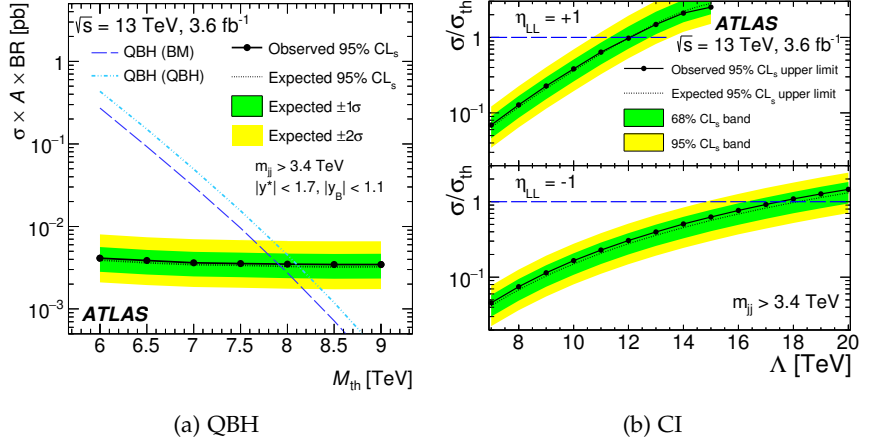


Figure 78: Lower limits on the scale of new phenomena derived from the $\sqrt{s} = 13 \text{ TeV}$ data analysis: (a) on QBH M_{th} as generated by the QBH (QBH) and BlackMax (BM) generators and (b) limits on CI Λ with destructive ($\eta_{LL} = +1$) and constructive ($\eta_{LL} = -1$) interference with QCD.

fit.⁵ This is also seen from the fact that the signal predictions in the highest m_{jj} region of Fig. 67 are more similar than in Fig. 71, despite the fact that all of them illustrate the signal prediction at the observed limit. Finally, the shift in the observed destructive interference limit from being weaker to becoming stronger than the expected limit, as Λ grows, is a sign that we are soon entering the regime where the net effect of signal and destructive interference is a deficit.

For completeness, the limits obtained on m_{q^*} from the angular distributions are also shown, despite not previously having been made public. This is a narrow resonance, with an expected exclusion limit at the final integrated luminosity at $m_{q^*} = 4.9 \text{ TeV}$ in the mass distribution analysis. The region in m_{jj} populated by this signal lies within the m_{jj} regions probed in the combined bin analysis. As

⁵ The combined fit increases the reach in Λ by about 15% compared to the single-bin fit.

Fig. 79 shows, the expected limit from the angular distributions is even slightly stronger, and the observed limit at $m_{q^*} = 5.2$ TeV coincides with the result from the mass distribution.

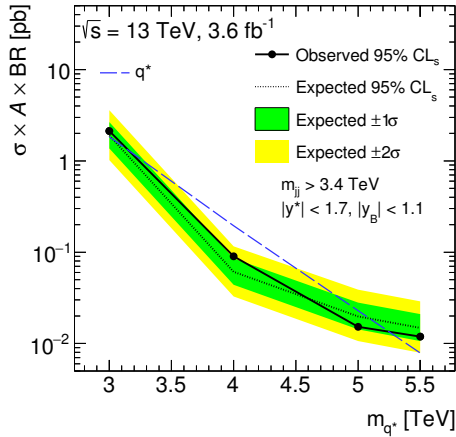


Figure 79: Lower limits on m_{q^*} derived from the angular distributions in $\sqrt{s} = 13$ TeV data.

That the angular distribution is sensitive also to resonant phenomena may prove valuable in the case of an excess in the dijet mass distribution. If this is not seen in the angular distributions, it could mean that the process producing the excess is not more isotropic than QCD, which is either an important physics message or an indication of an experimental problem.

