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## 22 **Abstract**

23 *Objective:* To evaluate feasibility and morbidity of robot assisted laparoscopic radical  
24 hysterectomy.

25 *Methods:* From December 2005 to September 2008 robot assisted laparoscopic radical  
26 hysterectomy and pelvic lymphadenectomy was performed on 80 women. Using a prospective  
27 protocol, and an active investigation policy for defined adverse events, perioperative, short  
28 and long term data were obtained.

29 *Results:* Time for surgery (skin to skin) reached 176 and 132 minutes after 9 and 34  
30 procedures respectively. All tumours were radically removed. Median number of retrieved  
31 lymph nodes was 26 (range 15-55). All women had an early follow up (1-3 months) and 43  
32 of eligible 46 women (93%) had a long term follow up ( $\geq 12$  months). In 33 of 80 women  
33 (41%) the peri/postoperative period was uneventful. The remainder had one or more mainly  
34 mild adverse events, most commonly from the vaginal cuff ( $n=17$ , 21%) or the lymphatic  
35 system ( $n=16$ , 20%). The proportion of uneventful cases increased significantly over time.  
36 Five women were resutured for dehiscence of the vaginal cuff, two women were reoperated  
37 for trocar site hernias and one woman had a ureter stricture that resolved following stent  
38 treatment. Eight women (14 %) needed 60 days or more to resume spontaneous voiding. One  
39 72-year old woman with disseminated endometrial cancer on autopsy died of pulmonary  
40 embolism 31 days after surgery.

41 *Conclusions:* Robot assisted laparoscopic radical hysterectomy is a feasible alternative to  
42 conventional laparoscopy and open surgery. Effort should be made to ensure proper closure of  
43 the vaginal cuff, trocar sites and to develop nerve sparing techniques.

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46 *Keywords:* Cervical cancer, robotic surgery, radical hysterectomy

## 47 **Introduction**

48 The adoption of laparoscopic surgery has provided the advantages of minimally invasive  
49 surgery also for women with gynecological malignancies. Several studies have demonstrated  
50 that laparoscopic surgery is safe for this group of women [1-4]. However, the complexity of  
51 the procedures has limited laparoscopic surgery to centres with large volumes of cancer. In  
52 many parts of the world, the incidence of cervical cancer, the main indication for radical  
53 hysterectomy and pelvic lymph node dissection, has diminished and even larger centres may  
54 have a too low case load to maintain and develop good laparoscopic skill.

55 The da Vinci system (da Vinci<sup>®</sup> Surgical System, Intuitive Surgical Inc, CA, USA)  
56 was approved for gynecological applications in April 2005 by the Food and Drug  
57 Administration of the United States. The system provides instruments with a wrist function at  
58 the tip, movement downgrading, tremor elimination, a stable 3-dimension view of the  
59 operative field and an ergonomic working position. These features may help the surgeon  
60 overcome some of the limitations associated with traditional laparoscopic surgery.

61 The use of robot-assistance for radical hysterectomies is still in its infancy. A few reports  
62 describing the technique are published [5-10]. Magrina et al. report shorter operative time for  
63 robot assisted laparoscopy compared with traditional laparoscopy and shorter hospital stay  
64 and less blood loss compared with open surgery [9]. Boggess et al. report shorter operative  
65 time, less blood loss and shorter hospital stay in favour of the robot assisted approach when  
66 comparing with open surgery [10].

67 Lund University Hospital is a tertiary referral centre for gynecological oncologic surgery  
68 with an expected annual case load of 40 radical hysterectomies. Included surgeons had a  
69 minimum of five years experience with advanced conventional laparoscopic procedures, e.g.  
70 pelvic lymphadenectomies with less case load surgeon C. Four laparoscopic radical  
71 hysterectomies have been performed.

72 Robot assisted surgery was introduced in October 2005 following a training programme  
73 for surgeons and operating room teams. From the start, detailed protocols for prospective  
74 retrieval of perioperative and follow up data were used. All data were consecutively entered to  
75 a computerized quality registry instituted for all robot assisted gynecological procedures on  
76 demand of, and approved by, the hospital administration. For the present study, we retrieved  
77 the data from women planned for robot assisted laparoscopic radical hysterectomy and pelvic  
78 lymphadenectomy with the aim of assessing feasibility, short and long term morbidity of the  
79 procedure. The study was approved by the regional Institutional Review Board.

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## 97 **Subject and method**

98 From December 2005 to September 2008, 110 consecutive women with early stage cervical  
99 cancer or stage 2 endometrial cancer were considered for a modified Piver II-III robot assisted  
100 laparoscopic radical hysterectomy and pelvic lymphadenectomy. We excluded women with a  
101 compromising cardiovascular/respiratory comorbidity ( $n=5$ ), a uterine size not allowing  
102 vaginal retrieval ( $n=4$ ) and known intraabdominal adhesions or multiple midline incision  
103 ( $n=6$ ). Five women had open surgery due to limited access to the robot.

104 The remaining 90 women were offered robot assisted laparoscopy after an information  
105 including their option of alternative surgical approaches. All eligible women approved.

106 In 55 of 70 women with cervical cancer, 120 MBq  $^{99m}\text{Tc}$  was injected superficially  
107 at four points in the cervix the day before surgery followed by a lymphoscintigram to identify  
108 sentinel lymph nodes as a part of a parallel study. During surgery, the sentinel lymph nodes  
109 were detected by a laparoscopic gamma probe (Neo2000® laparoscopic probe, Neoprobe  
110 Corporation, Dublin OHIO) and sent for frozen section. The hysterectomy was aborted in  
111 favour of radiation therapy if a sentinel node was metastatic.

