A Simplified Nonlinear Model of a Drum Boiler-Turbine Unit

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A DRUM BOILER-TURBINE UNIT.

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ABSTRACT.

In the analysis of power systems it is highly de-
sirable to have models of the different power ge-
nerators. In this paper we present a model for a
drum boiler whose purpose is to describe the gross
behaviour of the boiler. The major control vari-
ables are fuel flow and control valve setting. The
output variables are drum pressure and active out-
put power. The model is verified by experiments on
a 160 MW boiler.

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1. INTRODUCTION.

This paper presents a simple nonlinear model for a
drum boiler-turbine unit having the form

$$\begin{cases} \dfrac{dp}{dt} = \alpha\left[- f(p,u_2) + g(u_1,u_3)\right] \\[2em] P = f(p,u_2) \end{cases} \qquad (1.1)$$

where the state variable p equals drum pressure. The
control variables are fuel flow u_1, control valve
setting u_2 and feedwater flow u_3. The output $P=f$ is
the output power and g is the input power.

It is shown that the model agrees well with measure-
ments for the actual boiler in the range half power to
full power. It is also shown that the model can be
derived using physical arguments. This gives the form
of f and g as

$$f(p,u_2) = \alpha_4\left[u_2 p^{5/8} - \alpha_5\right] \qquad (1.2)$$

$$\alpha g(u_1,u_3) = \alpha_2 u_1 - \alpha_3 u_3, \quad \alpha = \alpha_1/\alpha_4 \qquad (1.3)$$

The model is thus characterized by five parameters
$\alpha_1, \ldots, \alpha_5$.

The structure of function f given by (1.2) is obtained
by several approximations. Other structures are possible.

The model can be used in several different ways, e.g.

o As a boiler-turbine model in power systems studies.

o As a tool to design experiments for delivery tes-
   ting of boilers.

o   To understand how a boiler behaves under different
    operating conditions. In particular to define con-
    cepts like regulating power (reglerstyrka) and
    storage capacitance (buffertkapacitet).

o   To synthesize optimal treajectories for large load
    changes.

The report is organized as follows. Section 2 describes'
the experiments that were used as a basis for the mo-
delling. A derivation of a simplified model based on
physical considerations is given in section 3. In par-
ticular it is shown what assumptions are required in
order to arrive at the simplified model. Some alterna-
tive approaches are also given. A crude method of es-
timating the parameters of the simplified model is gi-
ven in section 4. Section 5 contains a comparison of
the model output with experimental data. It should be
observed that the model parameters are not adjusted
to fit each individual run. In section 6 are given
some of the conclusions about the dynamics of a drum
boiler that can be drawn from the model.

2. EXPERIMENTS.

The experiments were made on the boiler unit P16 and
the turbine unit G16 at Öresundsverket of Sydsvens-
ka Kraft AB in June, 1969. The boiler is an oilfired
drum boiler designed for a maximum power of 160 MW.
The experiments were designed for two tasks:

o to obtain a qualitative understanding of the beha-
   viour of the boiler during transient loads,

o to obtain a detailed linear model for steady state
   operation.

None of the experiments were designed specifically
for the purpose of developing nonlinear mathematical
models valid for a wide operating range. The possibi-
lity to obtain such models was not originally antici-
pated.

A schematic diagram of the boiler-turbine unit is
shown in Fig. 1. In the experiment the variables,
fuel flow, feedwater flow, two attemperator flows
and the control valve position were considered as
inputs. The recorded outputs were drum pressure, ge-
nerated electric power, drum level, temperatures and
pressures in various parts of the system. In the expe-
riments 24 variables were recorded on a datalogger.
In the graphs given in this report only a selection
of these variables will be given. A detailed account
of the experiment is given in [3] .

The major controllers used during normal operation of
the boiler are controllers for air-fuel ratio, drum
level, drum pressure, steam temperature and turbine
power. When these controllers are in operation they
may change control variables which we would like to
have at specific values during the experiment. In ma-
ny experiments the ordinary regulators were therefore
disconnected.
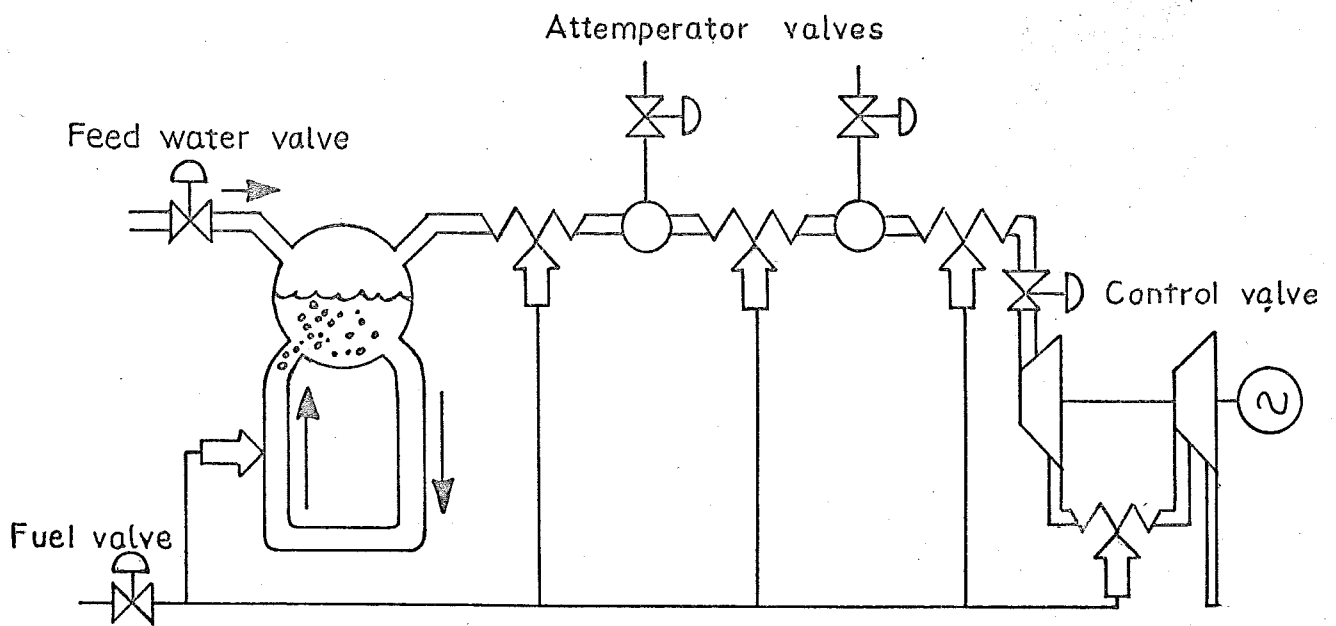
Fig. 1 - Schematic diagram of the boiler-turbine unit.

A list of the experiments discussed in this report is given in Table 2.1. A detailed discussion of each experiment is given below.

Experiment	Power level	Input	Remark
A	140 MW	Fuel flow	Small perturbations. Regulators for steam temperature, drum level and drum pressure (power) disconnected.
B	130 MW	Control valve	Same as A except that the control valve setting is changed.
C	70 MW	Fuel flow	Same as A except that the experiments are done at half power.
D	70 MW	Control valve	Same as C except that control valve setting is changed.
E	90-160 MW	Fuel flow	Wide power range. Drum pressure controller disconnected.
F	75-90 MW	Control valve	Drum pressure controller disconnected.

Table 2.1 - A complete list of experiments discussed in the report.

Experiments A and B.

Both experiments were designed for the purpose of de-
termining linear models for steady state operation.
The input, fuel flow in experiment A and control
valve position in experiment B, was changed manually
according to a prescribed program. The input signal
was chosen on the basis of preliminary experiments
and à priori estimates of system dynamics. The samp-
ling rate was 10 seconds and the duration of the ex-
periment was one hour. The operating conditions were
chosen so that the output power was slightly below
the maximum power. The feedwater flow was also changed
manually in both experiments. This was necessary in
order to keep drum level within acceptable limits.

Fig. 2 and Fig. 3 show the responses of active power,
drum pressure and steam flow in the experiments. It
is clear from these figures that the drum pressure
responds in more or less the same way to changes in
fuel flow and control valve position. The responses
of active power and steam flow are, however, very dif-
ferent in experiment A and experiment B. The smooth
changes of active power and steam flow to a step change
of fuel flow in Fig. 2 are replaced by very fast ini-
tial changes to a step change in control valve setting
in Fig. 3.

In both Fig. 2 and Fig. 3 there is a good qualitative
agreement between responses of active power and steam
flow.

Fig. 2 - Experiment A showing responses of active power, drum pressure and steam flow to changes in fuel and feedwater flows.

Fig. 3 - Experiment B showing responses of active
power, drum pressure and steam flow to chan-
ges in control valve position and feedwater
flow.

Experiments C and D.

These experiments are performed at half-power but are otherwise analogous to experiments A and B. The results of these experiments are shown in Fig. 4 and 5. The behaviour of the system at half-power is similar to that at full power.

Experiment E.

The purpose of this experiment was to study a fairly normal load change from 90 MW to 160 MW (full load). The control valve was fully opened. All regulators except the fuel flow regulator were in operation. The fuel flow was increased manually during the experiment.

The result of the experiment is shown in Fig. 6. The curves indicate that the changes in active power are proportional to the changes in steam flow and drum pressure.

Experiment F.

In this experiment all controllers are in operation except the drum pressure controller which normally controls the fuel flow valve. The control valve is roughly half closed which gives an initial drum pressure of 132 kg/cm^2. The fuel flow is initially set to give 77 MW active power. The control valve is manipulated manually.

The valve is first opened as quickly as possible to yield an output power of 90 MW. This took about 15 seconds. The valve is then manipulated manually in