DM recast

In addition to the CI limits, a DM recast of the limits on the CI Λ can be done, following the method outlined in Ref. [99]. Here a maximum constraint on the coupling strength between the mediator and both fermions and DM is set at $g \leq \sqrt{4\pi}$, from the assumption that the

interaction is perturbative. It is shown that, by identifying the effective CI coupling as

$$G_q \leq \frac{4\pi}{\Lambda^2} \quad (52)$$

one can obtain 2-dimensional limits on the DM effective coupling G_χ and mediator mass M_V through

$$G_\chi \leq \frac{1}{M_V} \frac{4\pi}{\Lambda}. \quad (53)$$

The resulting exclusion limits from the limits on Λ in a destructive interference scenario are shown here for the first time, for three⁶ ATLAS results in Fig. 80. The horizontal axis is truncated at 5 TeV to ensure that the EFT approach is valid also at $\sqrt{s} = 13$ TeV. The destructive interference limits are used here as they are more conservative than the constructive interference ones.

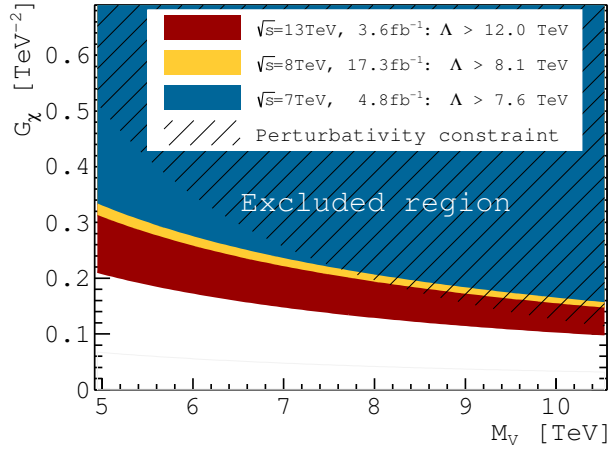


Figure 80: Upper limits on G_χ and M_V derived from the limits on CI Λ in the destructive interference scenario, obtained from angular distributions in $\sqrt{s} = 7, 8$ and 13 TeV data.

⁶ The results are obtained using the full 2011 [7], 2012 and 2015 data sets.

11.3 DISCUSSION

We have seen that the shape of the angular distributions shows a remarkable independence on m_{jj} . Given the impact on the shape from the removal of the masked modules in the $\sqrt{s} = 8$ TeV data, which lowers the low- χ region, the $\sqrt{s} = 8$ and 13 TeV angular distributions are not in agreement. However, comparing to the data distributions obtained at $\sqrt{s} = 7$ TeV (see Ref. [7])⁷, they agree very well (within uncertainties) across m_{jj} , as well as with the $\sqrt{s} = 13$ TeV result. We thus see independence on both m_{jj} and \sqrt{s} . In fact, this relates to several points that we have touched upon previously. One is the small PDF uncertainty in the angular distributions: which part of the PDF we are probing, be it with a different \sqrt{s} or different PDF distribution, does not affect the shape of the angular distribution. Following the discussion of factorisation and the argument made in Sec. 8.2, this either implies a miraculous cancellation of hard-scatter and non-perturbative effects, or, it means that the non-perturbative effects are negligible and the partonic cross section is the same: no new scales are entering, and we are probing the same matrix elements. Put differently, we see scaling in the angular distributions. Another implication of this relates to F_χ . Given its definition, it is the ratio of the integral of the first four χ bins of the angular distribution, to the total integral. Since the shape of the angular distribution is independent on m_{jj} , F_χ will correspondingly be flat in m_{jj} . This is also what was seen in the $\sqrt{s} = 8$ TeV analysis (cf. Fig. 69).

That there is no deviation from the SM prediction in the angular distributions, could mean that the new phenomena they are sensitive to do not exist at the energy scale these distributions probe, or not with large enough cross section, or not at all. The large leap in sensitivity from the increased \sqrt{s} between 2012 and 2015 enabled extending the reach in parameter space for many models with comparatively little data, but from here on, progress with the dijet final state will be slower. Apart from slowly reducing the statistical uncertainty, one can consider enhancing the sensitivity to new phenomena by retaining

⁷ In hindsight, the agreement between data and MC would likely have improved already at $\sqrt{s} = 7$ TeV if the EW corrections had been available at the time.

more information about the final state, or by employing a methodology that reduces the systematic uncertainties. The latter point will be discussed shortly. The former point relates to using single-jet or event-level observables in addition to the dijet observables of mass and angular separation explored thus far. One idea is to also measure the single-jet mass for high m_{jj} , low χ , and compare to signal-free regions. This procedure requires understanding the compatibility across phase space regions, which can be explored in MC. Furthermore, it requires a good jet mass calibration and introduces the corresponding systematic uncertainty.