112 We used a four arm da Vinci or da Vinci-S robot. To facilitate an optimal exposure for the  
113 gamma-probe scanning, first and foremost in the common iliac area, two assistants' trocars  
114 were used (Excel ®12 millimetre Ethicon Inc, Somerville, NJ and Versaseal® Plus15  
115 millimetre, Auto Suture/ Tyco Health care, Oriscany Falls, NY). The probe was used in  
116 either of the trocars to achieve an optimal angle for the sidemounted gamma-element. The 15  
117 millimetre trocar was also used for compartmentwise retrieval of lymph nodes in a  
118 reinsertable retrieval bag (LINA Medical, Glostrup, Denmark). The port placements and  
119 instruments are illustrated in Figure 1. The grasper was used to present the specimen in an  
120 appropriate position and to apply adequate tension of the tissue for monopolar dissection.  
121 Posterior dissection was finished first to avoid impaired visibility by bleeding from anterior

122 dissection. A folded swab on a forceps was placed vaginally to help to decide the level for the  
123 vaginal transection and to prevent gas-leakage after opening of the vagina. No vaginal dilator  
124 or uterine manipulator was used. Monopolar diathermia was set a 30-40 Watts using the  
125 coagulating mode for electrodissection and the cutting mode for opening of the vagina.

126 Initially, the paravesical and pararectal spaces were developed and sentinel nodes  
127 identified. Full uterine blood supply was preserved until the sentinel nodes were found  
128 negative. The full lymphadenectomy was performed *en bloc* compartmentwise starting with  
129 the common iliac nodes (boundary five centimetres cranial of the bifurcation of the iliac  
130 artery), followed by the external iliac nodes (distal boundary the Cloquet's node, lateral  
131 boundary the genitofemoral nerve), and the obturator nodes (distal boundary the pubic bone,  
132 dorsal boundary the obturator nerve).

133 A modified Piver II (stage 1A 2 and stage 1b1 <1 centimetres) or Piver III (stage 1b1 ≥1  
134 centimetres) radical hysterectomy was performed. For the modified Piver II and Piver III we  
135 aimed at a shorter vaginal specimen length (minimum two and four centimetres respectively)  
136 and a less extended dissection of the sacrouterine ligaments (minimum two and four  
137 centimetres from the cervix respectively) compared with the original Piver classification.  
138 Technically, we followed a uniform plan for the radical hysterectomy. The uterine vessels  
139 were divided at their origin (all tumor stages). The parametria and the ureters were dissected  
140 as far distally as possible. The uterus was lifted, the rectovaginal space was opened and the  
141 sacrouterine ligaments isolated at appropriate distance. After a dissection of the bladder in the  
142 midline, the bladder pillar was isolated followed by division of the lower parametria and  
143 paracolpia before the vagina was transected. To ensure the desired level for the vaginal  
144 transection, the vaginal swab was pushed inwards and then slowly moved back to visualize  
145 the level of the distal cervix. We first incised the vagina anteriorly and the following  
146 transection was performed under visual control from the inside of the vagina. The specimen

147 was removed vaginally using either a tenaculum or a retrieval bag. The vagina was closed  
148 from inside using a continuous Vicryl 0 (Ethicon Inc, Somerville, NJ) suture secured with  
149 laparoscopic knots. Surgeon A used a figure-of-eight inverting suture whereas surgeon B and  
150 C used plain sutures for vaginal closure. The fascia was closed at the site of the  
151 supraumbilical optics port and the 15 millimetre assistants' port.

152 In case of small tumours (<1 centimetre) we usually identified the ileohypogastric nerves  
153 by further developing the pararectal space. Vessel loops were used to facilitate nerve sparing  
154 dissection to the bladder by pulling the nerves and ureters laterally together.

155 Bladder catheterization was interrupted when residual urine was less than 100mL once or less  
156 than 150mL twice provided that the voided volume was at least 200 mL. Women with  
157 persistent inadequate voiding after seven postoperative days were prescribed self  
158 catheterization monitored by telephone controls until approved residual urine. All women  
159 received antibiotic prophylaxis and low molecular weight heparin according to local treatment  
160 protocol. In median, women were discharged on the third postoperative day (range 1-9 days).

161 According to protocol, surgical data, short and long term postoperative complications and  
162 time to spontaneous voiding were prospectively registered. During follow-ups, including a  
163 vaginal ultrasonography for identification of lymphoceles, women were actively asked and  
164 investigated for defined adverse events in particular from the urogenital, neural and lymphatic  
165 systems and the abdominal wall.

166 Data were consecutively entered into a StatView<sup>®</sup> database (SAS Institute Inc., Cary, NC,  
167 USA). For statistical analyses we used Fishers' exact test, Mann-Whitney's test or Kruskal-  
168 Wallis' test as appropriate. A value of  $p < 0.05$  was considered statistically significant.

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## 172 Results

173 During surgery, metastatic sentinel lymph nodes were identified in six women and the radical  
174 hysterectomy was aborted. Four women were converted to open surgery, one due to an  
175 irreversible robot system error, two for anesthesiological reasons and one due to  
176 intraabdominal metastases.