order to maintain a constant output power. The chan-
ges of major process variables during the experiment
are shown in Fig. 7. As seen from this diagram the
pressure curve has almost a constant slope. The knee
in the pressure at t=200 sec. is due to the changes
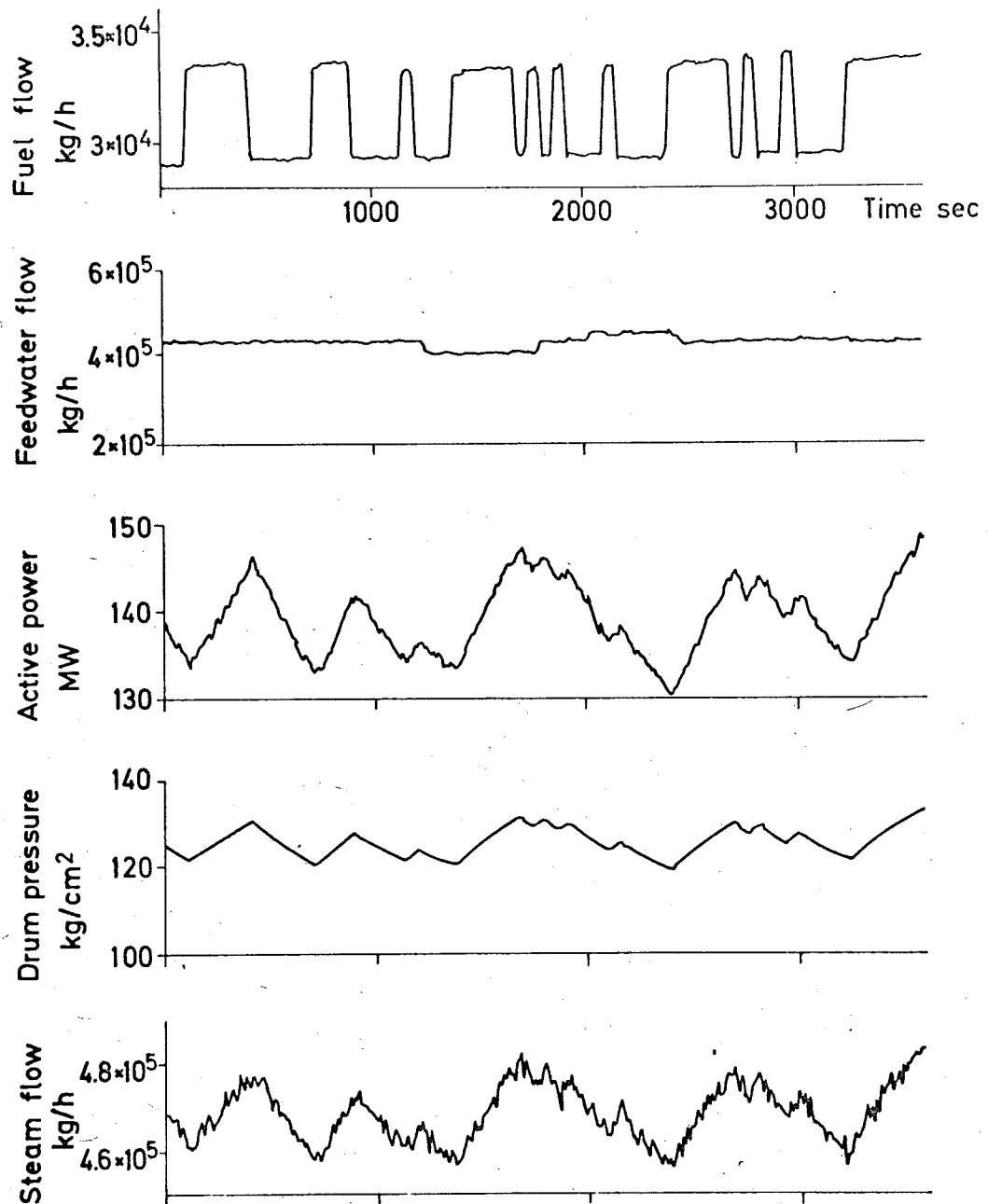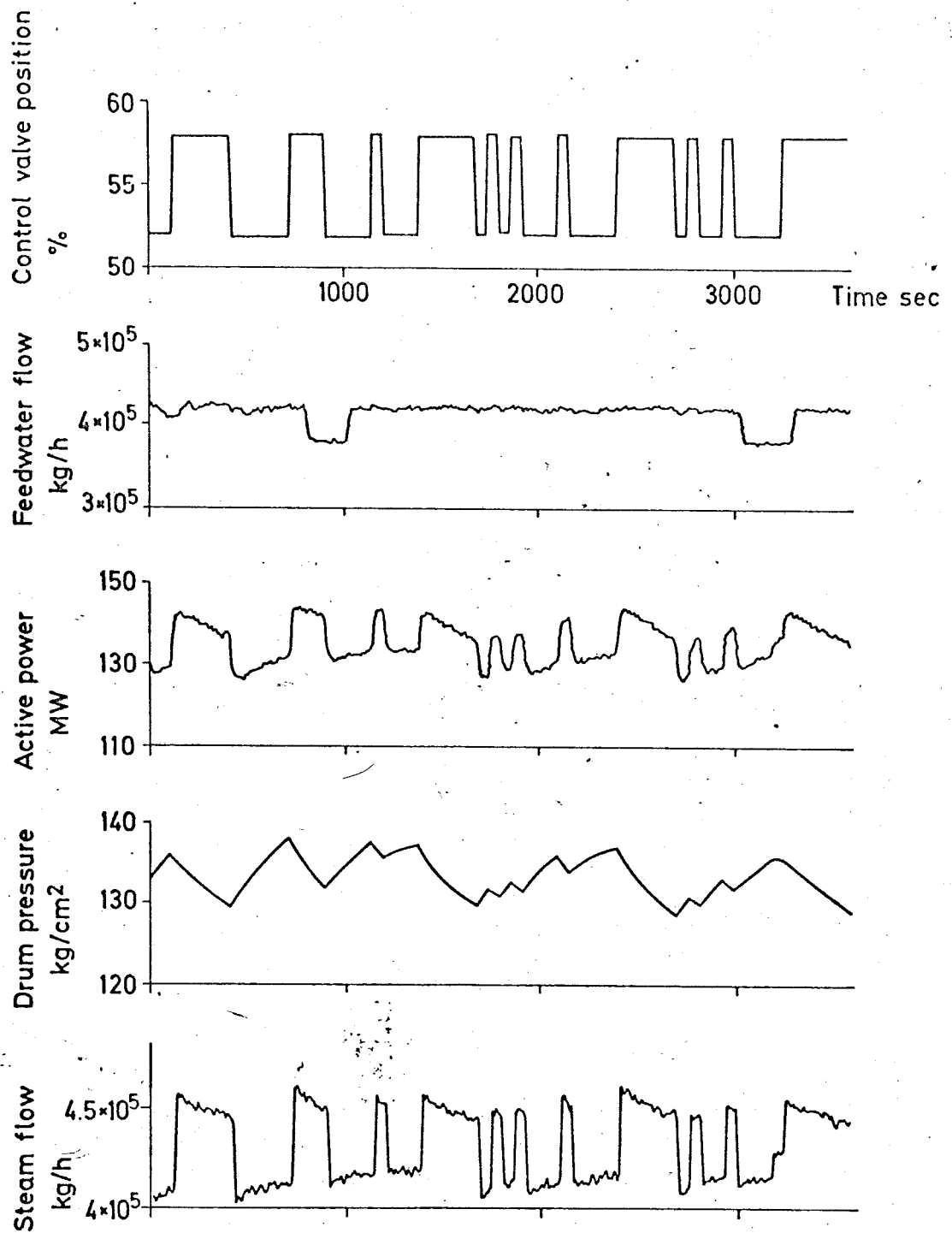in feedwater flow and steam flow.
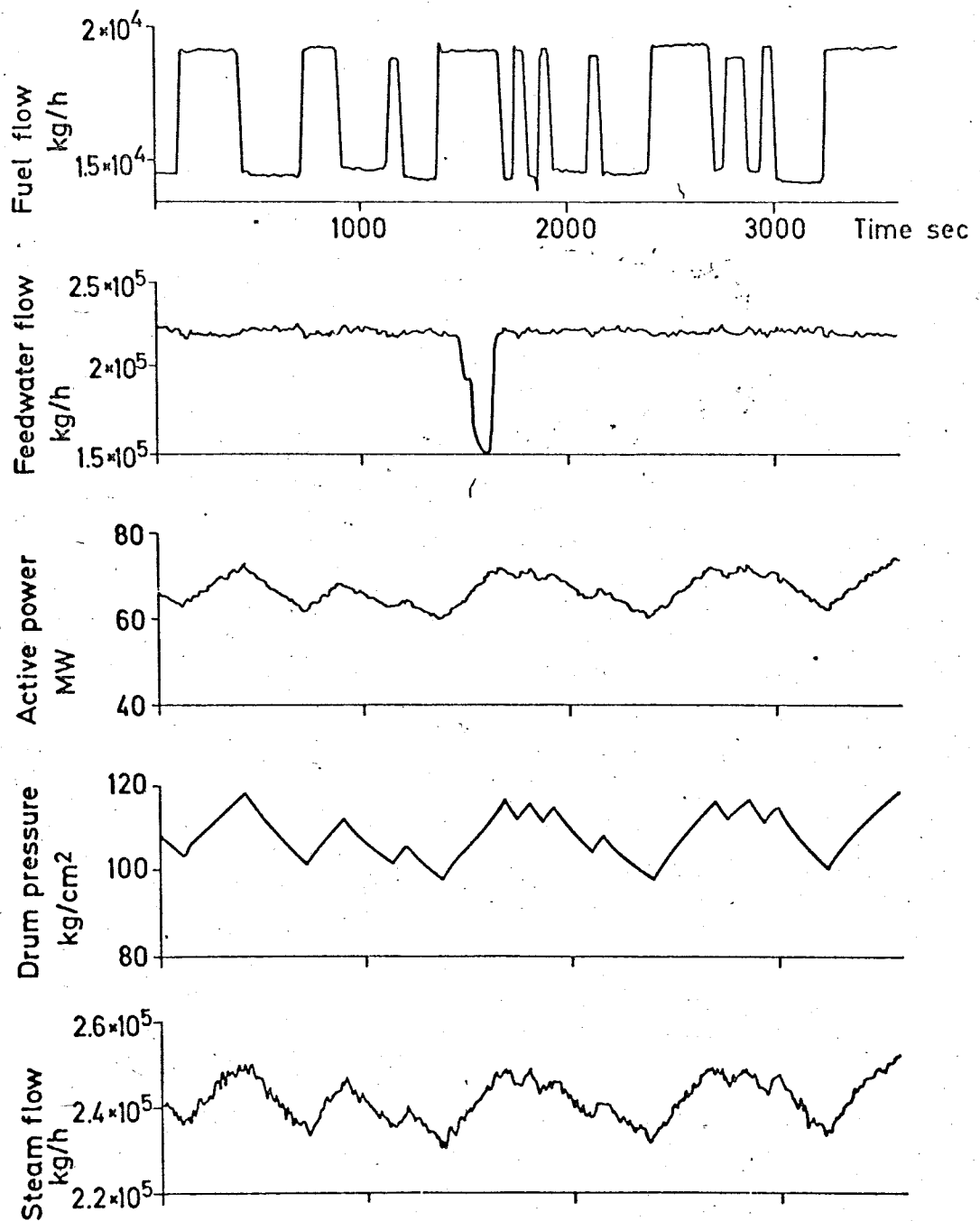
Fig. 4 - Experiment C showing responses of active power, drum pressure and steam flow to changes in fuel and feedwater flows.

Fig. 5 - Experiment D showing responses of active
power, drum pressure and steam flow to chan-
ges in control valve position and feedwater
flow.
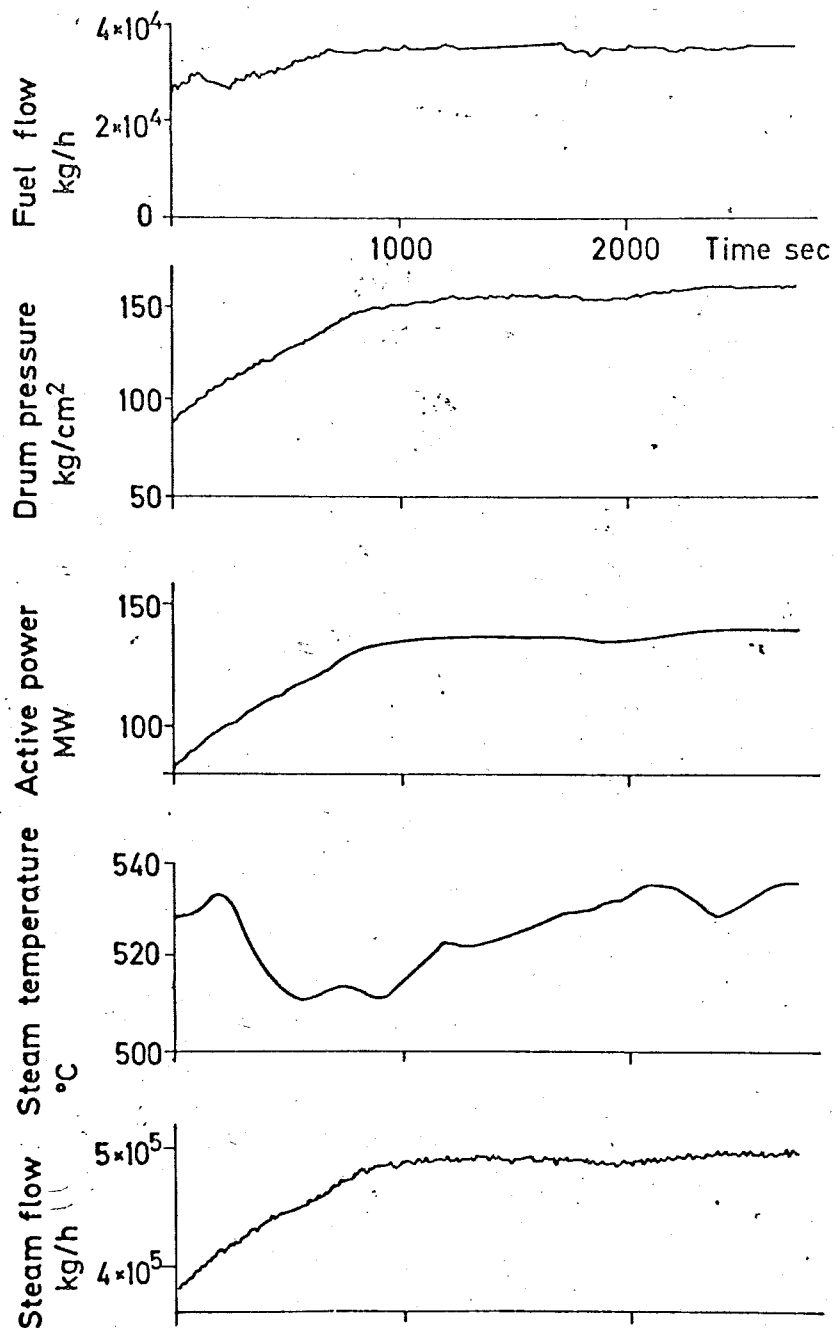
Fig. 6 - Experiment E showing responses of active power, drum pressure and steam temperature after reheater to a changing fuel flow.