11.3.1 Outlook for methodology improvements

The independence on m_{jj} strongly suggests that a data-driven SM estimate could be used, based on comparing the shapes across different m_{jj} — or even \sqrt{s} — to find the most discrepant region. In the version of F_χ , a simple implementation is a low-order polynomial fit; for instance a constant, or a first-order polynomial allowing for a small slope in the case of modulation from detector effects.⁸ Here the reasoning follows that of the dijet mass spectrum fit in the search for resonant deviations. Given the more complicated shape of a falling spectrum, it uses a higher-order parameterisation, assuming that detector effects don't introduce bumps. For F_χ , with its simpler shape, “any” smooth fit would work. However, maintaining sensitivity to non-resonant effects requires some rigidity compared to the dijet mass spectrum fit.

For the angular distributions in χ , some tests have been performed calculating the χ^2 probability for each m_{jj} region of a prediction based on the others, as drawn in the distributions in Fig. 68 and Fig. 72.

⁸ Given the successful prediction of scale invariance in the fully corrected MC prediction, albeit at a slightly different shape, assessing the impact of detector effects in MC is entirely feasible. It could be used either for correction of irregular effects, or for producing angular distributions that are fully corrected to particle-level (so-called *unfolding* of detector effects). One should note that unfolding always introduces additional uncertainties, making it preferable to search for new phenomena on detector-level distributions, retaining their statistical power.

However, this is a global assessment of the agreement over all χ , and better sensitivity could likely be obtained if only the low- χ region is allowed to contribute — agreement at high χ is guaranteed by construction!

If the MC prediction is retained and one were to pursue an analysis of F_χ , the statistical modelling problem needs to be addressed. The ratio between the m_{jj} distributions for two regions of y^* follows a binomial distribution around a small number ($F_\chi \approx 0.07$). However, the statistical framework expects integer observables that are Poisson distributed, and this is the model constructed for the angular distributions (using N vs χ with distributions normalised to have the same integral in all predictions as in data). One could construct analogous “ F_χ -like” distributions, using only two bins in χ , corresponding to the first four current bins, and the rest.⁹ This would again allow for a finer binning in m_{jj} ; the one derived from the dijet mass resolution would be a reasonable choice. Deriving corrections and systematic uncertainties in such fine binning is somewhat computationally costly, however, all uncertainties not dominated by statistical uncertainties show smooth evolution in m_{jj} , making interpolations feasible.

A data-driven SM prediction would make the angular distribution search limited by statistical rather than systematic uncertainties. Given the overwhelming jet production at a hadron collider, and the outlook of much larger LHC data sets to come, the sensitivity to deviations in the lower m_{jj} regions would be fantastic. This also means that all detector effects have to be very well understood, as small deviations would rapidly become highly significant. We have seen that the major concern would be a gradual miscalibration at high p_T , since this would cause migrations across m_{jj} regions, affecting the χ shape. We have also seen that the large uncertainty on this effect as estimated in the JES uncertainty, is not supported in data, given the m_{jj} independence of the shape, and the constraint from profiling across m_{jj} on precisely

⁹ The reason why F_χ uses the inclusive y^* in the denominator is to avoid division by zero in the case of signal-like entries only. This is not a concern in the setup proposed here and thus the “exclusive” outer region $0.6 < |y^*| < 1.7$ (or corresponding optimised choices) should be used to preserve as much shape information as possible.

RESULTS

this uncertainty. It thus seems like the ATLAS calorimeters and jet calibration are both performing very well, giving enough confidence to encourage the exploration of data-driven methods in the data sets to come.