177 Thus, 80 women, 64 with cervical cancer (stage 1A1  $n=4$ , stage 1A2  $n=10$ , stage 1B1  $n=$   
178 44, and stage 2A  $n=6$ ) and 16 with stage 2 endometrial cancer, underwent the complete  
179 procedure. The four women staged as 1A1 cervical cancer after final histology had a radical  
180 hysterectomy due to difficulties in the preoperative staging (adenocarcinoma and/or  
181 multifocality and/or intracervical lesions proximal to cone specimens). The procedures were  
182 performed by either of three surgeons (surgeon A,  $n=38$ , surgeon B,  $n=22$ , surgeon C,  $n=20$ ).  
183 Median age was 48 years (range 23-86 years) and median Body Mass Index 24.4 kg/m<sup>2</sup>  
184 (range 17.5-39.0 kg/m<sup>2</sup>). 16 women had a history of one or more previous laparotomies. In  
185 11 women adhesiolysis added a median time of 20 minutes to the procedures (range 5-60  
186 minutes). Surgery was prolonged in seven cases due to reversible system errors. Baseline  
187 patients characteristics were evenly distributed among surgeons.

188 Time for surgery (skin to skin including time for the sentinel node procedure and time for  
189 frozen section) reached 171 and 132 minutes after 9 and 34 procedures respectively (Figure  
190 2). Median blood loss during surgery was 150 mL (range 25-1300 mL). Time for surgery was  
191 significantly related to Body Mass index of the patients ( $p<0.01$ ). Excluding the first 10  
192 procedures for each surgeon (initial learning curve), the median time for surgery (all surgeons  
193 together) was 219 minutes (range 141-310 minutes) for women with the lowest Body Mass  
194 Index (range 17.5-24.4) and 279 minutes (range 170-406 minutes) for women with the highest  
195 Body Mass Index (range 24.8-39.0). For surgeon A only, the median surgical times were 174  
196 and 206 minutes respectively using the same criteria ( $p<0.01$ ).

197 No patient received intraoperative blood transfusion and no intraoperative complications  
198 occurred apart from the neural complications described in Table 2. Time for surgery and blood  
199 loss differed significantly between surgeons (Table 1).

200 All 64 women with cervical cancer had radical surgery. 21 of them (16 women with stage 1B1  
201 >2 centimetres and five women with stage 2A) were offered postoperative radiation therapy  
202 either due to positive lymph nodes ( $n=8$ , including three cases of micrometastases in sentinel  
203 nodes and two cases with no uptake of radiotracer), small cell squamous carcinoma ( $n=1$ ) or  
204 less than the eight millimetres of free margins at final histology required according to local  
205 treatment protocol ( $n=12$ ). The insufficient margins were all in the circumferential part of the  
206 cervix where anatomy restricts anterior/posterior margins. Median number of retrieved lymph  
207 nodes was 26 (range 15-55).

208 All women had the early follow up (1-3 months) and 43 of eligible 46 women (93%) had the  
209 long term follow up ( $\geq 12$  months). One woman was lost due to high age, one had moved  
210 abroad, and a 72-year old woman with disseminated endometrial cancer on autopsy died of  
211 pulmonary embolism 31 days after surgery.

212 33 of 80 women (41%) had an uneventful peri/postoperative period whereas the remainder  
213 experienced one or more mainly mild complications (Table 1). Five women were resutured  
214 for vaginal cuff dehiscences. One woman had a ureter stricture temporarily treated with a  
215 stent. One woman experienced a reversible partial obturator nerve palsy. In two cases the  
216 small bowel was incarcerated through the peritoneal opening at the site of the 15 millimetre  
217 trocar despite an intact sutured fascia. Two women had a partial rupture of the rectus muscle  
218 close to a robot trocar.

219 Significantly fewer women had complications when comparing the second and first half  
220 of the series of operations for the respective surgeons (28 of 40 compared with 17 of 40,  
221  $p=0.02$ ). For the latter analyses we excluded lymphatic complications as they were evenly

222 distributed over time and among surgeons and were unrelated to the number of retrieved  
223 nodes. Overall complications did not differ between surgeons. However, vaginal cuff  
224 dehiscence occurred significantly more often for surgeon B compared with surgeon A (4 of 22  
225 cases compared with 0 of 38 cases,  $p=0.02$ ).

226 Time to resume spontaneous voiding is presented in figure 3. There was a significant  
227 association with tumour stage ( $p=0.02$ ) but no association with surgeon.

228 Three recurrences have been identified after 7, 15 and 14 months respectively, the first  
229 two by an optional separate PET-CT follow up programme.

230 A 65 year old woman with stage 1B1 lymphoepitelioma type squamous epithelial cancer  
231 with no sentinel node procedure had a nodal recurrence in the deep presacral/pararectal area.

232 A 41 year old woman with stage 1B1 medium grade squamous epithelial cancer and  
233 postoperative pelvic radiation therapy due to multiple metastatic pelvic nodes had a paraaortic  
234 nodal recurrence. No pelvic or paraaortic nodes (benign or metastatic) had detectable uptake  
235 of radiotracer. A paraaortic lymph node dissection was not performed.

236 A 26 year old woman with a stage 1B1 medium grade squamous epithelial cancer and no  
237 postoperative radiation therapy recurred with pulmonary metastases.

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## 247 **Discussion**

248 This study indicates that the da Vinci robot is useful for implementing laparoscopic radical  
249 hysterectomy in a centre with limited experience of this procedure by traditional laparoscopy  
250 and with a restricted case load of cervical cancers. Time for surgery decreased rapidly and  
251 short term complications diminished significantly over time. The operating time was  
252 comparable with times reported for conventional laparoscopic radical hysterectomies by  
253 larger institutions [11-13].