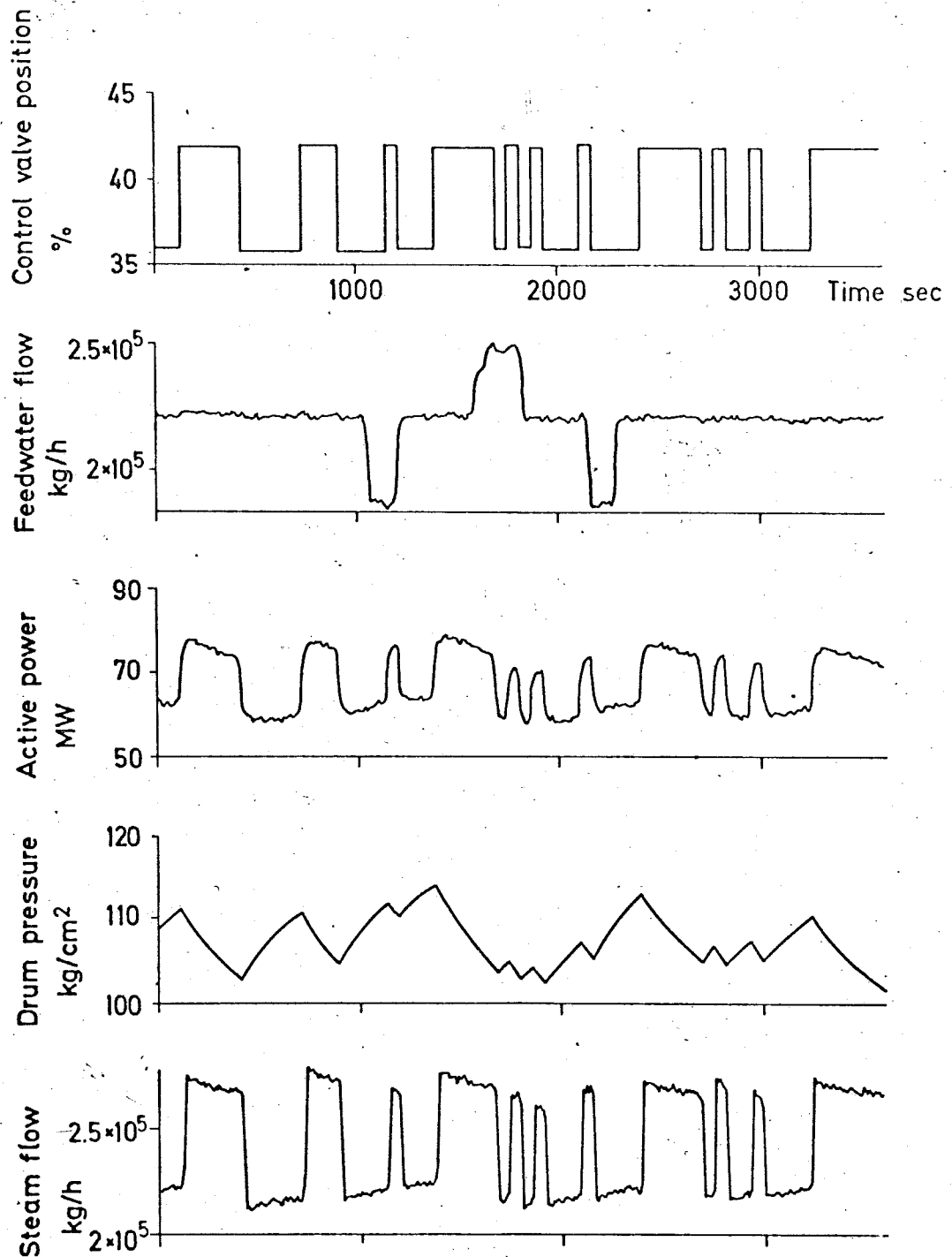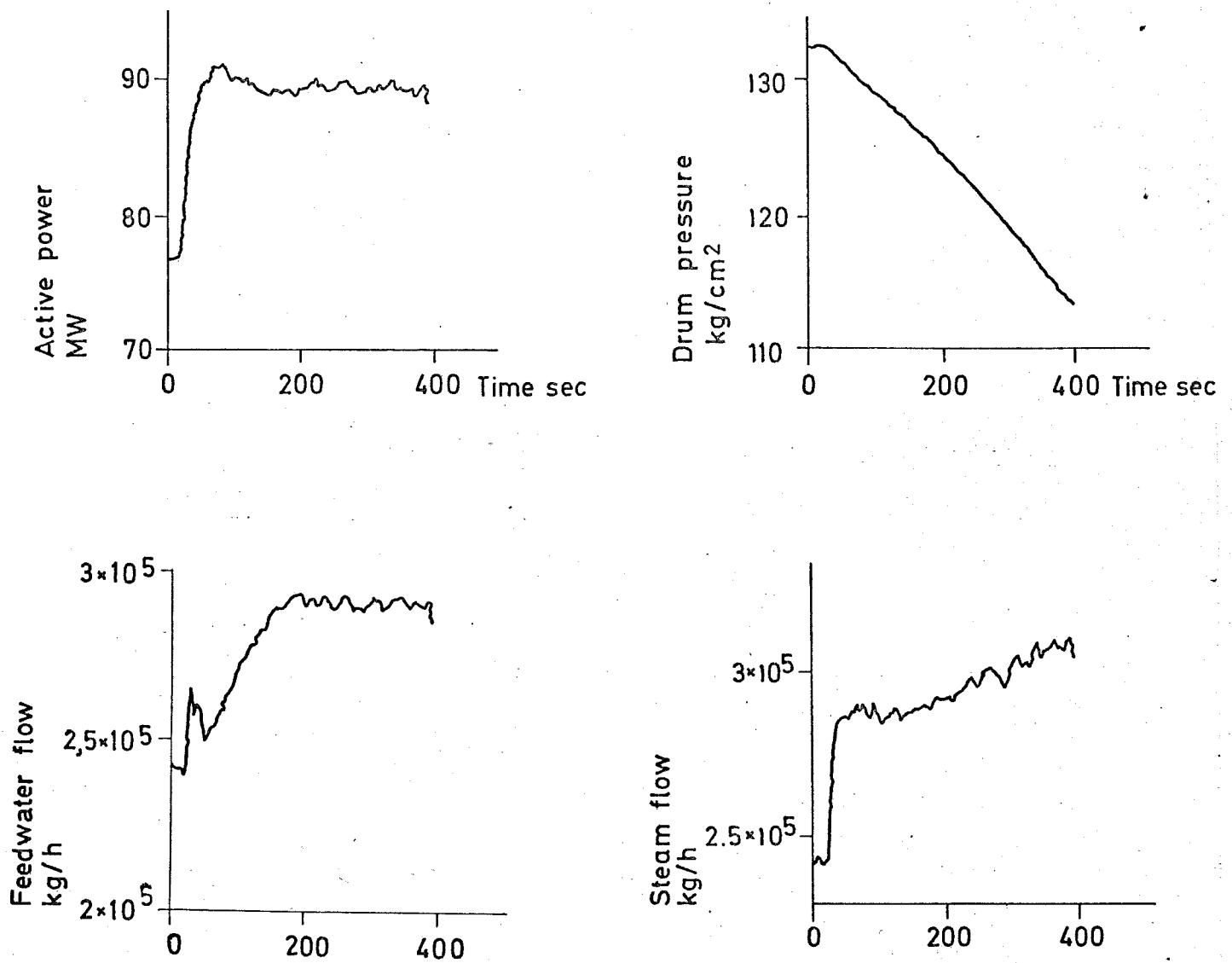**Fig. 7** - Experiment F showing responses of active
power, drum pressure and steam flow to a
change in control valve position (not shown)
and feedwater flow.

3. A SIMPLE PHYSICAL MODEL.

The simplified model was developed by a combination
of data analysis and physical arguments. The work
was significantly guided by the results of a concur-
rent study [3] aimed at developing a detailed linear
model of the boiler. The results of the experiments
described in the previous section can be summarized
by the responses, shown in Fig. 8.
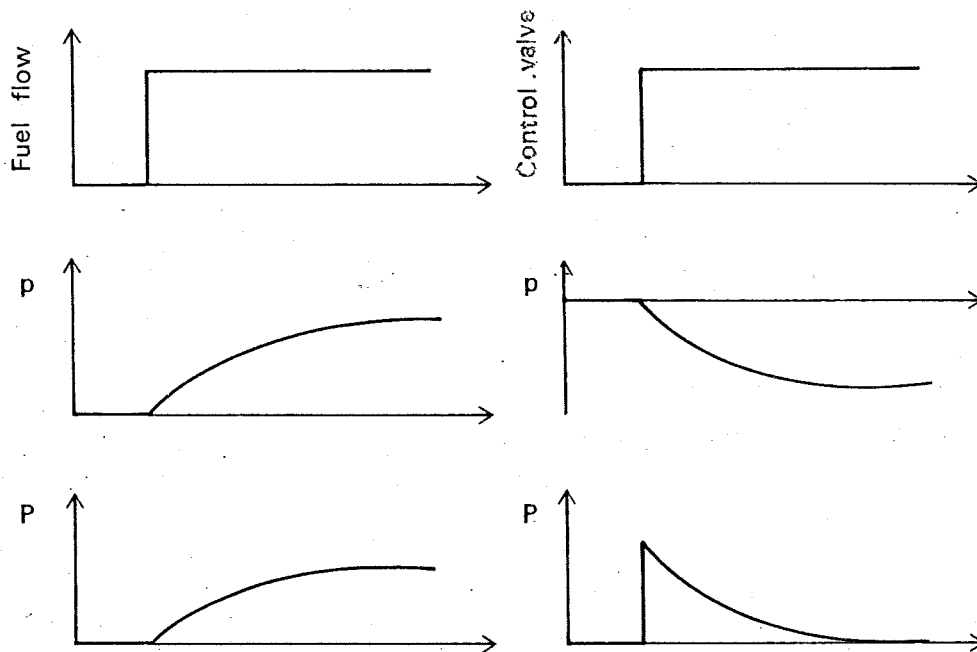
Fig. 8 - Shows qualitative responses of drum pressure
(p) and output power (P) to step changes in
fuel flow and control valve. Notice that the
"time constants" associated with all the va-
riables are approximately the same.