CONCLUSIONS AND OUTLOOK

We are still in the early days of LHC operation. Since 2010, this accelerator has seen two collision energy increases: from 7 to 8 in 2012, and then to 13 TeV in 2015. This thesis describes one of the best early measurements to do: dijet searches. Best because it reaches far into new energy domains, benefits greatly from increased centre-of-mass energies, and uses the most abundant final state at a hadron collider. It can thus break new ground already with a very small data set.

The data at $\sqrt{s} = 8$ and 13 TeV were used to search for phenomena beyond the Standard Model, exploiting the fact that the QCD prediction is well known: the dijet mass spectrum is featureless, and the dijet angular distribution in QCD is dominated by small scattering angles. The search looks for an onset of more isotropic dijet production at some new scale in physics. At both energies, the distributions were well described by the SM prediction, both in terms of a smooth fit to the dijet mass spectrum and a MC prediction for the angular distributions, which are the focus of this thesis. The results were thus used to set new limits on parameters of models of phenomena beyond the Standard Model. Models for quark compositeness and strong gravity, both types introduced as solutions to the hierarchy problem, are used as benchmark models. The resulting limits on the quark compositeness scale Λ in a Contact Interaction model obtained in the 2015 data

CONCLUSIONS AND OUTLOOK

set at $\sqrt{s} = 13$ TeV are the strongest to date. A combined fit across m_{jj} regions improved the reach in Λ compared to the single-bin method used in the $\sqrt{s} = 8$ TeV data. In particular an enhanced sensitivity to resonant phenomena was achieved. Limits on the masses of both quantum black hole in an $n = 6$ ADD scenario and excited quarks were thus set with the dijet angular distributions. In addition, a dark matter interpretation of the limits obtained on the Contact Interaction Λ were shown here for the first time.

For the first time, EW corrections were included in the SM prediction of the angular distributions. These corrections are substantial and bring the MC prediction to the same m_{jj} independence of angular distributions as observed in data. With the new results in hand, this m_{jj} independence is now seen across several \sqrt{s} and m_{jj} ranges, and it is suggested to exploit this for a data-driven SM prediction in coming dijet angular distribution searches.

Part IV

APPENDIX



SIMULATION SETTINGS

A.1 QCD PREDICTION

A.1.1 8 TeV

PYTHIA8 with AU2 [75] underlying event tune and leading-order CT10 [19] PDFs.

A.1.2 13 TeV

PYTHIA8 with A14 underlying event tune [76] and leading-order NNPDF2.3 [77, 78] PDFs.

A.2 SIGNAL SIMULATION

The CI and q^* simulation use the same choice for tune and PDF as the corresponding PYTHIA8 prediction. All samples are fully simulated using GEANT4.

For QBH, the CTEQ6L1 [100, 101] PDFs are used, and it was verified that the results from so-called fast detector simulation were equivalent

SIMULATION SETTINGS

to those obtained using the full GEANT4 simulation. Thus for speed, some mass points use fast detector simulation.

A.3 *k*-FACTOR CALCULATIONS

A.3.1 PYTHIA8 LO + parton shower settings

All settings equal to the nominal PYTHIA8 prediction, but with these settings to make sure the processing is halted after parton showers:

```
pythia.readString("HardQCD:all = on");
pythia.readString("PartonLevel:FSR = on");
pythia.readString("PartonLevel:ISR = on");
pythia.readString("PartonLevel:MPI = off");
pythia.readString("SpaceShower:QCDshower = on");
pythia.readString("BeamRemnants:primordialkT = off");
pythia.readString("HadronLevel:all = off");
```

A.3.2 NLOJET++

$$\sqrt{s} = 8 \text{ TeV}$$

The settings for the NLOJET++ calculations are: PDF set o from CT10, $\alpha_s(M_Z) = 0.118$ with NLO precision in the running of α_s , and the renormalisation and factorisation scales μ_R and μ_F are both set to $p_T^{avg} = (p_T^{lead} + p_T^{sublead})/2$.

$$\sqrt{s} = 13 \text{ TeV}$$

Like for $\sqrt{s} = 8 \text{ TeV}$ running, but with PDFs from NNPDF2.3, with NLO precision in the running of α_s .