254 Times for surgery and bleeding differed significantly between surgeons (Table 1). The  
255 surgeon with the longest times for surgery and the largest median bleeding had the least  
256 experience with traditional laparoscopic surgery. All surgeons intended to follow the defined  
257 steps of the surgical procedure. Discrepancies in surgical technique/skill are difficult to define  
258 but we believe that the extent of previous experience with advanced traditional laparoscopy  
259 affects the performance of robot surgery at least during an introductory phase.

260 The separate times for the sentinel node procedures were not recorded in our protocol and  
261 would have been difficult to define as we finished at least the common iliac node dissection  
262 bilaterally while waiting for the frozen section results. Overall, mean surgical time with the  
263 sentinel procedure included was 21 minutes longer than for operations without the sentinel  
264 node procedure. However, this difference diminished over time as we became more efficient  
265 in identifying the sentinel nodes. Seven of the 10 fastest operations included the sentinel node  
266 procedure. We intend to publish the details of the sentinel node study separately.

267 Strengths of this study are the prospective retrieval of data, the relatively large number of  
268 included women and the few women lost for follow up. A weakness of this study is the lack  
269 of comparison with established surgical techniques. However, this prospective study describes  
270 a surgical approach during an introductory phase and a retrospective comparison with  
271 previous open radical hysterectomies at our institution would inevitably be biased in favour of

272 the established technique. Moreover, the differences between surgeons in surgical time and  
273 bleeding would further bias such a comparison.

274 Our complication rate was higher than rates reported by most other authors, in particular  
275 complications from the vaginal cuff and lymphatic system (Table 2 and 3). The active  
276 investigation policy for defined types of adverse events used in our study may explain some  
277 of this discrepancy. Moreover, loss of genitofemoral nerve innervation and proximal  
278 lymphoedema (eight and 12 cases respectively in our study) is neither mentioned nor denied  
279 by any other author indicating different definitions of complications.

280 Some complications may be associated with robotic or laparoscopic surgery *per se*.  
281 Leaking of lymphatic fluid through the vagina and/or vaginal cuff dehiscence occurred in 10  
282 (12%) cases. The leaking resolved spontaneously within a couple of weeks but was  
283 bothersome and fistulas had to be excluded. Our rate of vaginal cuff dehiscences is equal to  
284 the rate reported by Hur et al. for total laparoscopic hysterectomies but significantly higher  
285 than for hysterectomies performed by laparotomy (14). Moreover, in our series this  
286 complication differed significantly between surgeons. This implies that laparoscopic closure  
287 of the vaginal cuff, robot assisted or not, may be less efficient but also that differences in  
288 individual surgeons techniques may play a role. In our study the only identifiable difference  
289 between surgeons in vaginal closure technique was the use of an inverting suture by surgeon  
290 A (no dehiscences). Such sutures may promote an increased area for healing in the vaginal  
291 apex as it approximates the raw abdominal sides of the vagina in contrary to the epithelial  
292 sides. Moreover, inverting sutures requires the distal stitch to be placed at least 7-8  
293 millimetres from the cauterized vaginal edge, probably beneficial to ensure approximation of  
294 thermally non-damaged tissue. We also believe that meticulous tightening of the sutures is  
295 important as vaginal leaking short time after surgery preceded three of five dehiscences.

296 Time to spontaneous voiding was associated with clinical stage but with large variations  
297 within stages. Despite the excellent visualization and dissection properties of the robot  
298 bleeding often occurs in the lower parametrium and paracolpium. Extended use of diathermia  
299 for hemostasis in this area may have inflicted thermal injury to nearby nerves in some cases.  
300 Unfortunately, we did not include separate measurements of the length of the resected vagina  
301 and parametria in our protocol which may have provided further information on a  
302 possible association between voiding difficulties and the radicality of the procedure.

303 Two women had a partial rupture of the rectus muscle close to a robot trocar. Strong lateral  
304 movements of the robot arms in combination with non-pivotal position of trocars may be the  
305 reason.

306 The incarcerations of the small bowel both occurred through the peritoneal opening at the place  
307 for the 15 millimetre assistant's trocar despite an intact sutured fascia. To avoid this  
308 complication we included a peritoneal suture during the second half of the procedures. No  
309 hernias occurred at the da Vinci trocar sites.

310 In our series, in-patient times were longer than reported by other authors (5-10). There are  
311 several explanations: First, as we were pioneers from a European perspective, we initially  
312 wanted to gain experience with the procedure and to ensure the women were perfectly fit to  
313 go home, in particular the majority of women living in distant parts of the hospital recruitment  
314 area. Second, nine women were older than 70 years and were kept longer for socio-medical  
315 reasons. Third, initially we often kept women for repeated assessment of voiding if the criteria  
316 for approved residual urine were close to be met. Later we abstained from the initial second  
317 postoperative day control of voiding. Instead, women were discharged with an indwelling  
318 catheter and a scheduled outpatient control of voiding seven days after surgery. Altogether,  
319 during the last year, 55% of unselected women were discharged within 48 hours after the  
320 surgical procedure.