The behaviour shown in Fig. 8 can be explained by a
first order model given by the eq. (1.1) and (1.2),
where f is linear in x. A closer analysis of the ex-
perimental data indicates, however, that a linear mo-

del is not sufficient. The possibility of using a first order model is also supported by the observation that the steam temperatures do not greatly affect the responses. We will thus attempt to derive a physical model of first order and find what approximations are needed for this purpose.

Energy Balance.

The starting point in the modelling is to consider the boiler as a reservoir of energy, as illustrated by the block diagram of Fig. 9.

Fig. 9 - A schematic picture of the boiler as an energy reservoir.

Energy is fed to the reservoir by the fuel and the feedwater. The boiler-turbine unit delivers energy in the form of active power. The energy is stored in iron masses, water and steam. The amount of energy stored in each part is a complicated function of temperature and pressure. An energy balance gives

$$\frac{dH}{dt} = P_i - P_o \qquad (3.1)$$

where H is the total energy stored in the boiler, P_i the input power and P_o the output power. To obtain a mathematical model it is now necessary to express H, $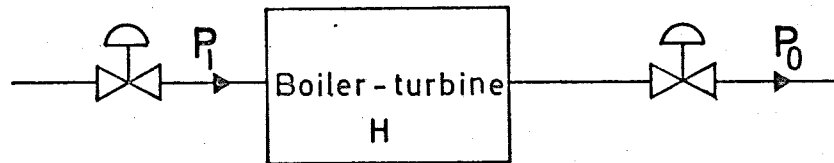P_i$ and P_o in terms of significant variables in the boiler. Since the total energy is distributed over the boiler in a rather complicated way it is in general necessary to introduce temperatures and pressures all over the system as state variables. However, the experiments described in section 2 indicate that the gross features can be described by a first order dynamics. We will thus try to express the stored energy as a function of one variable, namely the drum pressure. This means in essence, that it is assumed that the distribution of the energy over the boiler does not greatly change over the operating range. The reason for choosing drum pressure rather than any other variable is that drum pressure is a significant measure of the state of the boiler. Furthermore, it is measured and the rate of change of drum pressure is an important constraint in the operation of the boiler.

Input power P_i is assumed to be a function of fuel flow and feedwater power. The input power associated with air flow and coolant flows to the attemperators are neglected. They are indeed small and their inclusion in the model gives only marginal effects.

The output power is a function of the control valve position and the steam temperature and pressure at the turbine.

There are two other output flows from the boiler which both represent power outputs, namely the flows of combustion gases and condensate. The flow of combustion gas is approximately proportional to the fuel flow. If this flow is neglected it only means a reduced effect of the fuel flow. Similarly if the enthalpy of

the condensate is assumed constant, the condensate flow can be taken into account by changing the feed-water flow accordingly.

After these preliminaries we will now develop the model in detail by expressing the stored energy H, the input power P_i and the output power P_o as functions of the control variables and the state variable.

Stored Energy.

The major part of the boiler energy H is stored in iron and water masses. The stored energy thus depends on material temperatures, which are essentially determined by steam temperatures, steam pressures and the load. The energy of steam masses is a minor part.

The critical simplifying assumption is that the distribution of energy stored in iron, water and steam masses do not change during transients. This implies that any energy dependent variable could be used as a measure of stored energy. Tube material temperatures are usually not measured and for good operation the boiler is constructed so as to keep turbine inlet temperatures constant over a wide load range. However, the drum pressure will change significantly according to changing load. For this reason and others stated previously drum pressure is chosen as the measure of energy storage.

Assuming that mass content of the drum is constant the energy storage of water and steam can be approximated by

$$H = H(p) = ap + b \hspace{3cm} (3.2)$$

in the pressure range 50 - 150 bar, where p is the drum pressure and a and b constants. According to our energy distribution assumption this is believed to be a reasonable approximation of total energy storage of the boiler.

Input Power.

Input and output power will be computed with respect to the enthalpy level of the drum defined by the drum pressure.

Boiler input power depends on fuel and feedwater flow. The power of feedwater is the flow multiplied with the enthalpy difference between feedwater and saturation state in the drum. For simplicity the enthalpy difference is assumed to be constant. This is further discussed in section 5. Input power is thus modelled as

$$P_i = a_1 u_1 - a_2 u_3 \hspace{3cm} (3.3)$$

where u_1 is the fuel flow, u_3 the feedwater flow and a_1, a_2 constants. It is assumed that the efficiency of the boiler is constant. This also implies that the air flow during fast changes of the fuel flow always can be manipulated to meet the demand.

Output Power.

Neglecting the pressure drop across superheaters and turbine, active power can be modelled as steam flow multiplied by the enthalpy drop across the turbine, i.e.

$$P = b_1 q \Delta h \qquad (3.4)$$

where b_1 is a constant and

$q = q(u_2, p)$ steam flow

$\Delta h = \Delta h(p)$ enthalpy drop across turbine.

The dependence of temperature is as stated before neglected. Eq. (3.4) implies that active power is zero when drum pressure is zero. This is not true since the flow is not free from losses. This can be taken into account by adding a constant b_2 to eq. (3.4). Output power is then modelled as

$$P_o = b_1 q \Delta h + b_2 \qquad (3.5)$$

Assume that

$$q = b_3 u_2 \sqrt{p} \qquad (3.6)$$

where b_3 is a constant and it is assumed that u_2 is proportional to the open valve area. Using data from Exp. E the coefficient b_3 is a determined. In Fig. 10 field data and computed values of steam flow, using $b_3 = 41.5$, are shown.

The agreement is very good and eq. (3.6) is accepted as the steam flow.
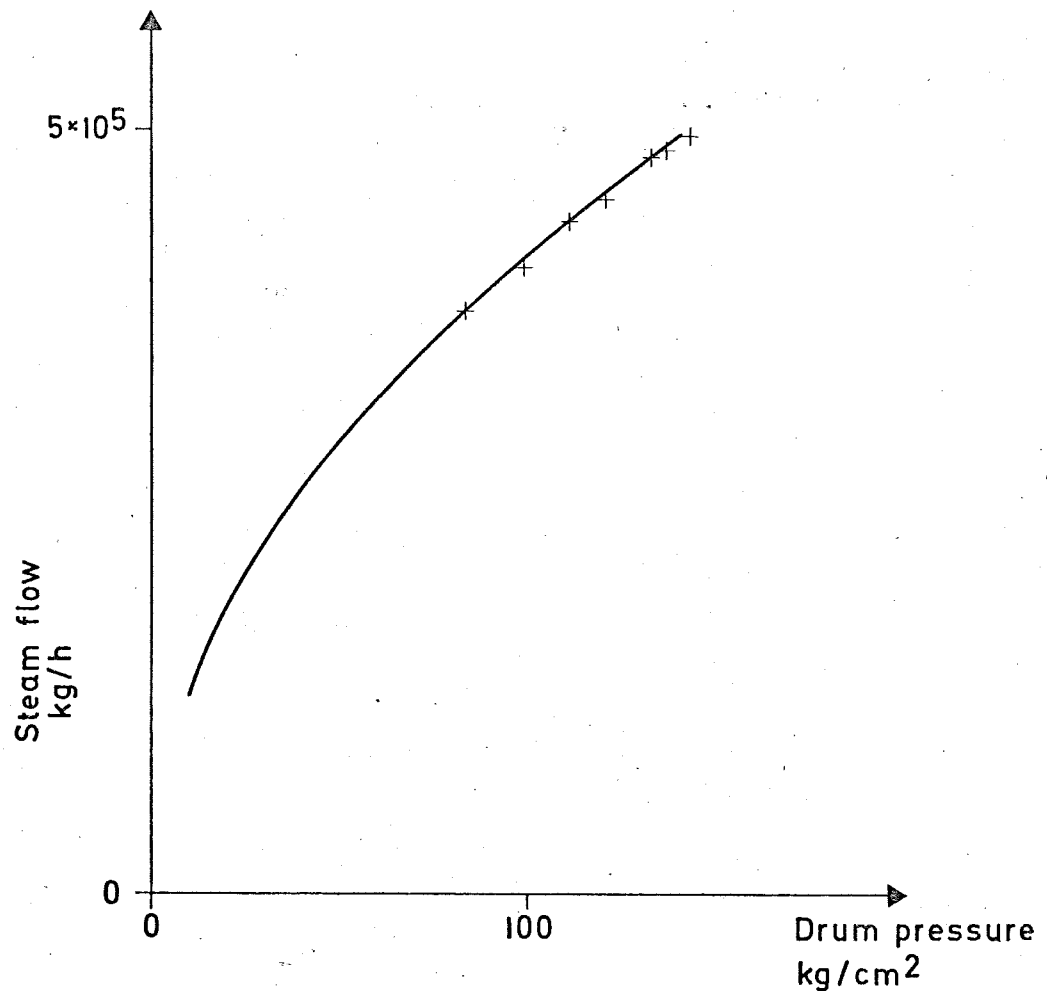
Fig. 10 - Steam flow in Exp. E as a function of drum
pressure for fully opened control valve.
(x) is field data and the continuous curve
is computed according to eq. (3.6).

To compute the output power P_o we still need an ex-
pression for the enthalpy drop across the turbine. In
a power plant the main part of the power is generated
by the middle and low pressure parts of the turbine.
The output power is therefore estimated from the en-
thalpy drop in the pressure interval 1 to 35 bar. As-
suming inlet temperature T_o and condenser pressure p_o
constant the theoretical enthalpy drop for $T_o = 530°C$
and $p_o = 0.04$ bar is shown in Fig. 11. The curve will
pass close to origo and we assume that

$$\Delta h = b_4 p_i^r \qquad (3.8)$$

where p_i is the turbine inlet pressure.
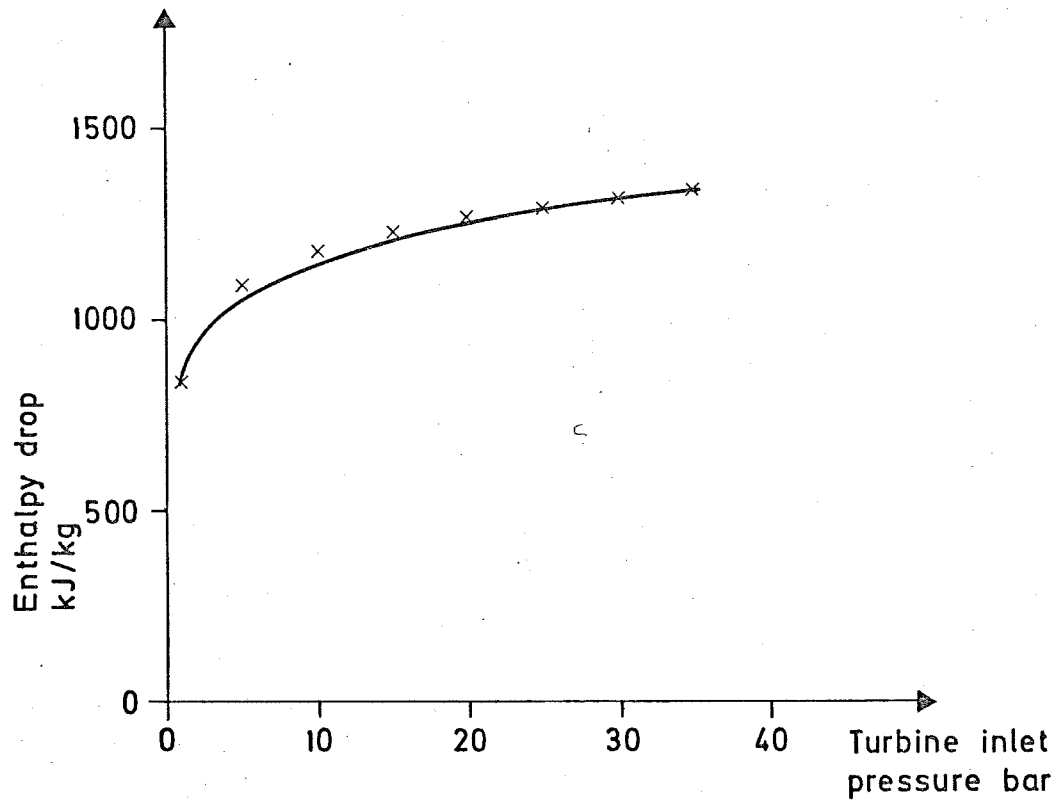
Fig. 11 – The theoretical enthalpy drop across a turbine. Steam inlett data $T_o = 530^{\circ}C$; 1 bar $\leq p \leq$ 35 bar and condenser pressure $P_o = 0.04$ bar. (x) is data from steam tables, and the continuous curve is computed according to eq. (3.8), using $r = 1/8$.