A.4 PDF UNCERTAINTY CALCULATION

The PDF uncertainty is calculated using NLOJET++ connected to APPLgrid. Three PDFs are considered: CT10, MSTW2008 [102], and NNPDF2.3. The error members of each PDF are used to calculate that

A.4 PDF UNCERTAINTY CALCULATION

PDF's uncertainty through the envelope method [103] in equation 54, where $X[q^{(i)}]$ is the cross section evaluated at the member set i .

$$\sigma^{\text{CT}_{10}, \text{MSTW}}(\text{PDF}, \pm) = f \cdot \sqrt{\sum_{i=1}^{N/2} (\max(\{\pm X[\{q^{(2i-1)}\}] \mp X[\{q^{(0)}\}], (\pm X[\{q^{(2i)}\}] \mp X[\{q^{(0)}\}], 0)\}^2)}$$

$$\sigma^{\text{NNPDF}}(\text{PDF}, \pm) = \sqrt{\frac{1}{N-1} \sum_{i=1}^N X[\{q^{(i)}\}] - X[\{q^{(0)}\}]}, \quad (54)$$

where N corresponds to different sizes of member sets for the different PDF sets. For CT₁₀, a rescaling factor of $f = \frac{1}{1.64485}$ is included to scale the CT₁₀ uncertainty from 90% to 68% C.L., while MSTW PDF has no need for rescaling ($f = 1$). The uncertainties of all three PDFs are then combined through Eqs 55 - 57, where j is the PDF set ($j = \text{CT}_{10}, \text{MSTW}, \text{NNPDF}$). The final uncertainties are given by $\delta(\pm)$.

$$U = \max\{X^j[\{q^{(0)}\}] + \sigma^j(\text{PDF}, +)\} \quad (55)$$

$$L = \min\{X^j[\{q^{(0)}\}] - \sigma^j(\text{PDF}, -)\} \quad (56)$$

$$M = \frac{U+L}{2}; \quad \delta(+)=\frac{U-M}{M}; \quad \delta(-)=\frac{L-M}{M} \quad (57)$$

B

DATA SET AND EVENT SELECTION DETAILS

This section gives the technical details for data set selection for the two searches.

B.1 8 TEV

The data used in the 8 TeV analysis correspond to a total integrated luminosity of 17.3 fb^{-1} . The data samples employed are the centrally produced NTUP-SLIMSMQCD slims for the JetTauETMiss and HadDelayed streams, together with the full NTUP-COMMON for the debug stream. The event selection (below) is based on the following GRL:

```
data12_8TeV.periodAllYear_DetStatus-v61-pro14-  
02_DQDefects-00-01-00_PHYS_StandardGRL_All_Good.xml.
```

```
Jet calibration uses the ATLAS recommendation for Moriond 2013:  
tag 00-08-15 for uncertainties and  
ApplyJetCalibration-00-03-03/  
JES_Full2012dataset_Preliminary_Jan13.config  
for calibration.1
```

¹ See the ATLAS internal twiki.cern.ch/twiki/bin/viewauth/AtlasProtected/JetUncertainties2012 for further information

B.1.1 *Analysis cutflow*

The analysis selection criteria below are applied to collision data events in the listed order. These criteria are repeated in Table 6, which tabulates the number of events surviving each cut, N_{ev} . This section states the final numbers after removing the blinding cuts used in the optimisation phase of the analysis.