321        Apart from the high cost for investment and maintenance of the da Vinci system, we  
322 believe the major disadvantage with robot assisted surgery is the relatively long time for  
323 nurses preparation affecting the total time for patient in the operating room as well as time for  
324 change in between procedures (Table 1). In our series, the median time from patients entry in  
325 the operating room (including anesthesia) until onset of surgery was 68 minutes (range 35-123  
326 minutes). So far, we have not been able to significantly diminish that time, probably since we  
327 still introduce new nurses into robotics and since we suffer from a constant turnover of  
328 anesthesia teams. Considering the times for nurses preparation and cost for the robot it is  
329 unclear whether the robot concept is cost efficient compared with laparoscopy or open  
330 surgery.

331        We believe that the implementation of laparoscopic radical hysterectomies at our  
332 institution was facilitated by the da Vinci system and that further shortening of surgical time  
333 and nurses preparation time is possible. Moreover, once familiar with the da Vinci system we  
334 have managed to apply laparoscopic surgery also for rare advanced oncological procedures  
335 such as laparoscopic radical trachelectomy, surgery for vaginal cuff recurrences and removal  
336 of bulky nodes and pelvic side wall tumors (15). We do not believe that those procedures  
337 would have been laparoscopic at our institution without the robot.

338        However, it is unclear to which extent the robot facilitates laparoscopic radical  
339 hysterectomies at an institution with a previous large experience of traditional laparoscopic  
340 radical hysterectomies.

341        In conclusion, we found robot assisted laparoscopic radical hysterectomy to be associated  
342 with a steep learning curve and a diminishing number of complications over time. Effort  
343 should be made to ensure an efficient closure of the vaginal cuff. There may be a need for  
344 alternative hemostatic techniques allowing less use of diathermia in areas close to the pelvic

345 nerves. The properties provided by the da Vinci system may facilitate further refinement of  
346 nerve sparing techniques.

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370 **Article précis**

371 Robotic radical hysterectomy.

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395 **Conflict of interest statement**

396 Jan Persson is a proctor for surgery with the Da Vinci Robot.

397 The authors all declare that there are no conflicts of interest.

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446 **Legends to figures**

447

448 **Figure 1**

449 Port placements used for robot assisted laparoscopic radical hysterectomy.

450 1: Robot (monopolar scissors, needledriver) 2:Robot (bipolar grasper). 3: Robot (grasper). 4:

451 15 mm assistants port (retrieval of nodes, gamma-probe, retraction, suction/irrigation). 5: 12

452 mm assistants port (gamma-probe, retraction, suction/irrigation). 6: Robot (optics)

453

454 **Figure 2**

455

456 Time for surgery (skin to skin including docking of robot) for robot assisted laparoscopic

457 radical hysterectomy and pelvic lymphadenectomy.

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460 **Figure 3.** Time to resume spontaneous voiding following robot assisted laparoscopic radical

461 hysterectomy in women with early stage cervical cancer.