Fig. 11 shows the result, using $r = 1/8$, and b_4 determined for good fit. There is a clear difference but the accuracy is believed to be satisfactory. Of course, there is the possibility to determine the value of r in this special case more accurate. The value of r will change very little with changing inlet steam temperature and the pressure range is not less than 50 bar.

The drum pressure is taken to be proportional to the turbine inlet pressure p_i.

Accepting these approximations the output power is

$$P_o = \alpha_4 \left(u_2 p^{5/8} - \alpha_5 \right) \qquad (3.9)$$

where α_4 and α_5 are constants. The constants can be estimated from a diagram showing output power as a function of drum pressure.

Summary

Summing up the results we find that the boiler can be modelled by the equations (3.1), where the stored energy H is given by (3.2), the input power P_i by (3.3) and the output power by (3.9). Hence

$$a \frac{dp}{dt} = -\alpha_4 \left(u_2 p^{5/8} - \alpha_5 \right) + a_1 u_1 - a_2 u_3$$

Introducing the normalized coefficients

$$\alpha_1 = \alpha_4/a, \quad \alpha_2 = a_1/a, \quad \alpha_3 = a_2/a \qquad (3.10)$$

we get

$$\begin{cases} \dfrac{dp}{dt} = -\alpha_1 \left(u_2 p^{5/8} - \alpha_5 \right) + \alpha_2 u_1 - \alpha_3 u_3 \\[2em] P_o = \alpha_4 \left(u_2 p^{5/8} - \alpha_5 \right) \end{cases} \qquad (3.11)$$

which can be written as (1.1), (1.2) and (1.3)
with $\quad \alpha = \alpha_1 / \alpha_4$.

The model (3.11) is a first order nonlinear differential equation. If the input signals $u_1(t)$, $u_2(t)$ and $u_3(t)$ are continuous functions and $p(t) > 0$, then there exists a unique solution to eq. (3.11). Assuming that u_1, u_2 and u_3 are constants the stationary solution is given by

$$p = \left(\frac{\alpha_2 u_1 - \alpha_3 u_3 + \alpha_5 \alpha_1}{\alpha_1 u_2} \right)^{8/5} \tag{3.12}$$

The steady state output is given by

$$P_o = \frac{\alpha_4}{\alpha_1} \left(\alpha_2 u_1 - \alpha_3 u_3 \right) \tag{3.13}$$

This implies that output power equals input power in the steady state.

Linearization of eq. (3.11) gives

$$\frac{dp}{dt} = - \frac{5 \alpha_1 \bar{u}_2}{8 \bar{p}^{3/8}} \Delta p - \alpha_1 \bar{p}^{5/8} \Delta u_2 + \alpha_2 \Delta u_1 - \alpha_3 \Delta u_3 \tag{3.14}$$

where Δv is the deviation of the variable v from its steady state value $\bar{v}$. The time constant T is

$$T = \frac{8\bar{p}^{3/8}}{5\alpha_1\bar{u}_2} = \frac{8a\bar{p}}{5a\alpha_1\bar{u}_2\bar{p}^{5/8}} = \frac{8}{5} \cdot \frac{H(\bar{p}) - H(0)}{P(\bar{p}) - P(0)} \qquad (3.15)$$

where the last equality follows from (3.2), (3.9) and (3.10).

Since the drum pressure p is assumed always to be greater than zero the linearized equation (3.18) is asymptotically stable. The time constant is inversely proportional to the control valve position $\bar{u}_2$. For constant drum pressure this means that a reduction of $\bar{u}_2$ to half its previous value will double the time constant T. Recalling the picture of the boiler as an energy reservoir we find that the time constant of the derived model can be interpreted in the usual manner as stored energy divided by heat flow.

Defining the efficiency of the boiler-turbine unit as

$$\eta = \gamma \cdot \frac{P_o}{u_1} \qquad (3.16)$$

where P_o is the output power in MW and u_1 is the fuel flow in kg/hour. The constant γ is a factor converting the oil flow into an energy flow. Using eq. (3.13) we get

$$\eta = \gamma \left[\frac{\alpha_4\alpha_2}{\alpha_1} - \frac{\alpha_4\alpha_3}{\alpha_1} \cdot \frac{u_3}{u_1} \right] \qquad (3.17)$$

The boiler model efficiency is thus constant if the ratio between feedwater and fuel flow are constant. During short time periods the efficiency can be ~~in-~~ temporarily/ creased using the storage capacity of the drum by decreasing the feedwater flow.

Another important property of the model is that output power will respond directly to a change in control valve position. This is approximately the physical behaviour shown in Exp. B and D. The smooth responses in experiments are due to the large reheater of this particular boiler.

Finally it should be emphasized that the structure of the function f, that is the output power is not unique. It not only depends on the set of approximations used but also of the approach taken when defining the reference level for input and output power.

4. CRUDE PARAMETER ESTIMATES.

The nonlinear boiler-turbine model developed contains five unknown parameters $\alpha_1, \ldots, \alpha_5$. In this section we will estimate the numerical values of these parameters for the boiler used in the experiments. A schematic diagram of this boiler as well as the experimental data, which will be used here, were shown in section 2. The parameters will be determined from at least two different experiments in order to test the invariance. Small differences should indicate a suitable model structure. The type of experiments to be used is discussed and a suitable set recommended.

Parameters α_4 and α_5.

It follows from the physical arguments of section 3 that the output power is related to drum pressure by the equation

$$P_o = f(p, u_2) = \alpha_4 \left(u_2 p^{5/8} - \alpha_5 \right) \tag{4.1}$$

Notice that this equation also holds in the transient stage. To determine the parameters α_4 and α_5 (and also to determine if the physical arguments leading to (4.1) are reasonable) it is thus necessary to have an experiment where p and P_o vary over a reasonable range. Data from experiment E are shown in Fig. 12 together with curves, computed from (4.1).
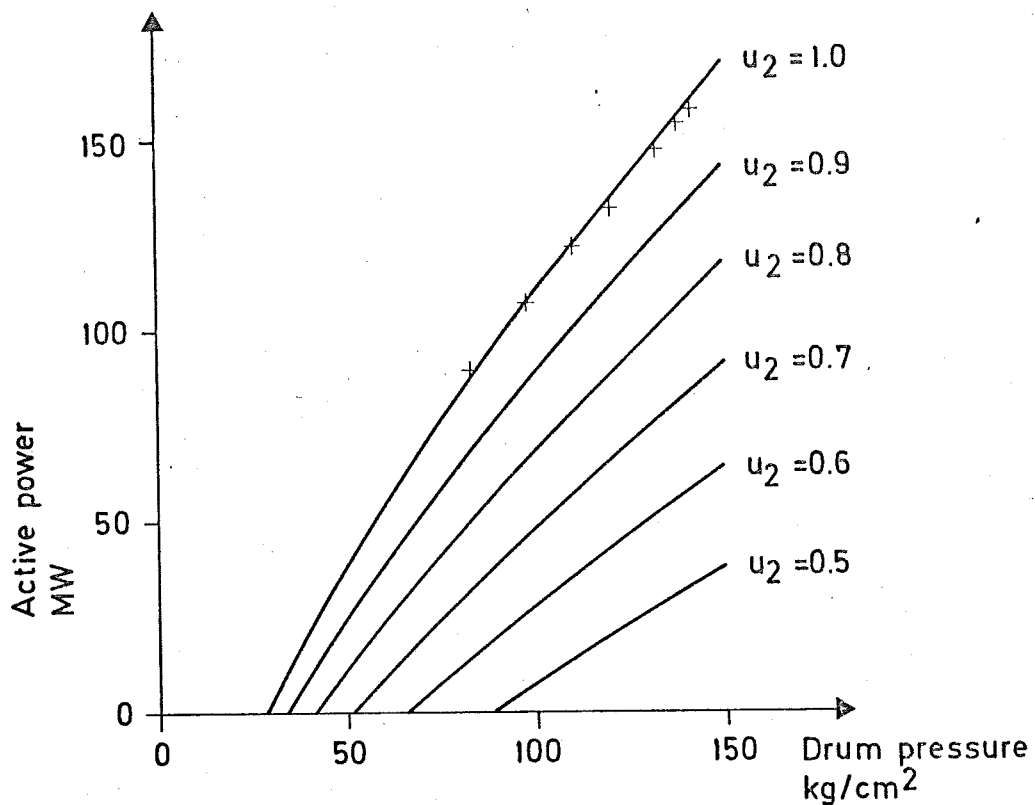
Fig. 12 - Active power as a function of drum pressure.
Field data (x) is taken from Exp. E. The
continuous curves are computed using eq.
(4.1) and $\alpha_4 = 11.45$ and $\alpha_5 = 8.2$.

The control valve position is normalized to the in-
terval [0,1]. The parameters α_4 and α_5 are simply es-
timated using two points from experimental data. We
get

$$\alpha_4 = 11.45$$
$$\alpha_5 = 8.2$$
<div style="text-align: right">(4.2)</div>

The family of curves in Fig. 12, corresponding to dif-
ferent values of u_2, give for every drum pressure the
active power generated. The diagram can be used to cal-
culate the instantaneous power response to a step
change of control valve position. Fig. 12 will also
be used to compute the normalized values of control
valve position used in the simulations.

Parameter α_1.

The parameter α_1 will be estimated from a dynamical experiment. From the model equation (3.11) it is clear that if u_1 and u_3 are constant the change $\Delta dp/dt$ of dp/dt at time t_1 due to a change Δu_2 of u_2 is

$$\Delta \frac{dp}{dt}(t_1) = -\alpha_1 p^{5/8}(t_1)\Delta u_2(t_1) \qquad (4.3)$$

An estimate of α_1 is easily obtained using data from Exp. B, where the boiler was excited by u_2, using a square wave type signal. In Fig. 13 the first part of the drum pressure response is shown. We chose to determine $\Delta dp/dt$ at $t_1 = 400$ sec. Using the construction in Fig. 13 we get

$$\Delta \frac{dp}{dt}(t_1) = \frac{20}{400} \text{ kg/cm}^2\text{s} \qquad (4.4)$$
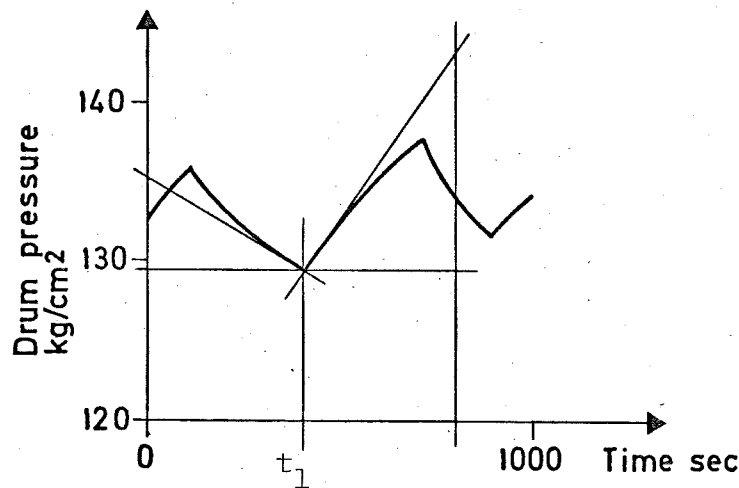

Fig. 13 - Construction to determine $\Delta dp/dt$ of drum pressure response from Exp. B.