1. Total events in the data sample, N_{ev} , using the NTUP_SLIMSMQCD data format.
2. Jets are recalibrated at this point. If the data sample is to be reduced by blinding (eg., every 4th event), it is done here.
3. Events must pass the trigger requirements. The trigger uses 11 single-jet triggers, covering 11 contiguous, non-overlapping p_T ranges with an efficiency of 99.5% or greater. (The trigger strategy is described in Section 10.1.2.)
4. Events must be from runs appearing in the GRL named above.
5. Require the first vertex to have $N_{track} > 1$.
6. Reject events with calorimeter data integrity problems: $larError = 2$, OR $tileError = 2$. Also reject incomplete events (where some detector information is missing), by checking the CoreFlags that would indicate this condition.
7. Reject events if there has been a calorimeter module trip, as indicted by TTileTripReader.
8. Require two leading jets, both within the range $|y| < 2.8$.
9. Reject the event if either the leading or subleading jet is associated with a Tile calorimeter hotspot.²

² More information at: https://twiki.cern.ch/twiki/bin/view/AtlasProtected/ExoticDijets2012Cutflows#Tile_hotspot_cleaning_for_Period

10. Reject events where either of the two leading jets is ugly, or if any other jet is ugly and has $p_T > 0.3 \times p_T^{\text{sublead}}$.³
11. Reject the event if either the leading or subleading jet is a bad jet, as determined by the Rel 17 BadLooser definition.⁴
12. Reject events where either of the two leading jets, or any other jets with $p_T > 0.3 \times p_T^{\text{sublead}}$, falls within a Tile module that is masked, as stated in Section 10.2.2.
13. Require each of the leading jets to have $p_T > 50 \text{ GeV}$. This selection criterion, and those that follow, are applied to jets that have been corrected for the pile-up energy, and calibrated to the hadronic scale.
14. Beginning here, selection criteria are applied to dijet variables. Retain events with $|y^*| = |y_1 - y_2|/2 < 1.7$.
15. Retain events with $|y_B| = |y_1 + y_2|/2 < 1.1$.
16. Retain events with $m_{jj} > 600 \text{ GeV}$.

The cut flow for the full data sample used is shown in Table 6 and 7, for the overlap and delayed stream, respectively. This doesn't include the additional 24 events from the debug stream, which are also used. The debug stream contains events, in which the trigger was not able to make a decision online⁵. Those are reprocessed later. If those events pass the trigger decision in the reprocessing, they are stored in debugrec_hltacc data. The 24 events quoted are the events passing event selection. The events from this stream include one event at 3.9 TeV, while the other 23 events are below 2.6 TeV.

Since the final distributions are all normalised to unit area, it may be interesting to see the how the actual number of events after full selection are distributed among the m_{jj} bins used in the analysis. These numbers are given in Table 8.

³ More information at: <https://twiki.cern.ch/twiki/bin/viewauth/AtlasProtected/HowToCleanJets2012>

⁴ More information at: <https://twiki.cern.ch/twiki/bin/viewauth/AtlasProtected/HowToCleanJets2012>

⁵ See <https://twiki.cern.ch/twiki/bin/view/Atlas/DebugStream>

Table 6: Cut flow for the full data sample used (overlap stream), showing N_{ev} and the cut efficiency for every cut in the analysis.

Selection criterion	N_{ev}	rel. change[%]
1 (before cuts)	796605696	0.00
2 (blinding, if enabled)	796605696	0.00
3 (trigger check)	2390060	-99.70
4 (after GRL)	2029261	-15.10
5 (vertex check)	2029243	$-8.87 \cdot 10^{-4}$
6 (calorimeter error cut)	2025437	-0.19
7 (TileTripReader cut)	2025437	-0.00
8 (2 leading jets and y cut)	1769276	-12.65
9 (Tile hotspot check)	1769276	0.00
10 (after ugly jet cut)	1745377	-1.35
11 (after bad jet cut)	1744395	-0.06
12 (masked Tile module cut)	1542609	-11.57
13 (after jet p_T cut)	1120754	-27.35
14 (after y^* cut)	1082194	-3.44
15 (after y_B cut)	759379	-29.83
16 (after m_{jj} cut)	209698	-72.39

For collision data samples, all selection criteria are applied. For MC samples (signal and QCD) we only apply the kinematic selection, and the emulation of the masked Tile calorimeter regions as explained in Sec [10.2.2](#).

Table 7: Cut flow for the full data sample used (delayed stream), showing N_{ev} and the cut efficiency for every cut in the analysis.