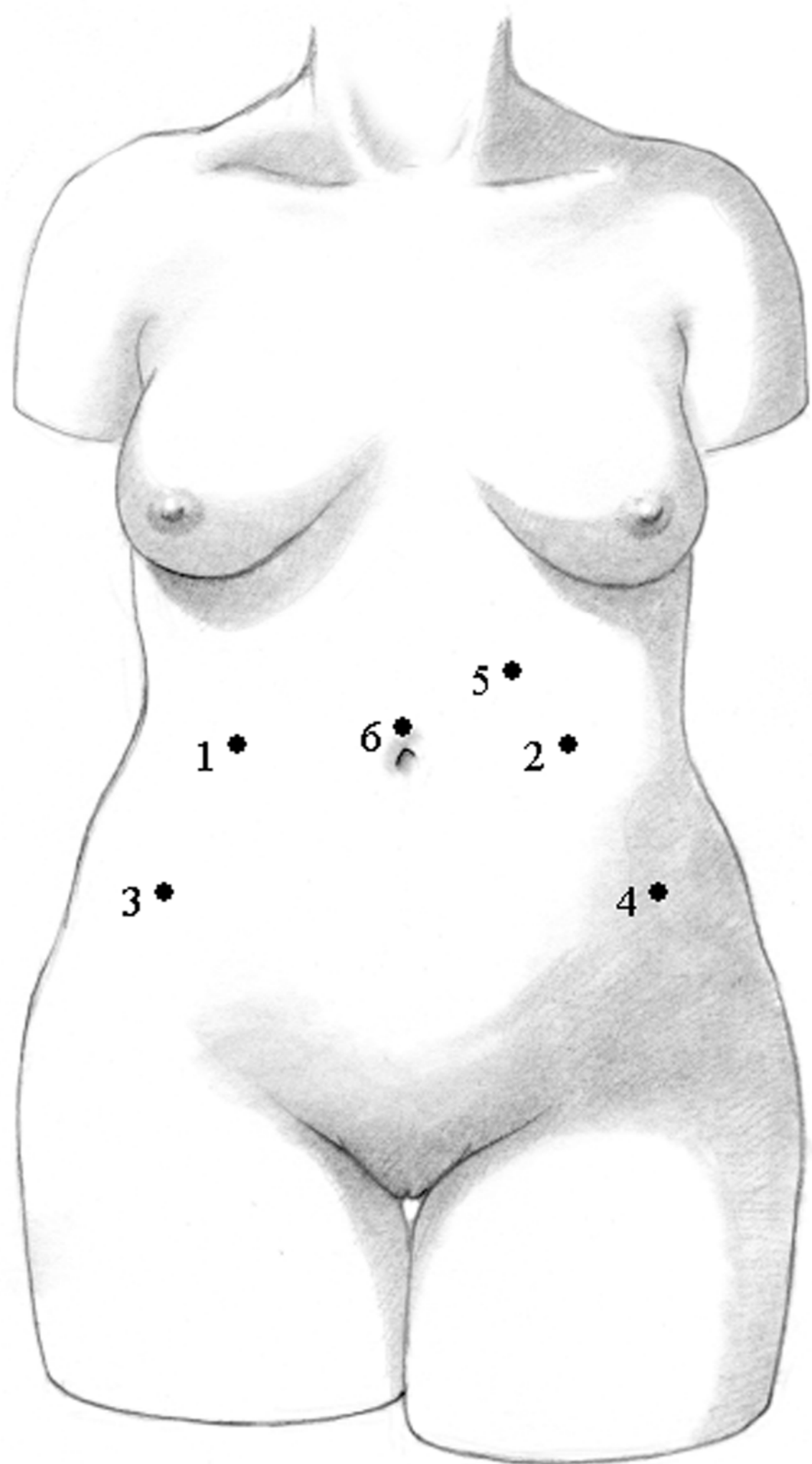
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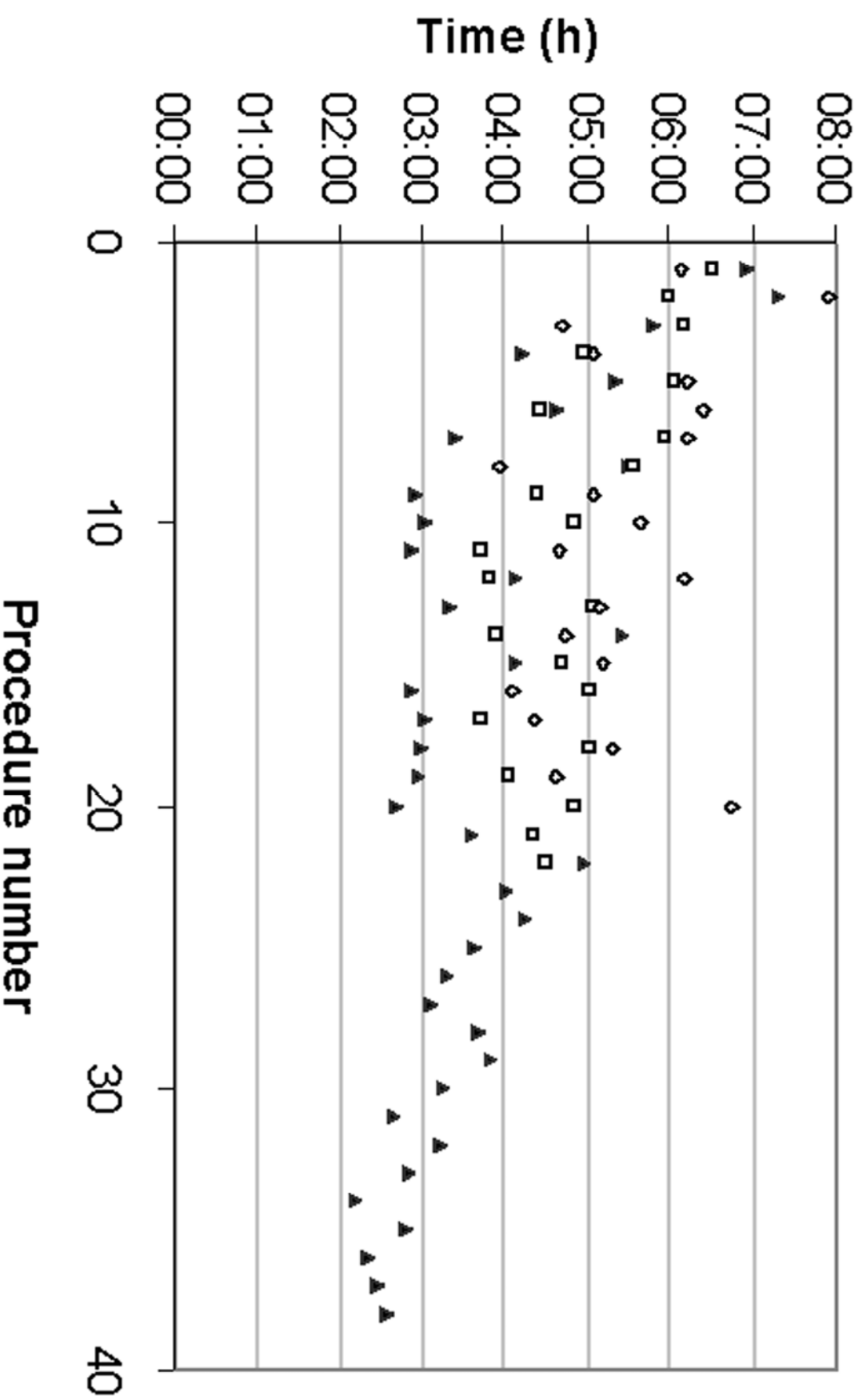
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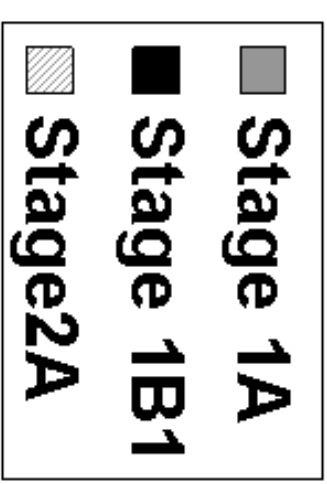
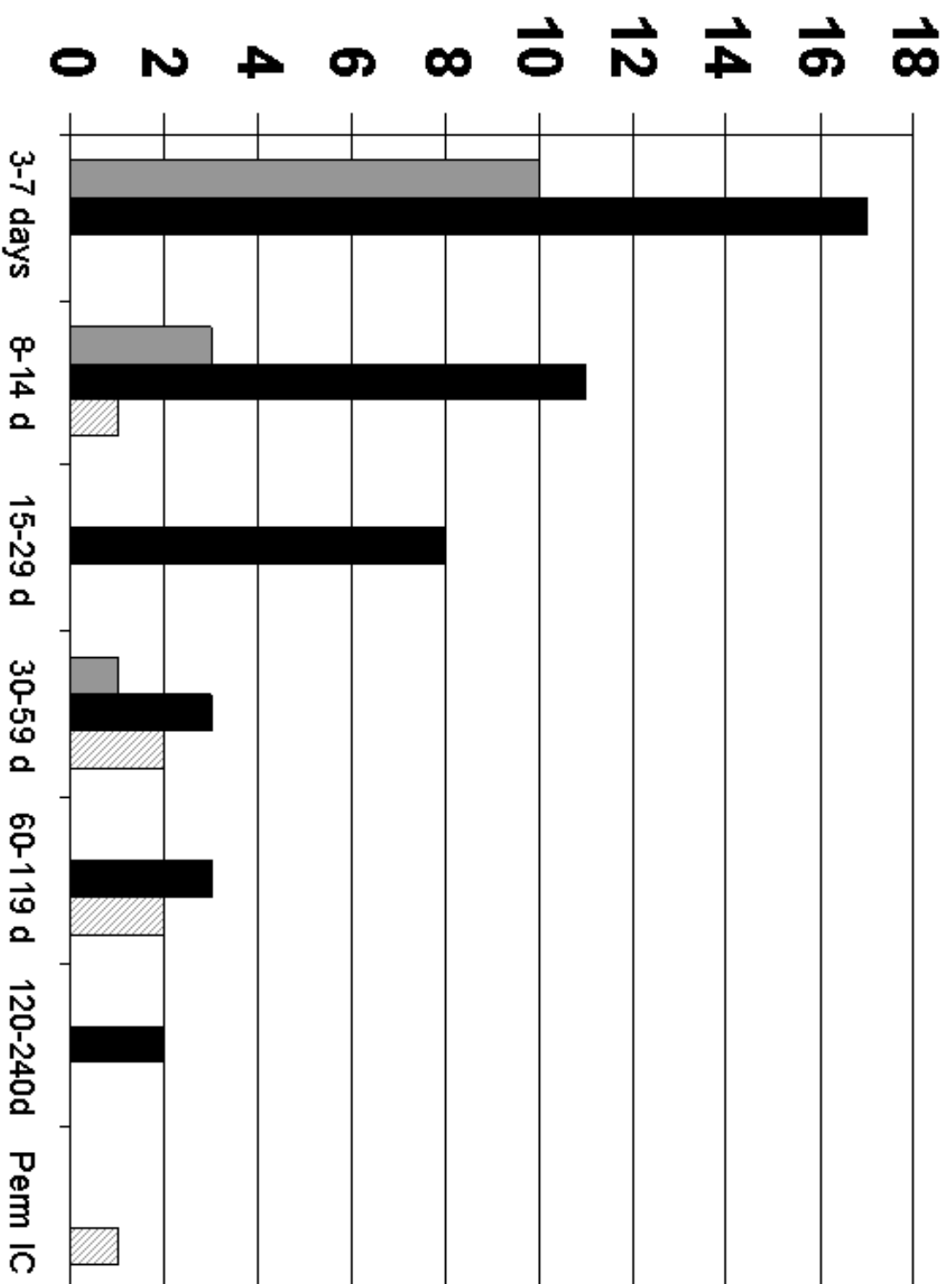
465