The change $\Delta u_2(t_1)$ in normalized units is read in
Fig. 12 knowing the drum pressure at $t_1 = 400$ sec. and
the active power before and after this time. The va-
lues of the active power is determined from the const-
ruction in Fig. 14. Note that the value of active
power after the change is extrapolated using the con-
tinuation of the response. This is necessary since
the model assumes a momentarily response, but the
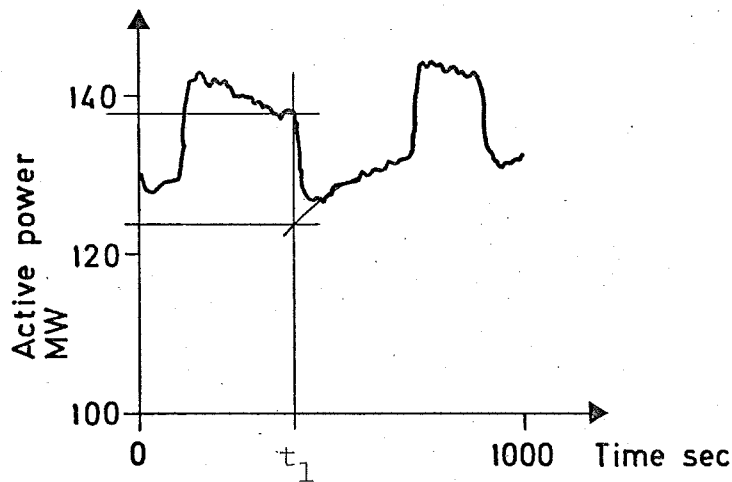real process shows a more smooth response.

Fig. 14 - Construction to determine the values of ac-
tive power before and after the change of
u_2 at $t_1 = 400$.

From Fig. 12 the change $\Delta u_2(t_1)$ is found to be

$$\Delta u_2(t_1) = -0.064 \tag{4.5}$$

All variables required to determine α_1 are now known.
The same method can be applied to Exp. D. The resul-
ting estimates of α_1 are shown in Table 4.1.

An experiment of the type, used in Exp. F, is especial-
ly attractive when estimating α_1. If the fuel flow and

feedwater flow are kept constant and the control valve position is manipulated to give a step shaped response in active power it is seen from the model equation that this should result in a constant derivative of drum pressure. This is verified by Exp. F, but here the feedwater flow has also been changed. The influence of the change appears as a bending of the drum pressure response.

Experiment	Estimate of α_1
B	0.038
D	0.033
F	0.036

Table 4.1 - Estimated values of parameter α_1, using three different experiments.

The estimate of parameter α_1, using Exp. F, is also given in Table. 4.1.

The variations of the estimate are not alarmingly large. Model sensitivity to parameter variations will be further commented on in section 5.

Parameter α_2.

Using the same type of arguments as when deriving eq. (4.3) a formula to estimate parameter α_2 is

$$\alpha_2 = \frac{\Delta \frac{dp}{dt}(t_1)}{\Delta u_1(t_1)} \tag{4.6}$$

The different values obtained at $t_1 = 400$ sec. from two experiments are given in Table 4.2. The change $\Delta u_1(t_1)$ is measured in ton/hour.

Experiment	Estimate of α_2
A	0.018
C	0.022

Table 4.2 - Estimated values of parameter α_2, using two different experiments.

Parameter α_3.

The remaining parameter is α_3. To assure an acceptable accuracy in steady state values of drum pressure this parameter is determined from steady state values. From several estimates we chose a reasonable mean value

$$\alpha_3 = 4.4 \cdot 10^{-4} \tag{4.7}$$

Recommended Experiments.

Summarizing the experience, obtained by applying the estimation procedure discussed in this section, the following recommendations can be made:

o Make one experiment, where the steam valve is suddenly changed and then manipulated in order to give a constant output power. This experiment will give a drum pressure curve with a constant slope (like in Exp. F) from which the parameter α_1 can

be determined. Notice that it is essential to keep the feedwater flow constant during the experiment.

o   The parameter α_2 can be determined from perturbation experiments when small changes in the fuel flow are made (similar to Exp. A and C). It is recommended to make the experiments at different power levels.

o   The parameter α_3 can be determined from steady state values or from a perturbation experiment when the feedwater flow is changed.

o   Make one experiment where the control valve is fully open and the fuel flow is increased from low power to full power. This experiment makes it possible to determine the function (4.1) relating output power to drum pressure and to determine the parameters α_4 and α_5. (Exp. E was of this type.) If possible the experiment should also be repeated for different settings of the steam valve.

These experiments will give rough estimates of the model parameters directly. Using more sophisticated data analysis it is also possible to get more accurate estimates of the parameters if the experimental data is analysed using nonlinear identification techniques.

5. COMPARISON WITH EXPERIMENTS.

The comparison is based on approximate mean values of numerical parameter values developed in the previous section. The model for Öresundsverket power station unit P16-G16 then is

$$\frac{dp}{dt} = - 0.035\left[u_2 p^{5/8} - 8.2\right] + 0.02u_1 - 4.4 \cdot 10^{-4}u_3$$

$$P = 11.45\left[u_2 p^{5/8} - 8.2\right]$$

(5.1)

In the sequel we will discuss efficiency, steady state values and time constants. The model responses to the input signals used in the experiments are also shown.

Efficiency.

From a set measurements including Exp. A, B, C, D, E and F we obtain

$\eta = 0.395 - 0.405$ full load range
$\eta = 0.340 - 0.360$ half load range

The efficiency of the boiler-turbine unit is thus decreased when load is decreased. The theoretical values of model efficiency derived from eq. (3.21) inserting steady state values from Exp. A, B, C and D are within the interval $\eta = 0.395 - 0.415$. The efficiency of the boiler model is thus roughly constant over a wide load range while the efficiency of the plant decreases with decreasing load. In the simulations this discrepancy is taken care of by adjusting the fuel flow so that an efficiency of 0.405 is obtained in all cases.

Steady State Values.

It is important that the model predicts steady state
values accurately since the model should cover at
least the upper half of the load range. The steady
state value of drum pressure does also influence the
increment in active power when e.g. control valve po-
sition is altered. In Table 5.1 computed and measured
steady state values of drum pressure are given. The

| Expe- | Drum pressure | |
riment	Mea-sured	Model
A	125	125.2
B	132.5	135.6
C	108	106.7
D	109	110.0

Table 5.1 - Steady state values of drum pressure.
          Measured and computed from the model (5.1).

maximum difference is roughly 3 kg/cm^2 which means
about 3 MW active power when control valve is fully
opened. The covered load range is from 70 MW to
160 MW active power. The percental error then range
from 1.8% to 4.3%.

Time Constants.

An expression for the time constant of the linearized model equation is given by eq. (3.19). Using the initial steady state values from the four experiments A, B, C and D the time constant can then be evaluated from eq. (3.19). The result is given in Table 5.2.

Experiment	T sec.
A	280
B	307
C	353
D	350

Table 5.2 - Time constant T for four different expe-
riments. Computed from the model (5.1).

The maximum likelihood identification method has also been applied to determine linear models relating the input variables, fuel flow and control valve position to the output variables, drum pressure and active power. The dominant time constant found was within the interval 200 - 800 sec. The time constant increased when decreasing the load. This indicates that the model responses will appear a little too fast but the load dependence of the time constant is correct.

Simulations.

The computed model responses compared to the measured
ones for the five experiments A through F are given
in Fig. 15-19. Since the control valve position was
not recorded automaticly in the experiments no calib-
rating curve referring real values to normalized can
be computed with an acceptable degree of accuracy. In
the simulations mean value and deviations for u_2 was
computed in one point and then used throughout the
experiment. All other input sequences used in the si-
mulations are the measured sequences. Note that the
steady state value of model responses is altered to
agree with the measured ones. The real error is pre-
viously given in Table 5.1.

Inspecting the discrepancies of responses there are
deviations which require some comments.

In Fig. 16 changes of feedwater flow at t∿1000 sec.
cause knees in the drum pressure response of the mo-
del which are not present in the measured curve. On
the other hand, in Fig. 17 and 18 the effect of feed-
water is in accordance with measurements.

The discrepancies of active power responses at the
time of changes in Fig. 16 and 18 can be explained
by two arguments. The control valve position exciting
the model is computed and not the real input signal.
This is clearly causing the disagreement at time
t=3200 in Fig. 16. The smooth shape of measured ac-
tive power curves is caused by the reheater of the
boiler. The reheater is not included in the model
which partly explains the differences. On this point
the model behaviour can be improved by introducing
a differential equation for the reheater. This is
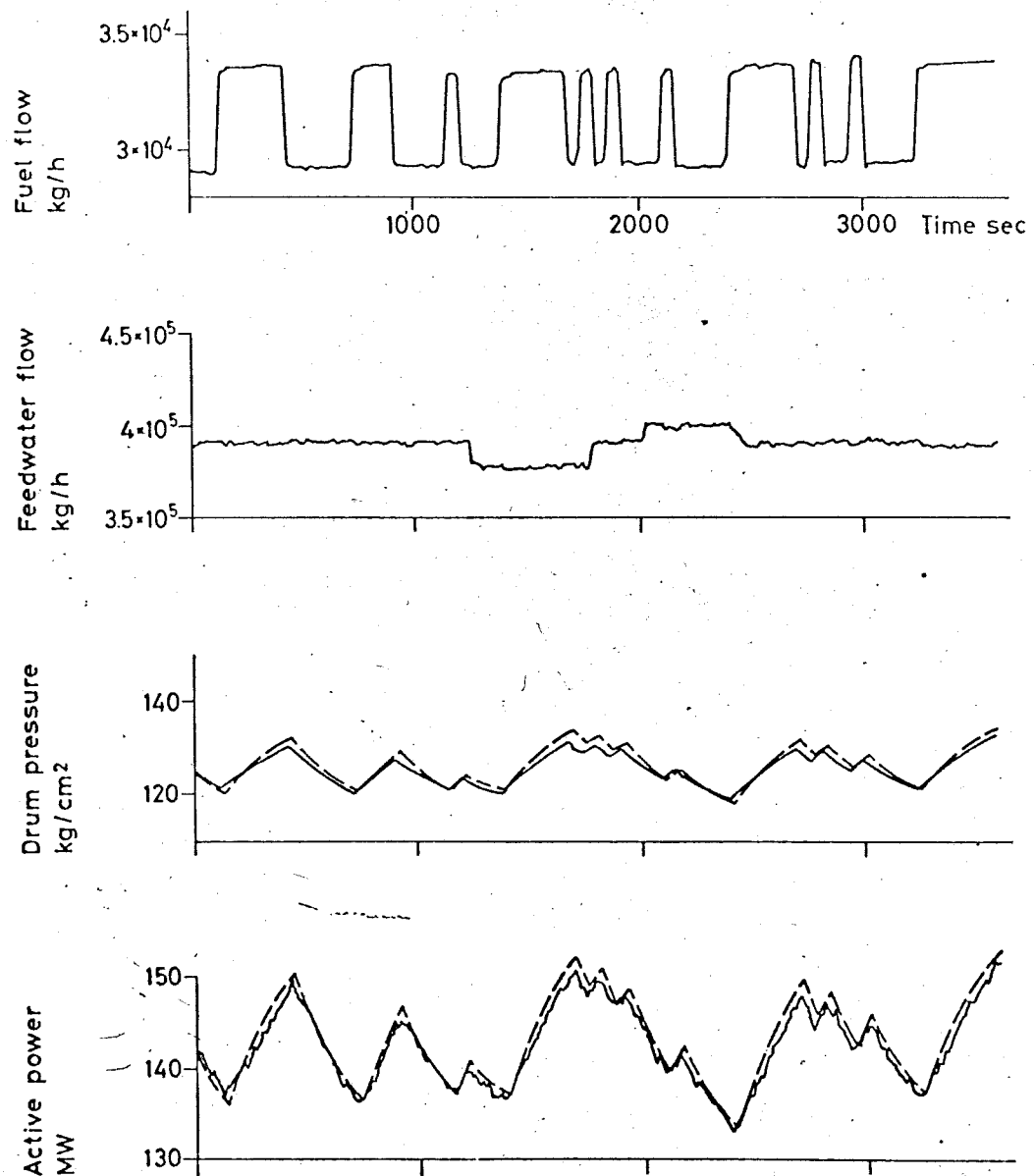easily done but at the expense of increased model
complexity.