Selection criterion	N_{ev}	rel. change[%]
1 (before cuts)	417493056	0.00
2 (blinding, if enabled)	417493056	0.00
3 (trigger check)	33883520	-91.88
4 (after GRL)	32385738	-4.42
5 (vertex check)	32385524	$-6.61 \cdot 10^{-4}$
6 (calorimeter error cut)	32285032	-0.31
7 (TileTripReader cut)	32285008	$-7.43 \cdot 10^{-5}$
8 (two leading jets and y cut)	32225564	-0.18
9 (Tile hotspot check)	32225564	0.00
10 (after ugly jet cut)	32221578	-0.01
11 (after bad jet cut)	32201909	-0.06
12 (masked Tile module cut)	28513018	-11.46
13 (after jet p_T cut)	28466487	-0.16
14 (after y^* cut)	28108922	-1.26
15 (after y_B cut)	23651795	-15.86
16 (after m_{jj} cut)	22090360	-6.60

Table 8: Final N_{ev} , for the full data sample used, in each m_{jj} interval used for binning the angular distributions.

m_{jj} range [GeV]	N_{ev}
600 – 800	8571722
800 – 1200	9917319
1200 – 1600	2825705
1600 – 2000	756044
2000 – 2600	183829
2600 – 3200	19609
3200 – 8000	2550

B.2 13 TEV

- Good Run List (GRL): Requirement that all relevant detectors were in a good state ready for physics
- LAr: Liquid Argon Calorimeter error rejected
(`errorState(xAOD::EventInfo::LAr)`)
- Tile: Tile Calorimeter error rejected
(`errorState(xAOD::EventInfo::Tile)`)
- Core: Incomplete event build rejected
(`isEventFlagBitSet(xAOD::EventInfo::Core, 18)`)
- Primary Vertex: the highest $\sum p_T^2(trk)$ vertex has at least two tracks associated with it
(`xAOD::VxType::VertexType::PriVtx`)
- Trigger: passes OR of L1_J75, L1_J100, HLT_J360, HLT_J380, HLT_J400
- at least two clean jets with $p_T > 50$ GeV
- Leading jet $p_T > 440$ GeV
- $|y^*| < 1.7$
- $|y_B| < 1.1$
- $m_{jj} > 2500$ GeV

The GRL xml file is

`data15_13TeV.periodAllYear_DetStatus-v65-pro19-01_DQDefects-00-01-02_PHYS_StandardGRL_All_Good.xml`

The information in parenthesis is technical information related to the xAOD EDM.

DATA SET AND EVENT SELECTION DETAILS

B.2.1 *Analysis selection and cutflow*

The data selection cutflow is shown in Table 9 and the MC selection cutflow in Table 10. The number of events passing the selection in MC is rounded to the nearest integer (the effective statistics vary between slices).

Selection criteria	N_{events}	rel. decrease (%)
all	35477718	0.0
LAr	35398888	-0.22
tile	35395678	-0.01
core	35393381	-0.01
NPV	35391453	-0.01
Trigger (OR)	23350594	-34.02
jetSelect signal	23020926	-1.41
$jet_1 p_T > 200$ GeV	12740838	-44.66
HLT j360	11995952	-5.85
cleaning	11988448	-0.06
LJetPt	4979860	-58.46
mjjMin	136300	-97.26
$y^* < 1.7$	71204	-47.76
$yBoost < 1.1$	70417	-1.11

Table 9: Cutflow for data events with the analysis cuts used for $\sqrt{s} = 13$ TeV data. "Trigger" corresponds to the events passing the OR of L1_J75, L1_J100, HLT_J360, HLT_J380, HLT_J400.

Selection criteria	N_{events}	rel. decrease (%)
HLT j360	4804917	0.0
LJetPt	1884597	-60.78
mjjMin	61818	-96.72
$y^* < 1.7$	29333	-52.55
yBoost < 1.1	28880	-1.54

Table 10: Cutflow for PYTHIA8 events in the analysis of $\sqrt{s} = 13$ TeV data.