466





- ▲ Surgeon A
- ▣ Surgeon B
- ◆ Surgeon C





**Table 1.** Times and bleeding recorded during robot assisted laparoscopic radical hysterectomy and pelvic lymphadenectomy.

<b>Data recorded during surgery</b> minutes, mL as appropriate (median, range)	<b>All surgeons</b> <i>n</i> =80	<b>Surgeon A</b> <i>n</i> =38	<b>Surgeon B</b> <i>n</i> =22	<b>Surgeon C</b> <i>n</i> =20	<b>Statistics</b>
Total time for patient in operating room*	355 (238-563)	293 (238-425)	388 (289-465)	414 (349-433)	<i>p</i> <0.001
Total time for surgery (skin to skin)	262 (132-475)	199 (132-438)	290 (220-389)	311 (237-475)	<i>p</i> <0.001
Consol time	215 (118-341)	170 (118-300)	250.5 (188-332)	257 (165-341)	<i>p</i> <0.001
Surgeons start up time **	20 (8-53)	17 (8-48)	20.5 (14-53)	25.5 (16-38)	<i>p</i> =0.003
Surgeons finishing time***	14.5 (5-49)	10 (5-40)	14 (5-29)	19.5 (6-49)	<i>p</i> =0.03
Estimated bleeding (ml)	150 (25-1300)	150 (25-400)	150 (50-650)	300 (100-1300)	<i>p</i> =0.005

\* Includes start and finish of anesthesia and OR-nurse preparations.

\*\* Time from first skin incision to onset of consol surgery including docking of robot.

Includes women requiring adhesiolysis before docking and situations with reversible system errors.