Fig. 15 – Comparison of measured boiler-turbine (solid)
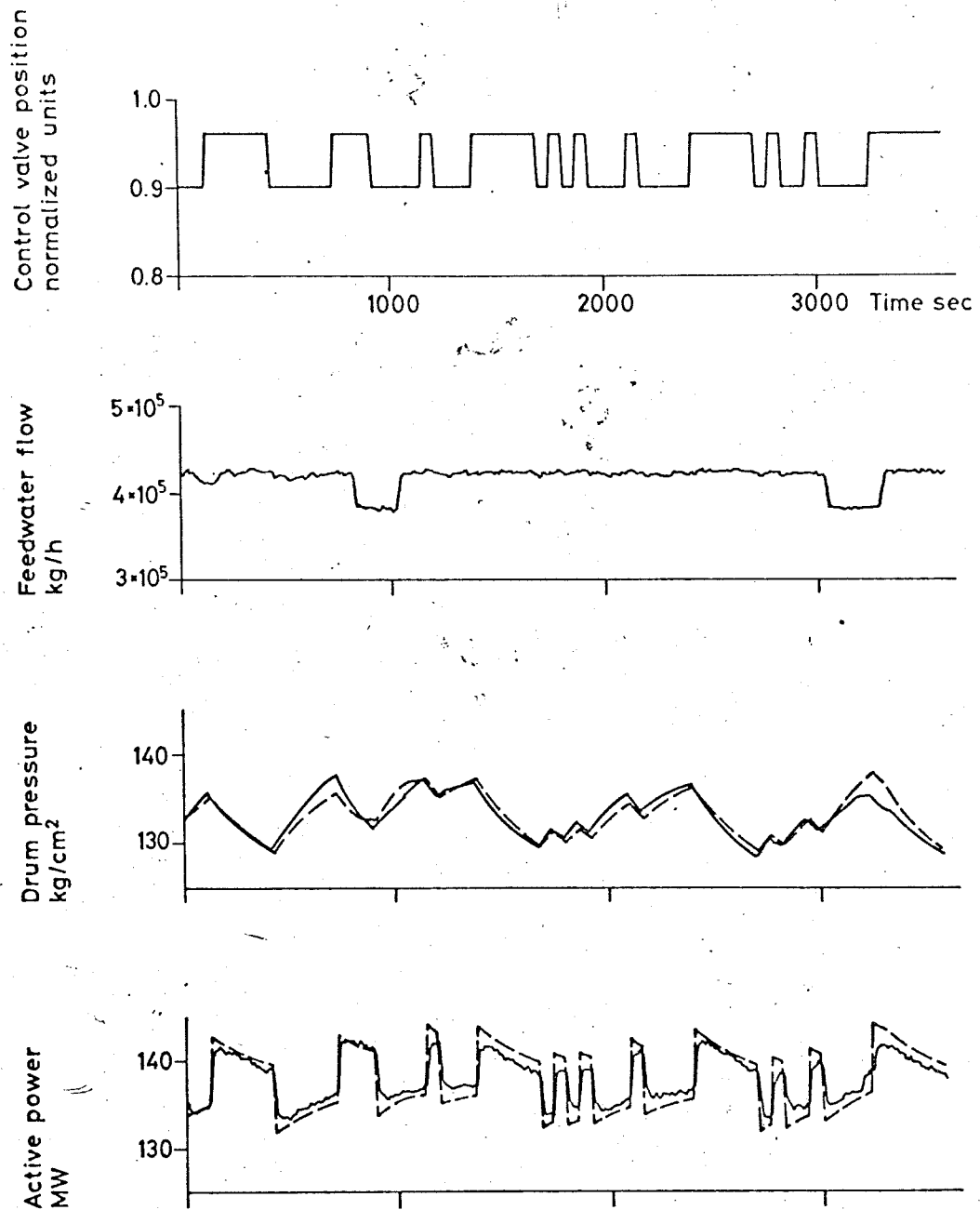and model (dashed) responses of Exp. A.

Fig. 16 – Comparison of measured boiler-turbine (solid)
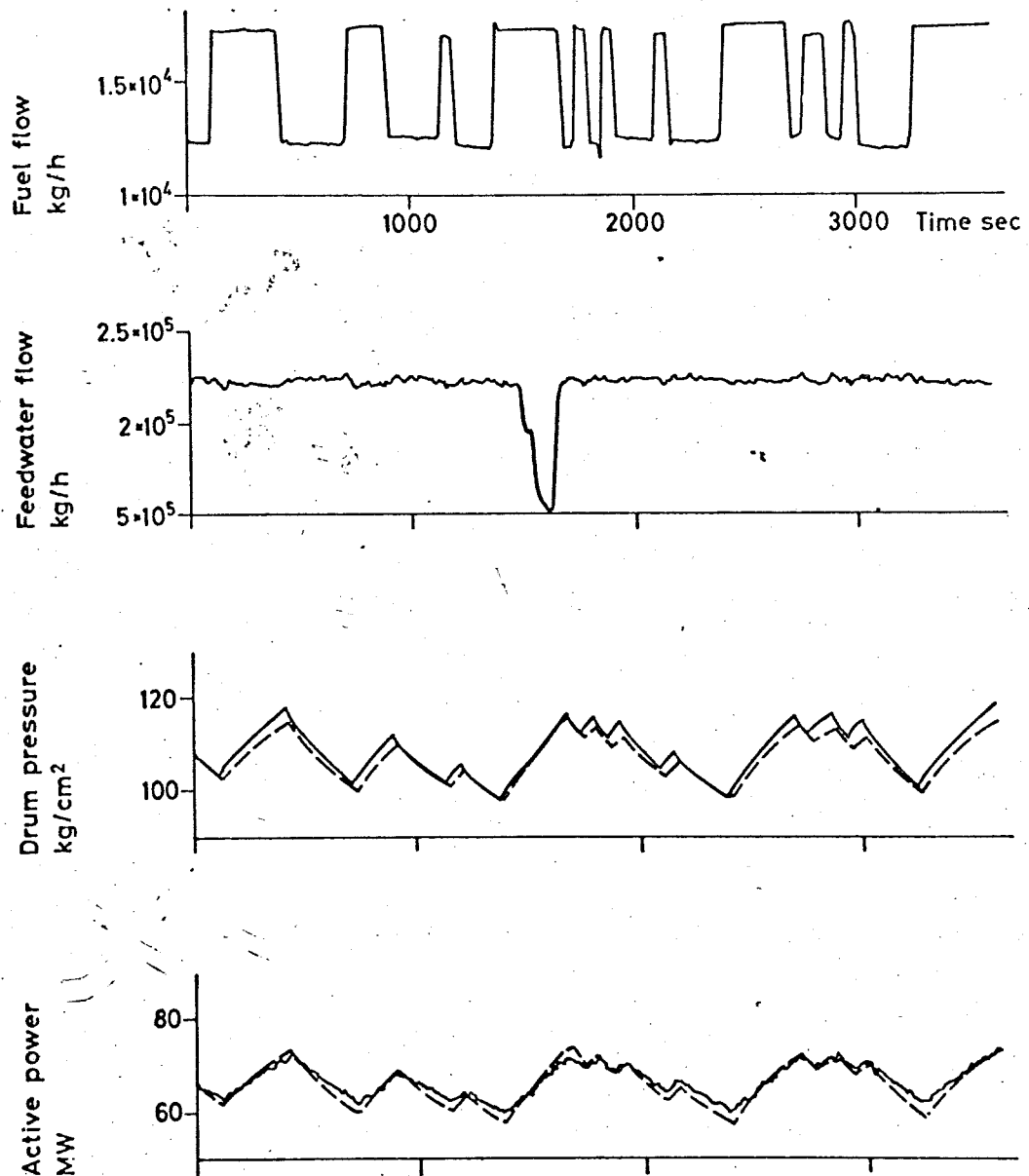and model (dashed) responses of Exp. B.

Fig. 17 - Comparison of measured boiler-turbine (solid)
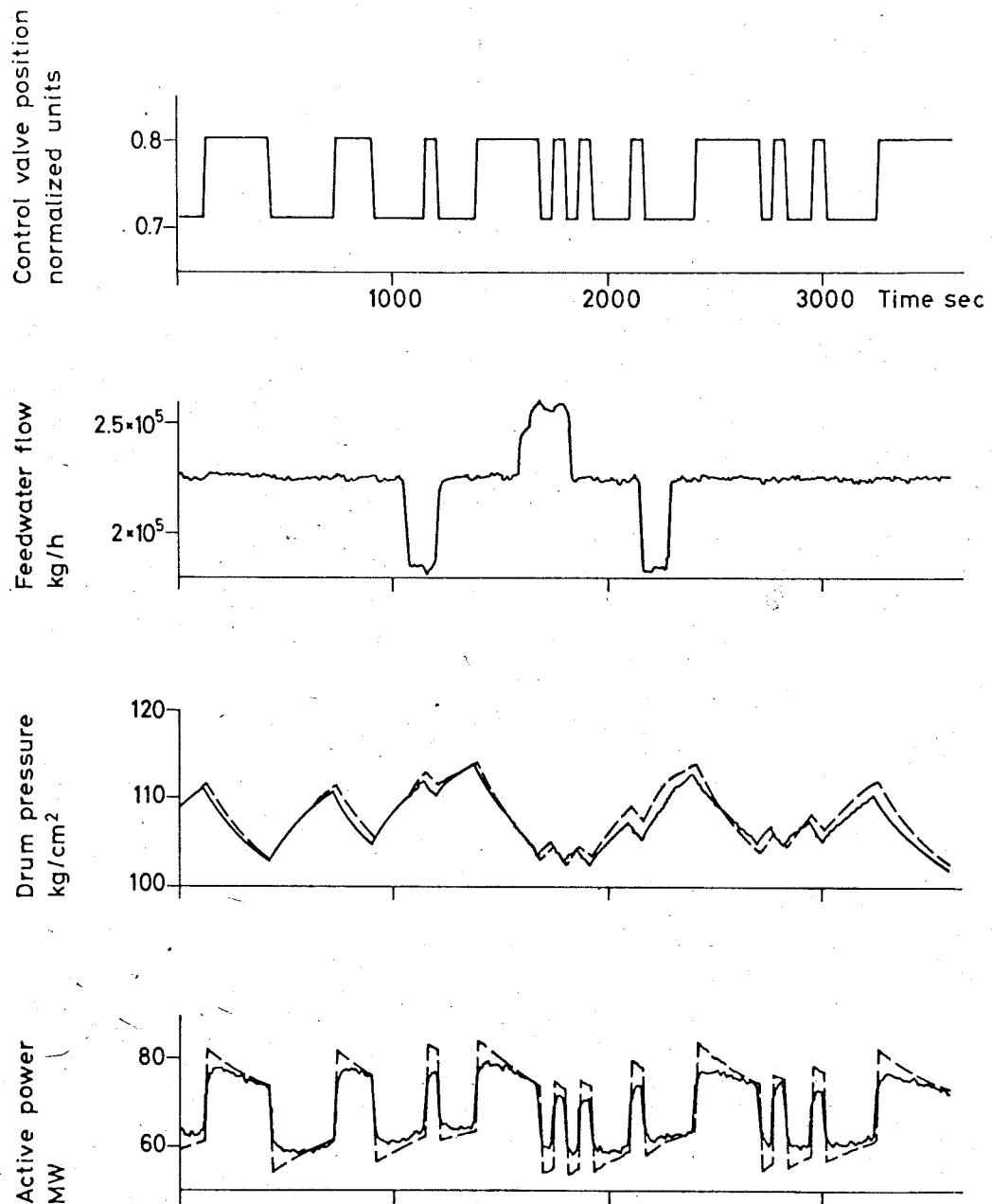and model (dashed) responses of Exp. C.