LHCP RESULTS

Here the results prepared for the LHCP conference are shown. These were the first search results to be approved by ATLAS in Run2 and represent 80 pb^{-1} of data at $\sqrt{s} = 13 \text{ TeV}$ [13]. No significant deviations from the SM prediction were found, and limits were set on QBH as modelled by BlackMax and QBH, which surpassed the limits obtained in Run1 using 20.2 fb^{-1} at $\sqrt{s} = 8 \text{ TeV}$. All details can be found in Ref. [13]. The only difference in methodology to the full 2015 data set result is the search strategy in the angular distributions: this result uses a single region $m_{jj} > 3.4 \text{ TeV}$ for the statistical analysis, while the analysis of the full 2015 data set uses a combination of the four highest regions in m_{jj} , starting from $m_{jj} = 3.4 \text{ TeV}$.

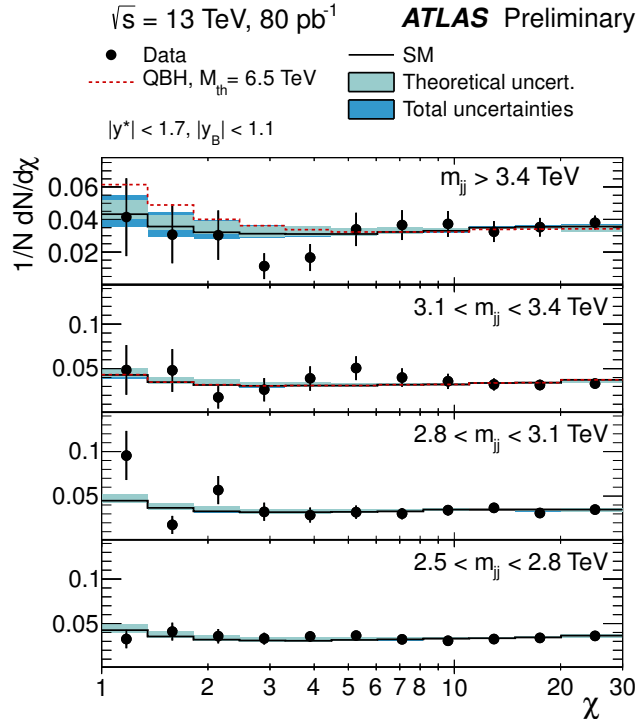


Figure 81: Normalised angular distributions in the $\sqrt{s} = 13 \text{ TeV}$ data, overlaid with the MC prediction. Theoretical and total uncertainties are shown as lighter and darker shaded bands, while the vertical error bars represent the statistical uncertainty. The predicted signal for QBH is also shown.

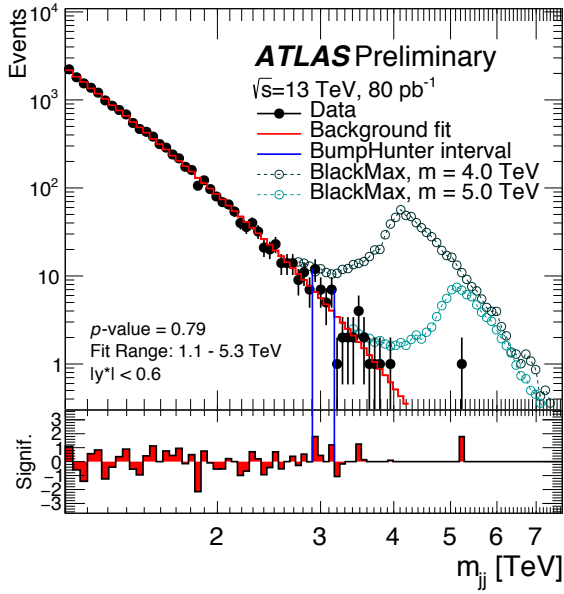


Figure 82: Dijet mass distribution in the $\sqrt{s} = 13$ TeV data, compared to the fit (red line) in the second panel, with QBH signal prediction for two M_{th} overlaid.

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