\*\*\* Time from end of consol surgery to last stitch in skin including dedocking of robot.

**Table 2.**

Complications following robot assisted radical hysterectomy and pelvic lymphadenectomy.

Type of complication	Complications until	Complications	
	1-3 months follow-up.	at one year follow-up.	
	<i>n</i> = 80	<i>n</i> = 43*	
<b>No complication</b>	33 (41%)	25 (58%)	
<b>Vaginal cuff:</b>			
Dehiscense	4 (5%)	1 (a)* * (2%)	
Lymphatic leaking	8 (10%)	-	
Infection	7 (9%)	-	
Hematoma	2 (3%)	-	
Vault prolapse	-	2 (a)	(5 %) (1 rad)
Short vagina	1 (1%)	2 (a+r)	(5 %) (1 rad)
<b>Lymphatic:</b>			
Proximal lymphoedema	12 (15%)	4 (r)	(10%)
Mild distal lymphoedema	1 (1 %)	4 (3a,1r)	(10%) (3 rad)
Severe distal lymphoedema	-	2 (a)	(5 %) (2 rad)
Lymphocyst	6 (8%)	2 (r)	(5 %)
<b>Neural:</b>			
Genitofemoral nerve injury	8 (10%)	6 (r)	(15%)
Partial obturator nerve palsy	1 (1 %)	1 (r)	(2 %)
<b>Abdominal wall:</b>			
Port site hernia	3 (4 %)	1 (r)	(2 %)

Port site muscle rupture	2 (3 %)	2 (r)	(4 %)
Hematoma	2 (3 %)	-	
Port site metastases	-	-	
<b>Vascular:</b>			
Postop hemoglobin <90 g/L and/or transfusion	10 (13%)	-	
Ovarian vein thrombosis	1 (1 %)	-	
Pulmonary embolism	1 (1%)	-	
<b>Infection:</b>			
Pneumonia	1 (1 %)	-	
Pyelonephritis	1 (1 %)	-	
Fever of unknown origin	2 (3 %)	-	
<b>Urinary:</b>			
Ureter stenosis	1 (1 %)	-	
<b>Positioning:</b>			
Arm / shoulder / leg pain ***	7 (13 %)	-	

More than one complication may have occurred for a single patient.

\*16 of 43 women at the one-year follow up had postoperative pelvic radiotherapy.

\*\* (a) = additional complication. (r) = remaining complication. (rad) = radiotherapy. Number within brackets indicate the number of women for each category.

\*\*\* All women had surgery time exceeding 5 hours

**Table 3.** Complications following robot assisted radical hysterectomy and pelvic lymphadenectomy as reported by other authors.

<b>Complication type by author</b>	<b>Bogges JF et.al.</b>	<b>Magrina J et.al.</b>	<b>Fanning et.al.</b>	<b>Nezhat FR et.al.</b>	<b>Kim YT et.al.</b>	<b>Sert B et.al.</b>
Cases ( <i>n</i> )	51	27	20	13	10	7
Study type	Case-control	Case-control	nd*	Case-control	Retrospective	nd
Follow up (months) (mean/median)	nd	31	24	12	9	14
<b>Overall complication rate (%)</b>	8%	15%	10%	38%**	8 %	71 %**
Lymphatic	1 (2%)	1 (4%)	0 (0%)	0 (0%) nsd	0 (0%) nsd	2 (28%)
	Distal lymphoedema	Distal lymphoedema	sd ***			Lymphocele
Vaginal cuff	2 (4%)	0 (0%) sd	0 (0%) nsd	1 (8%)	0 (0%) nsd	0 (0%) nsd
	Abscess Cuff dehiscence			Lymphatic leaking		
Neural	0 (0%) sd	0 (0%) nsd	0 (0%) nsd	0 (0%) nsd	0 (0%) nsd	0 (0%) nsd
Port site hernia	0 (0%) nsd	0 (0%) nsd	0 (0%) nsd	0 (0%) nsd	0 (0%) nsd	0 (0%) nsd
Port site metastases	0 (0%) nsd	0 (0%) nsd	0 (0%) nsd	0 (0%) nsd	0 (%) sd	0 (%) nsd

Vascular	0 (0%) sd	1 (4%) postop. blood transfusion	0 (0%) sd	0 (0%) sd	0 (0%) sd	1 (14%) DVT
Infection	0 (0%) sd	0 (0%) sd	0 (0%) sd	1 (8%) Cl. difficile enterocolitis	1 (10%) Pneumonia	1(14%) UTI
Urinary	0 (0%) sd	0 (0%) sd	2 (10%) Cystotomy Uretero- vaginal fistula	2 (15%) Cystotomy	0 (0%) sd	1 (14%) Cystotomy
Positioning	0 (0%) nsd	0 (0%) nsd	0 (0%) sd	0 (0%) nsd	0 (0%) nsd	0 (0%) nsd
Other	1 (2%) abdominal pain, readmitted	2 (8%) Pneumo- thorax Pleural effusion	0 (0%)	1 (8%) Ileus	0 (0%)	0 (0%)
Conversion	0 (0%)	0 (0%)	0 (0%)	0 (0%)	0 (0%)	0 (0%)
Bleeding (mL) (mean/median)	96	133	300	157	355	71
Recurrent disease	nd	0 (0%)	2 (10%)	0 (0%)	0 (0%)	0 (0%)

\* nd = not defined

\*\* Proportion of uneventful cases unknown

\*\*\* sd = specifically denied, nsd = not specifically denied