Fig. 18 - Comparison of measured boiler-turbine (solid)
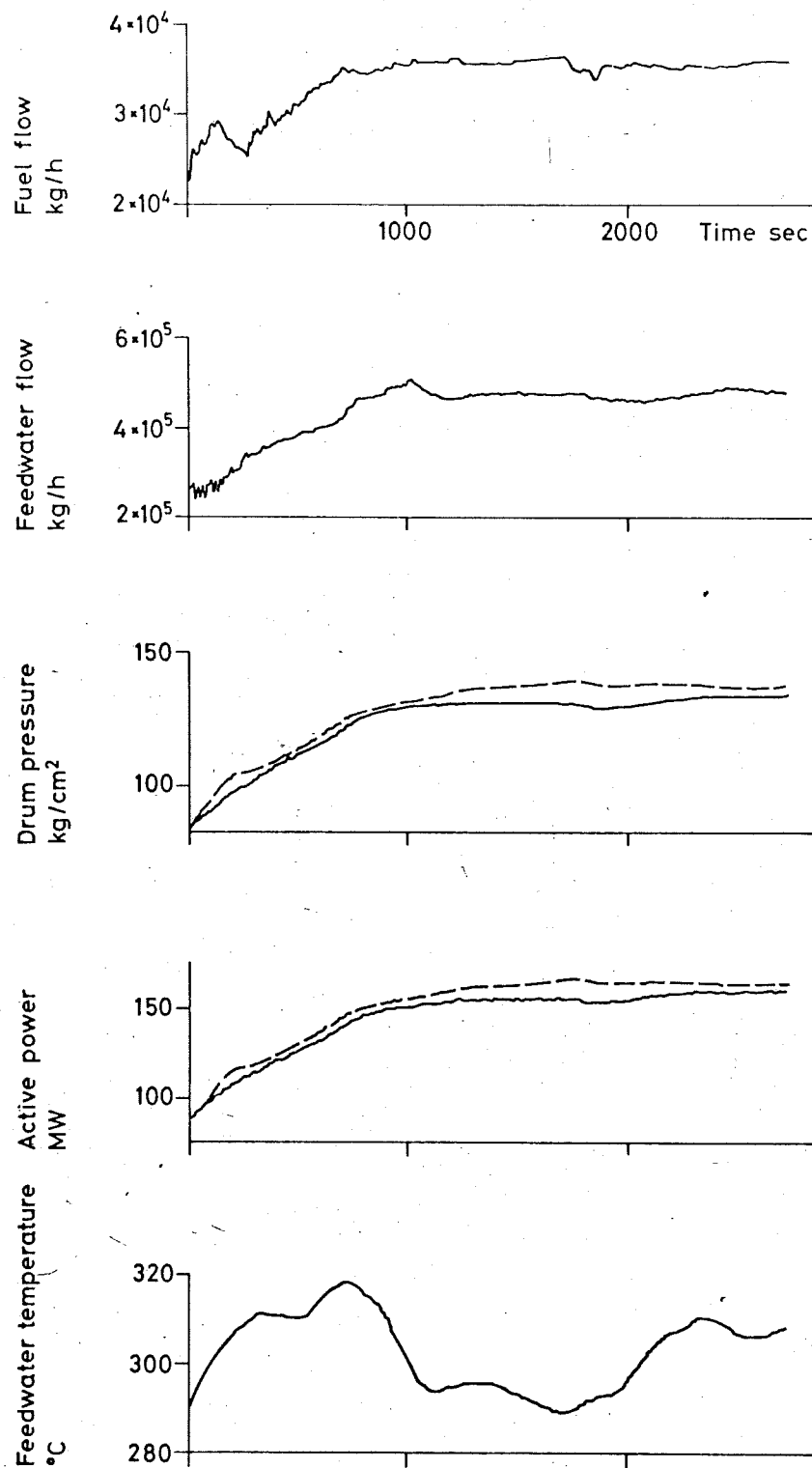and model (dashed) responses of Exp. D.

Fig. 19 - Comparison of measured boiler-turbine (solid)
and model (dashed) responses of Exp. E.

In Exp. E, shown in Fig. 19, also the feedwater temperature is given. The large discrepancy in drum pressure and active power in the later half of the experiment is due to the decreased feedwater temperature. The enthalpy difference between feedwater and drum saturation enthalpy was assumed to be constant. The modelling of this difference requires a model of the economizer which means (at least) one additional state variable for feedwater temperature. If model complexity is allowed to grow it seems more appropriate to include this phenomenon than the effects, caused by the reheater.

Any systematic investigation of the influence of parameter variations on model behaviour has not been made. Simple simulations, however, show that model properties not critically depend on the choice of model parameters.

6. QUALITATIVE PROPERTIES OF DRUM BOILERS.

The simplified model can be used in many different
ways. As an illustration we will here show how it can
be used to obtain a qualitative understanding of the
behaviour of a drum boiler.

Assuming steady state we get from eq. (3.12)

$$y = f(x,u_2) = g(u_1,u_3)$$

i.e. the output power f equals input power g. In Fig.
20 we show a graph of the function f for different
values of u_2. Assume that the plant is operating in
steady state with a given drum pressure and a given
steam valve position $u_2 < 1$ (point A of the diagram).
Now if the input power is increased the drum pressure
and the output power will slowly increase until a new
steady state condition is achieved (point B of the
diagram). However, if the control valve is suddenly
opened the output power will immediately increase to
a new value indicated by point C in the diagram.

Keeping control valve position constant the pressure
and output power will then slowly decrease until point
D is reached. Also if control valve instead is mani-
pulated (valve area increased) to keep output power
constant point E of the diagram will be reached. The
valve is now fully opened and the pressure and the
output power decrease until a new steady state condi-
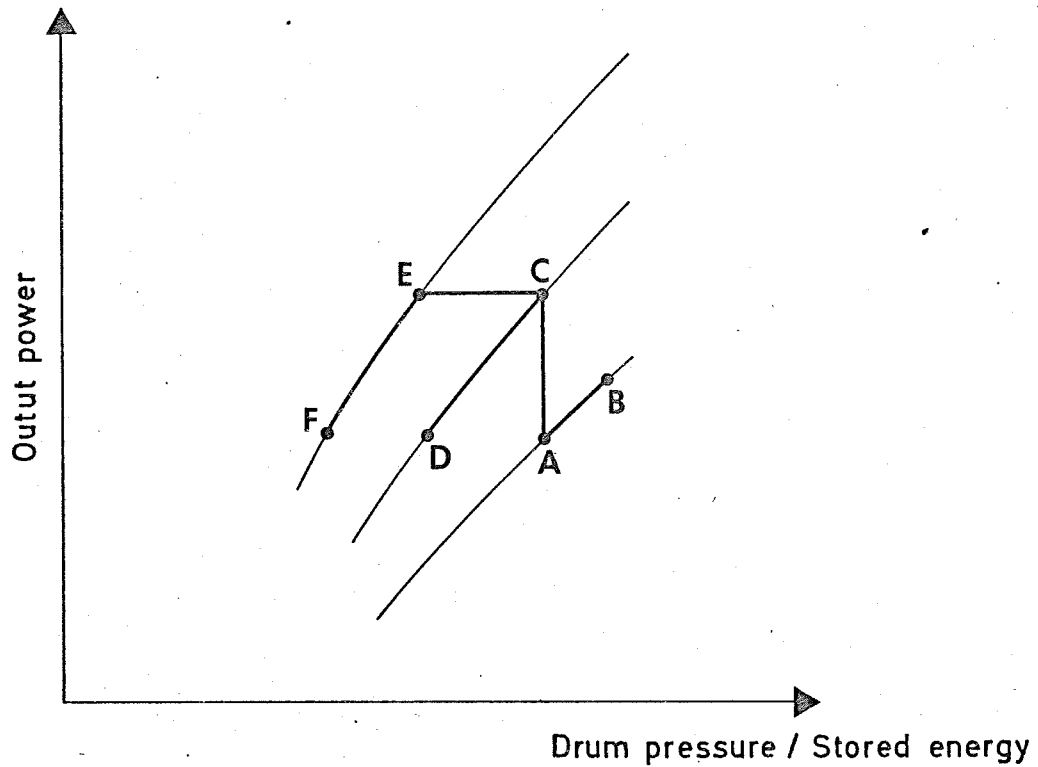tion is assumed in point E. This is the operating
procedure of Exp. F.

- Relationship between output power and drum
pressure or stored energy during load chan-
ges.

The axis of abscissa can also be graded in energy,
stored in the boiler, using eq. (3.2), e.g.

$$H(p) = ap + b$$

where

$$a = \frac{\alpha_4}{\alpha_1}$$

This means that the decrease in energy storage for the
operating schemes ACD and ACEF can be read from the
diagram. The energy decrease is commonly referred to
as storage capacitance.

The storage capacitance S can be expressed in several ways. For both schemes ACD and ACEF S can be given as total energy reduction

$$S_{ACD} = H_A - H_D \qquad MWh \qquad\qquad (6.1)$$

$$S_{ACEF} = H_A - H_F \qquad MWh \qquad\qquad (6.2)$$

where H_I is energy stored at point I of the diagram.

In the interval CE the rate of change of drum pressure is constant (u_1 and u_3 are kept constant). Then in this interval storage capacitance can be given as

$$S_{ACE} = \frac{H_A - H_E}{P_A - P_E} \qquad MWh/bar \qquad\qquad (6.3)$$

Using the model equation still another measure can be given as

$$S'_{ACE} = \frac{H_A - H_E}{P_A - P_E} \cdot \frac{dp}{dt} \qquad MW \qquad\qquad (6.4)$$

where dp/dt is constant. The measures (6.3) and (6.4) are exact in the interval CE. Approximately they can be extended to the entire interval ACEF. It is clear from this discussion that considerable insight into the properties of the drum boiler is provided by the simple diagram. Also notice that the function f can be determined experimentally by observing the steady state relation between drum pressure and output power.

7. ACKNOWLEDGEMENT.

8. REFERENCES.

A number of drum boiler models based on basic physical laws are available in literature. Model order is high ranging from 10 to 100 and the equations usually linearized.

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